

# Coordinated optimization of visual cortical maps

## (I) Symmetry-based analysis

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## Abstract

In the primary visual cortex of primates and carnivores, functional architecture can be characterized by maps of various stimulus features such as orientation preference (OP), ocular dominance (OD), and spatial frequency. It is a long-standing question in theoretical neuroscience whether the observed maps should be interpreted as optima of a specific energy functional that summarizes the design principles of cortical functional architecture. A rigorous evaluation of this optimization hypothesis is particularly demanded by recent evidence that the functional architecture of orientation columns precisely follows species invariant quantitative laws [1]. Because it would be desirable to infer the form of such an optimization principle from the biological data, the optimization approach to explain cortical functional architecture raises the following questions: i) What are the genuine ground states of candidate energy functionals and how can they be calculated with precision and rigor? ii) How do differences in candidate optimization principles impact on the predicted map structure and conversely what can be learned about an hypothetical underlying optimization principle from observations on map structure? iii) Is there a way to analyze the coordinated organization of cortical maps predicted by optimization principles in

general? To answer these questions we developed a general dynamical systems approach to the combined optimization of visual cortical maps of OP and another scalar feature such as OD or spatial frequency preference. From basic symmetry assumptions we obtain a comprehensive phenomenological classification of possible inter-map coupling energies and examine representative examples. We show that each individual coupling energy leads to a different class of OP solutions with different correlations among the maps such that inferences about the optimization principle from map layout appear viable. We systematically assess whether quantitative laws resembling experimental observations can result from the coordinated optimization of orientation columns with other feature maps.

## Author Summary

Neurons in the visual cortex form spatial representations or maps of several stimulus features. How are different spatial representations of visual information coordinated in the brain? In this paper, we study the hypothesis that the coordinated organization of several visual cortical maps can be explained by joint optimization. Previous attempts to explain the spatial layout of functional maps in the visual cortex proposed specific optimization principles ad hoc. Here, we systematically analyze how optimization principles in a general class of models impact on the spatial layout of visual cortical maps. For each considered optimization principle we identify the corresponding optima and analyze their spatial layout. This directly demonstrates that by studying map layout and geometric inter-map correlations one can substantially constrain the underlying optimization principle. In particular, we study whether such optimization principles can lead to spatially complex patterns and to geometric correlations among cortical maps as observed in imaging experiments.

## Introduction

Neurons in the primary visual cortex are selective to a multidimensional set of visual stimulus features, including visual field position, contour orientation, ocular dominance, direction of motion, and spatial frequency [2, 3]. In many mammals, these response properties form spatially complex, two-dimensional patterns called visual cortical maps [4–24]. The functional advantage of a two dimensional mapping of stimulus selectivities is currently unknown [25–27]. What determines the precise spatial organization of

these maps? It is a plausible hypothesis that natural selection should shape visual cortical maps to build efficient representations of visual information improving the 'fitness' of the organism. Cortical maps are therefore often viewed as optima of some cost function. For instance, it has been proposed that cortical maps optimize the cortical wiring length [28, 29] or represent an optimal compromise between stimulus coverage and map continuity [30–43]. If map structure was largely genetically determined map structure might be optimized through genetic variation and Darwinian selection on an evolutionary timescale. Optimization may, however, also occur during the ontogenetic maturation of the individual organism for instance by the activity-dependent refinement of neuronal circuits. If such an activity-dependent refinement of cortical architecture realizes an optimization strategy its outcome should be interpreted as the convergence towards a ground state of a specific energy functional. This hypothesized optimized functional, however, remains currently unknown. As several different functional maps coexist in the visual cortex candidate energy functionals are expected to reflect the multiple response properties of neurons in the visual cortex. In fact, consistent with the idea of joint optimization of different feature maps cortical maps are not independent of each other [8, 10, 18, 22, 41, 44–47]. Various studies proposed a coordinated optimization of different feature maps [30, 32, 33, 36, 37, 39–41, 43, 48–50]. Coordinated optimization appears consistent with the observed distinct spatial relationships between different maps such as the tendency of iso-orientation lines to intersect OD borders perpendicularly or the preferential positioning of orientation pinwheels at locations of maximal eye dominance [8, 10, 18, 22, 41, 44, 46]. Specifically these geometric correlations have thus been proposed to indicate the optimization of a cost function given by a compromise between stimulus coverage and continuity [32, 34, 37, 39, 41, 43], a conclusion that was questioned by Carreira-Perpinan and Goodhill [51].

Visual cortical maps are often spatially complex patterns that contain defect structures such as point singularities (pinwheels) [6, 11, 52, 53, 53, 54] or line discontinuities (fractures) [12, 55] and that never exactly repeat [1, 4–24, 56]. It is conceivable that this spatial complexity arises from geometric frustration due to a coordinated optimization of multiple feature maps in which not all inter-map interactions can be simultaneously satisfied [50, 57–60]. In many optimization models, however, the resulting map layout is spatially not complex or lacks some of the basic features such as topological defects [28, 50, 57, 61, 62]. In other studies coordinated optimization was reported to preserve defects that would otherwise decay [50, 57]. An attempt to rigorously study the hypothesis that the structure of cortical maps is explained by an optimization process thus raises a number of questions: i) What are the genuine ground states of candi-

date energy functionals and how can they be calculated with precision and rigor? ii) How do differences in candidate optimization principles impact on the predicted map structure and conversely what can be learned about an hypothetical underlying optimization principle from observations on map structure? iii) Is there a way to analyze the coordinated organization of cortical maps predicted by optimization principles in general? If theoretical neuroscience was able to answer these questions with greater confidence, the interpretation and explanation of visual cortical architecture could build on a more solid foundation than currently available. To start laying such a foundation, we examined how symmetry principles in general constrain the form of optimization models and developed a formalism for analyzing map optimization independent of the specific energy functional assumed.

Minima of a given energy functional can be found by gradient descent which is naturally represented by a dynamical system describing a formal time evolution of the maps. Response properties in visual cortical maps are arranged in repetitive modules of a typical spatial length called hypercolumn. Optimization models that reproduce this typical length scale are therefore effectively pattern forming systems with a so-called 'cellular' or finite wavelength instability, see [63–65]. In the theory of pattern formation, it is well understood that symmetries play a crucial role [63–65]. Some symmetries are widely considered biologically plausible for cortical maps, for instance the invariance under spatial translations and rotations or a global shift of orientation preference [50, 62, 66–70]. In this paper we argue that such symmetries and an approach that utilizes the analogy between map optimization and pattern forming systems can open up a novel and systematic approach to the coordinated optimization of visual cortical representations.

A recent study found strong evidence for a common design in the functional architecture of orientation columns [1]. Three species, galagos, ferrets, and tree shrews, widely separated in evolution of modern mammals, share an apparently universal set of quantitative properties. The average pinwheel density as well as the spatial organization of pinwheels within orientation hypercolumns, expressed in the statistics of nearest neighbors as well as the local variability of the pinwheel densities in cortical subregions ranging from 1 to 30 hypercolumns, are found to be virtually identical in the analyzed species. However, these quantities are different from random maps. Intriguingly, the average pinwheel density was found to be statistical indistinguishable from the mathematical constant  $\pi$  up to a precision of 2%. Such apparently universal laws can be reproduced in relatively simple self-organization models if long-range neuronal interactions are dominant [1, 69–71]. As pointed out by Kaschube and coworkers, these findings pose strong constraints on models of cortical functional architecture [1]. Many models exhibiting pinwheel annihilation

lation [50, 57] or pinwheel crystallization [61, 62, 72] were found to violate the experimentally observed layout rules. In [1] it was shown that the common design is correctly predicted in models that were based only on intrinsic OP properties. Alternatively, however, it is conceivable that they result from geometric frustration due to inter-map interactions and joint optimization. In the current study we therefore in particular examined whether the coordinated optimization of the OP map and another feature map can reproduce the quantitative laws defining the common design.

The presentation of our results is organized as follows. First we introduce a formalism to model the coordinated optimization of complex and real valued scalar fields. Complex valued fields can represent for instance orientation preference (OP) or direction preference maps [13, 23]. Real valued fields may represent for instance ocular dominance (OD) [2], spatial frequency maps [19, 44] or ON-OFF segregation [73]. We construct several optimization models such that an independent optimization of each map in isolation results in a regular OP stripe pattern and, depending on the relative representations of the two eyes, OD patterns with a regular hexagonal or stripe layout. A model-free, symmetry-based analysis of potential optimization principles that couple the real and complex valued fields provides a comprehensive classification and parametrization of conceivable coordinated optimization models and identifies representative forms of coupling energies. For analytical treatment of the optimization problem we adapt a perturbation method from pattern formation theory called weakly nonlinear analysis [63–65, 74–77]. This method is applicable to models in which the spatial pattern of columns branches off continuously from an unselective homogeneous state. It reduces the dimensionality of the system and leads to amplitude equations as an approximate description of the system near the symmetry breaking transition at which the homogeneous state becomes unstable. We identify a limit in which inter-map interactions that are formally always bidirectional become effectively unidirectional. In this limit, one can neglect the backreaction of the complex map on the layout of the co-evolving scalar feature map. We show how to treat low and higher order versions of inter-map coupling energies which enter at different order in the perturbative expansion.

Second we apply the derived formalism by calculating optima of two representative low order examples of coordinated optimization models and examine how they impact on the resulting map layout. Two higher order optimization models are analyzed in Text S1. For concreteness and motivated by recent topical interest [1, 78, 79], we illustrate the coordinated optimization of visual cortical maps for the widely studied example of a complex OP map and a real feature map such as the OD map. OP maps are characterized by

pinwheels, regions in which columns preferring all possible orientations are organized around a common center in a radial fashion [52,54,80,81]. In particular, we address the problem of pinwheel stability in OP maps [50,70] and calculate the pinwheel densities predicted by different models. As shown previously, many theoretical models of visual cortical development and optimization fail to predict OP maps possessing stable pinwheels [28,50,57,61]. We show that in case of the low order energies, a strong inter-map coupling will typically lead to OP map suppression, causing the orientation selectivity of all neurons to vanish. For all considered optimization models, we identify stationary solutions of the resulting dynamics and mathematically demonstrate their stability. We further calculate phase diagrams as a function of the inter-map coupling strength and the amount of overrepresentation of certain stimuli of the co-evolving scalar feature map. We show that the optimization of any of the analyzed coupling energies can lead to spatially relatively complex patterns. Moreover, in case of OP maps, these patterns are typically pinwheel-rich. The phase diagrams, however, differ for each considered coupling energy, in particular leading to coupling energy specific ground states. We therefore thoroughly analyze the spatial layout of energetic ground states and in particular their geometric inter-map relationships. We find that none of the examined models reproduces the experimentally observed pinwheel density and spatially aperiodic arrangements. Our analysis identifies a seemingly general condition for interaction induced pinwheel-rich OP optima namely a substantial bias in the response properties of the co-evolving scalar feature map.

## Results

### 1.1 Modeling the coordinated optimization of multiple maps

We model the response properties of neuronal populations in the visual cortex by two-dimensional scalar order parameter fields which are either complex valued or real valued [52,82]. A complex valued field  $z(\mathbf{x})$  can for instance describe OP or direction preference of a neuron located at position  $\mathbf{x}$ . A real valued field  $o(\mathbf{x})$  can describe for instance OD or the spatial frequency preference. Although we introduce a model for the coordinated optimization of general real and complex valued order parameter fields we consider  $z(\mathbf{x})$  as the field of OP and  $o(\mathbf{x})$  as the field of OD throughout this article. In this case, the pattern of preferred stimulus orientation  $\vartheta$  is obtained by

$$\vartheta(\mathbf{x}) = \frac{1}{2} \arg(z). \quad (1)$$

The modulus  $|z(\mathbf{x})|$  is a measure of the selectivity at cortical location  $\mathbf{x}$ .

OP maps are characterized by so-called *pinwheels*, regions in which columns preferring all possible orientations are organized around a common center in a radial fashion. The centers of pinwheels are point discontinuities of the field  $\vartheta(\mathbf{x})$  where the mean orientation preference of nearby columns changes by 90 degrees. Pinwheels can be characterized by a topological charge  $q$  which indicates in particular whether the orientation preference increases clockwise or counterclockwise around the pinwheel center,

$$q_i = \frac{1}{2\pi} \oint_{C_i} \nabla \vartheta(\mathbf{x}) d\mathbf{s}, \quad (2)$$

where  $C_i$  is a closed curve around a single pinwheel center at  $\mathbf{x}_i$ . Since  $\vartheta$  is a cyclic variable in the interval  $[0, \pi]$  and up to isolated points is a continuous function of  $\mathbf{x}$ ,  $q_i$  can only have values

$$q_i = \frac{n}{2}, \quad (3)$$

where  $n$  is an integer number [83]. If its absolute value  $|q_i| = 1/2$ , each orientation is represented only once in the vicinity of a pinwheel center. In experiments, only pinwheels with a topological charge of  $\pm 1/2$  are observed, which are simple zeros of the field  $z(\mathbf{x})$ .

OD maps can be described by a real valued two-dimensional field  $o(\mathbf{x})$ , where  $o(\mathbf{x}) < 0$  indicates ipsilateral eye dominance and  $o(\mathbf{x}) > 0$  contralateral eye dominance of the neuron located at position  $\mathbf{x}$ . The magnitude indicates the strength of the eye dominance and thus the zeros of the field correspond to the borders of OD.

In this article, we view visual cortical maps as optima of some energy functional  $E$ . The time evolution of these maps can be described by the gradient descent of this energy functional. The field dynamics thus takes the form

$$\begin{aligned} \partial_t z(\mathbf{x}, t) &= F[z(\mathbf{x}, t), o(\mathbf{x}, t)] \\ \partial_t o(\mathbf{x}, t) &= G[z(\mathbf{x}, t), o(\mathbf{x}, t)], \end{aligned} \quad (4)$$

where  $F[z, o]$  and  $G[z, o]$  are nonlinear operators given by  $F[z, o] = -\frac{\delta E}{\delta \bar{z}}$ ,  $G[z, o] = -\frac{\delta E}{\delta o}$ . The system then relaxes towards the minima of the energy  $E$ . The convergence of this dynamics towards an attractor is assumed to represent the process of maturation and optimization of the cortical circuitry. Various

biologically detailed models have been cast to this form [34, 50, 84].

All visual cortical maps are arranged in repetitive patterns of a typical wavelength  $\Lambda$ . We splitted the energy functional  $E$  into a part that ensures the emergence of such a typical wavelength for each map and into a part which describes the coupling among different maps. A well studied model reproducing the emergence of a typical wavelength by a pattern forming instability is of the Swift-Hohenberg type [64, 85]. Many other pattern forming systems occurring in different physical, chemical, and biological contexts (see for instance [74–77]) have been cast into a dynamics of this type. Its dynamics in case of the OP map is of the form

$$\partial_t z(\mathbf{x}, t) = \hat{L}z(\mathbf{x}, t) - |z|^2 z, \quad (5)$$

with the linear Swift-Hohenberg operator

$$\hat{L} = r - (k_c^2 + \Delta)^2, \quad (6)$$

$k_c = 2\pi/\Lambda$ , and  $N[z(\mathbf{x}, t)]$  a nonlinear operator. The energy functional of this dynamics is given by

$$E = - \int d^2x \left( \bar{z}(\mathbf{x}) \hat{L}z(\mathbf{x}) - \frac{1}{2} |z(\mathbf{x})|^4 \right). \quad (7)$$

In Fourier representation,  $\hat{L}$  is diagonal with the spectrum

$$\lambda(k) = r - (k_c^2 - k^2)^2. \quad (8)$$

The spectrum exhibits a maximum at  $k = k_c$ . For  $r < 0$ , all modes are damped since  $\lambda(k) < 0$ ,  $\forall k$  and only the homogeneous state  $z(\mathbf{x}) = 0$  is stable. This is no longer the case for  $r > 0$  when modes on the *critical circle*  $k = k_c$  acquire a positive growth rate and now start to grow, resulting in patterns with a typical wavelength  $\Lambda = 2\pi/k_c$ . Thus, this model exhibits a supercritical bifurcation where the homogeneous state loses its stability and spatial modulations start to grow.

The coupled dynamics we considered is of the form

$$\begin{aligned} \partial_t z(\mathbf{x}, t) &= \hat{L}_z z(\mathbf{x}, t) - |z|^2 z - \frac{\delta U}{\delta \bar{z}} \\ \partial_t o(\mathbf{x}, t) &= \hat{L}_o o(\mathbf{x}, t) - o^3 - \frac{\delta U}{\delta o} + \gamma, \end{aligned} \quad (9)$$



where  $\hat{L}_{\{o,z\}} = r_{\{o,z\}} - \left(k_{c,\{o,z\}}^2 + \Delta\right)^2$ , and  $\gamma$  is a constant. To account for the species differences in the wavelengths of the pattern we chose two typical wavelengths  $\Lambda_z = 2\pi/k_{c,z}$  and  $\Lambda_o = 2\pi/k_{c,o}$ . The dynamics of  $z(\mathbf{x}, t)$  and  $o(\mathbf{x}, t)$  is coupled by interaction terms which can be derived from a coupling energy  $U$ . In the uncoupled case this dynamics leads to pinwheel free OP stripe patterns.

## 1.2 Symmetries constrain inter-map coupling energies

How many inter-map coupling energies  $U$  exist? Using a phenomenological approach the inclusion and exclusion of various terms has to be strictly justified. We did this by symmetry considerations. The constant  $\gamma$  breaks the inversion symmetry  $o(\mathbf{x}) = -o(\mathbf{x})$  of inputs from the ipsilateral ( $o(\mathbf{x}) < 0$ ) or contralateral ( $o(\mathbf{x}) > 0$ ) eye. Such an inversion symmetry breaking could also arise from quadratic terms such as  $o(\mathbf{x})^2$ . In the methods section we detail how a constant shift in the field  $o(\mathbf{x})$  can eliminate the constant term and generate such a quadratic term. Including either a shift or a quadratic term thus already represents the most general case. The inter-map coupling energy  $U$  was assumed to be invariant under this inversion. Otherwise orientation selective neurons would, for an equal representation of the two eyes, develop different layouts to inputs from the left or the right eye. The primary visual cortex shows no anatomical indication that there are any prominent regions or directions parallel to the cortical layers [66]. Besides invariance under translations  $\hat{T}_y z(\mathbf{x}) = z(\mathbf{x} - \mathbf{y})$  and rotations  $\hat{R}_\phi z(\mathbf{x}) = z(R_\phi^{-1} \mathbf{x})$  of both maps we required that the dynamics should be invariant under orientation shifts  $z(\mathbf{x}) \rightarrow e^{i\theta} z(\mathbf{x})$ . Note, that the assumption of shift symmetry is an idealization that uncouples the OP map from the map of visual space. Bressloff and coworkers have presented arguments that Euclidean symmetry that couples spatial locations to orientation shift represents a more plausible symmetry for visual cortical dynamics [67, 86], see also [87]. The existence of orientation shift symmetry, however, is not an all or none question. Recent evidence in fact indicates that shift symmetry is only weakly broken in the spatial organization of orientation maps [88, 89]. A general coupling energy term can be expressed by integral operators which can be written as a Volterra series

$$E = \sum_{u=u_o+u_z}^{\infty} \int \prod_{i=1}^{u_o} d^2 x_i o(\mathbf{x}_i) \prod_{j=u_o+1}^{u_o+u_z/2} d^2 x_j z(\mathbf{x}_j) \prod_{k=u_o+u_z/2+1}^u d^2 x_k \bar{z}(\mathbf{x}_k) K_u(\mathbf{x}_1, \dots, \mathbf{x}_u), \quad (10)$$

with an  $u$ -th. order integral kernel  $K_u$ . Inversion symmetry and orientation shift symmetry require  $u_o$  to be even and that the number of fields  $z$  equals the number of fields  $\bar{z}$ . The lowest order term, mediating

an interaction between the fields  $o$  and  $z$  is given by  $u = 4, u_o = 2$  i.e.

$$E_4 = \int d^2x_1 d^2x_2 d^2x_3 d^2x_4 o(\mathbf{x}_1) o(\mathbf{x}_2) z(\mathbf{x}_3) \bar{z}(\mathbf{x}_4) K_4(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_4). \quad (11)$$

Next, we rewrite Eq. (11) as an integral over an energy density  $U$ . We use the invariance under translations to introduce new coordinates

$$\begin{aligned} \mathbf{x}_m &= (1/4) \sum_j^4 \mathbf{x}_j \\ \mathbf{y}_1 &= \mathbf{x}_1 - \mathbf{x}_m \\ \mathbf{y}_2 &= \mathbf{x}_2 - \mathbf{x}_m \\ \mathbf{y}_3 &= \mathbf{x}_3 - \mathbf{x}_m. \end{aligned} \quad (12)$$

This leads to

$$\begin{aligned} E_4 &= \int d^2x_m \int d^2y_1 d^2y_2 d^2y_3 o(\mathbf{y}_1 + \mathbf{x}_m) o(\mathbf{y}_2 + \mathbf{x}_m) z(\mathbf{y}_3 + \mathbf{x}_m) \\ &\quad \bar{z}(\mathbf{x}_m - \sum_i^3 (\mathbf{y}_i - \mathbf{x}_m)) K(\mathbf{y}_1, \mathbf{y}_2, \mathbf{y}_3) \\ &= \int d^2x_m U_4(\mathbf{x}_m). \end{aligned} \quad (13)$$

The kernel  $K$  may contain local and non-local contributions. Map interactions were assumed to be local. For local interactions the integral kernel is independent of the locations  $\mathbf{y}_i$ . We expanded both fields in a Taylor series around  $\mathbf{x}_m$

$$z(\mathbf{x}_m + \mathbf{y}_i) = z(\mathbf{x}_m) + \nabla z(\mathbf{x}_m) \mathbf{y}_i + \dots, \quad o(\mathbf{x}_m + \mathbf{y}_i) = o(\mathbf{x}_m) + \nabla o(\mathbf{x}_m) \mathbf{y}_i + \dots \quad (14)$$

For a local energy density we could truncate this expansion at the first order in the derivatives. The energy density can thus be written

$$\begin{aligned} U_4(\mathbf{x}_m) &= \int d^2y_1 d^2y_2 d^2y_3 (o(\mathbf{x}_m) + \nabla o(\mathbf{x}_m) \mathbf{y}_1) (o(\mathbf{x}_m) + \nabla o(\mathbf{x}_m) \mathbf{y}_2) \\ &\quad (z(\mathbf{x}_m) + \nabla z(\mathbf{x}_m) \mathbf{y}_3) \left( \bar{z}(\mathbf{x}_m) - \nabla \bar{z}(\mathbf{x}_m) \sum_i (\mathbf{y}_i - \mathbf{x}_m) \right) K(\mathbf{y}_1, \mathbf{y}_2, \mathbf{y}_3). \end{aligned} \quad (15)$$

Due to rotation symmetry this energy density should be invariant under a simultaneous rotation of both fields. From all possible combinations of Eq. (15) only those are invariant in which the gradients of the fields appear as scalar products. The energy density can thus be written as

$$\begin{aligned} U_4 &= f(c_1, c_2, \dots, c_8) \\ &= f(o^2, z^2, z\bar{z}, oz, \nabla o \cdot \nabla o, \nabla z \cdot \nabla z, \nabla z \cdot \nabla \bar{z}, \nabla o \cdot \nabla z), \end{aligned} \quad (16)$$

where we suppress the argument  $\mathbf{x}_m$ . All combinations  $c_j$  can also enter via their complex conjugate. The general expression for  $U_4$  is therefore

$$U_4 = \sum_{i>j} l_{ij}^{(1)} c_i c_j + \sum_{i>j} l_{ij}^{(2)} \bar{c}_i \bar{c}_j + \sum_{i,j} l_{ij}^{(3)} c_i \bar{c}_j. \quad (17)$$

From all possible combinations we selected those which are invariant under orientation shifts and eye inversions. This leads to

$$\begin{aligned} U_4 &= l_1 o^4 + l_2 |z|^4 + l_3 (\nabla o \cdot \nabla o)^2 + l_4 |\nabla z \cdot \nabla z|^2 \\ &\quad + l_5 (\nabla z \cdot \nabla \bar{z})^2 + l_6 (\nabla o \cdot \nabla o) o^2 + l_7 (\nabla z \cdot \nabla \bar{z}) |z|^2 \\ &\quad + l_8 (\nabla z \cdot \nabla z) \bar{z}^2 + l_9 (\nabla \bar{z} \cdot \nabla \bar{z}) z^2 \\ &\quad + l_{10} (\nabla o \cdot \nabla z) o \bar{z} + l_{11} (\nabla o \cdot \nabla \bar{z}) o z \\ &\quad + l_{12} o^2 |z|^2 + l_{13} |\nabla o \cdot \nabla z|^2 + l_{14} (\nabla z \cdot \nabla \bar{z}) o^2 \\ &\quad + l_{15} (\nabla o \cdot \nabla o) |z|^2 + l_{16} (\nabla z \cdot \nabla \bar{z}) (\nabla o \cdot \nabla o). \end{aligned} \quad (18)$$

The energy densities with prefactor  $l_1$  to  $l_9$  do not mediate a coupling between OD and OP fields and can be absorbed into the single field energy functionals. The densities with prefactors  $l_8$  and  $l_9$  (also with  $l_{10}$  and  $l_{11}$ ) are complex and can occur only together with  $l_8 = l_9$  ( $l_{10} = l_{11}$ ) to be real. These energy densities, however, are not bounded from below as their real and imaginary parts can have arbitrary positive and negative values. The lowest order terms which are real and positive definite are thus given by

$$U_4 = l_{12} o^2 |z|^2 + l_{13} |\nabla o \cdot \nabla z|^2 + l_{14} o^2 \nabla z \cdot \nabla \bar{z} + l_{15} \nabla o \cdot \nabla o |z|^2 + l_{16} (\nabla z \cdot \nabla \bar{z}) (\nabla o \cdot \nabla o). \quad (19)$$

The next higher order energy terms are given by

$$U_6 = o^2|z|^4 + |z|^2o^4 + o^4\nabla z \cdot \nabla \bar{z} + \dots \quad (20)$$

Here the fields  $o(\mathbf{x})$  and  $z(\mathbf{x})$  enter with an unequal power. In the corresponding field equations these interaction terms enter either in the linear part or in the cubic nonlinearity. We will show in this article that interaction terms that enter in the linear part of the dynamics can lead to a suppression of the pattern and possibly to an instability of the pattern solution. Therefore we considered also higher order interaction terms.

These higher order terms contain combinations of terms in Eq. (19) and are given by

$$\begin{aligned} U_8 = & o^4|z|^4 + |\nabla o \cdot \nabla z|^4 + o^4 (\nabla z \cdot \nabla \bar{z})^2 + (\nabla o \cdot \nabla o)^2 |z|^4 \\ & + (\nabla z \cdot \nabla \bar{z})^2 (\nabla o \cdot \nabla o)^2 + o^2|z|^2 |\nabla o \cdot \nabla z|^2 + \dots \end{aligned} \quad (21)$$

As we will show below examples of coupling energies

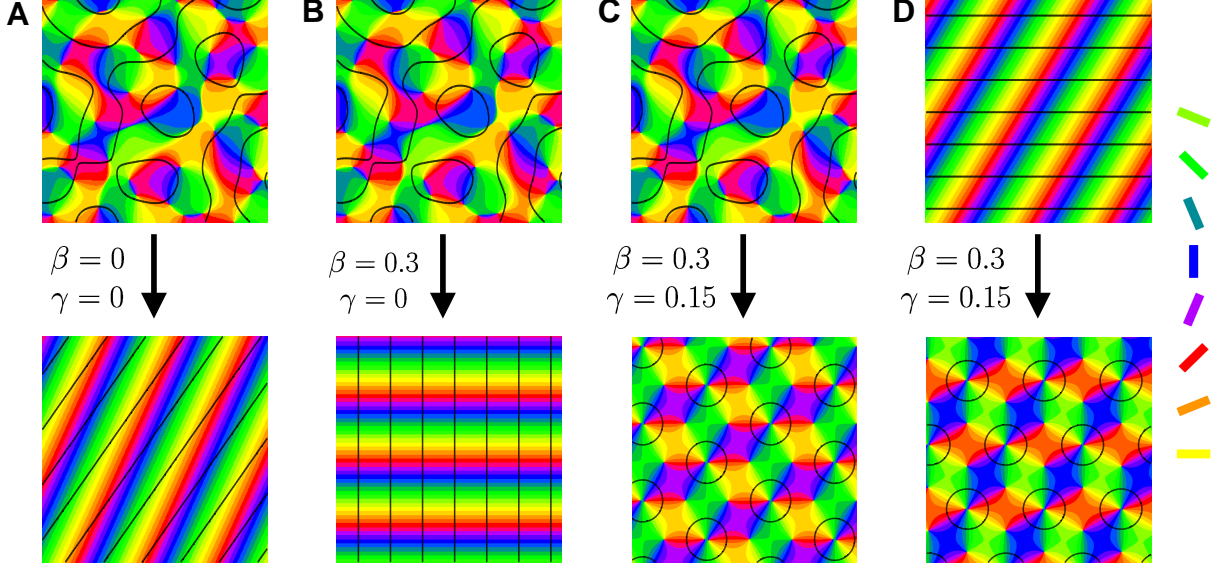
$$U = \alpha o^2|z|^2 + \beta |\nabla z \cdot \nabla o|^2 + \tau o^4|z|^4 + \epsilon |\nabla z \cdot \nabla o|^4, \quad (22)$$

form a representative set that can be expected to reproduce experimentally observed map relationships.

For this choice of energy the corresponding interaction terms in the dynamics Eq. (9) are given by

$$\begin{aligned} -\frac{\delta U}{\delta \bar{z}} &= N_\alpha[o, o, z] + N_\beta[o, o, z] + N_\epsilon[o, o, o, o, z, z, \bar{z}] + N_\tau[o, o, o, o, z, z, \bar{z}] \\ &= -\alpha o^2 z + \beta \nabla (a \nabla o) + \epsilon 2 \nabla (|a|^2 a \nabla o) - 2\tau o^4 |z|^2 z, \\ -\frac{\delta U}{\delta o} &= \tilde{N}_\alpha[o, z, \bar{z}] + \tilde{N}_\beta[o, z, \bar{z}] + \tilde{N}_\epsilon[o, o, o, z, z, \bar{z}, \bar{z}] + \tilde{N}_\tau[o, o, o, z, z, \bar{z}, \bar{z}] \\ &= -\alpha o |z|^2 + \beta \nabla (\bar{a} \nabla z) + \epsilon 2 \nabla (|a|^2 \bar{a} \nabla z) - 2\tau o^3 |z|^4 + c.c. \end{aligned} \quad (23)$$

with  $a = \nabla z \cdot \nabla o$  and *c.c.* denoting the complex conjugate. In general, all coupling energies in  $U_4, U_6$ , and  $U_8$  can occur in the dynamics and we restrict to those energies which are expected to reproduce the observed geometric relationships between OP and OD maps. It is important to note that with this restriction we did not miss any essential parts of the model. When using weakly nonlinear analysis the general form of the near threshold dynamics is insensitive to the used type of coupling energy and we



**Figure 1. Pinwheel annihilation, preservation, and generation** in numerical simulations for different strengths of inter-map coupling and OD bias,  $r_o = 0.2, r_z = 0.02$ . Color code of OP map with zero contours of OD map superimposed. **A**  $\gamma = 0, \beta = 0$  **B**  $\gamma = 0, \beta = 0.3$  **C** and **D**  $\gamma = 0.15, \beta = 0.3$ . Initial conditions identical in **A** - **C**,  $T_f = 10^4, k_{c,o} = k_{c,z}$ .

therefore expect similar results also for the remaining coupling energies.

Numerical simulations of the dynamics Eq. (9), see [62, 90], with the coupling energy Eq. (22) and  $\alpha = \epsilon = \tau = 0$  are shown in Fig. 1. The initial conditions and final states are shown for different bias terms  $\gamma$  and inter-map coupling strengths  $\beta$ . We observed that for a substantial contralateral bias and above a critical inter-map coupling pinwheels are preserved from random initial conditions or are generated if the initial condition is pinwheel free. Without a contralateral bias the final states were pinwheel free stripe solutions irrespective of the strength of the inter-map coupling.

### 1.3 Calculating ground states by coupled amplitude equations

We studied Eq. (9) with the low order inter-map coupling energies in Eq. (22) using weakly nonlinear analysis. We therefore rewrite Eq. (9) as

$$\begin{aligned}
 \partial_t z(\mathbf{x}, t) &= r_z z(\mathbf{x}, t) - \hat{L}_z^0 z(\mathbf{x}, t) - N_{3,u}[z, z, \bar{z}] - N_{3,c}[z, o, o] \\
 \partial_t o(\mathbf{x}, t) &= r_o o(\mathbf{x}, t) - \hat{L}_o^0 o(\mathbf{x}, t) + N_{2,u}[o, o] - N_{3,u}[o, o, o] - \tilde{N}_{3,c}[o, z, \bar{z}],
 \end{aligned} \tag{24}$$

where we shifted both linear operators as  $\hat{L}_z = r_z + \hat{L}_z^0$ ,  $\hat{L}_o = r_o + \hat{L}_o^0$ . The constant term  $\gamma$  in Eq. (9) is replaced by a quadratic interaction term  $N_{2,u}[o, o] = \tilde{\gamma}o^2$  with  $\tilde{\gamma} \propto \sqrt{r_o}$ , see Methods. The uncoupled nonlinearities are given by  $N_{3,u} = |z|^2 z$ ,  $\tilde{N}_{3,u} = o^3$  while  $N_{3,c}$  and  $\tilde{N}_{3,c}$  are the nonlinearities of the low order inter-map coupling energy Eq. (23). We study Eq. (24) close to the pattern forming bifurcation where  $r_z$  and  $r_o$  are small. We therefore expand both control parameters in powers of the small expansion parameter  $\mu$

$$\begin{aligned} r_z &= \mu r_{z1} + \mu^2 r_{z2} + \mu^3 r_{z3} + \dots \\ r_o &= \mu r_{o1} + \mu^2 r_{o2} + \mu^3 r_{o3} + \dots \end{aligned} \quad (25)$$

Close to the bifurcation the fields are small and thus nonlinearities are weak. We therefore expand both fields as

$$\begin{aligned} o(\mathbf{x}, t) &= \mu o_1(\mathbf{x}, t) + \mu^2 o_2(\mathbf{x}, t) + \mu^3 o_3(\mathbf{x}, t) + \dots \\ z(\mathbf{x}, t) &= \mu z_1(\mathbf{x}, t) + \mu^2 z_2(\mathbf{x}, t) + \mu^3 z_3(\mathbf{x}, t) + \dots \end{aligned} \quad (26)$$

We further introduced a common slow timescale  $T = r_z t$  and insert the expansions in Eq. (24) and get

$$\begin{aligned} 0 &= \mu \hat{L}^0 z_1 \\ &+ \mu^2 \left( -\hat{L}^0 z_2 + r_{z1} z_1 - r_{z1} \partial_T z_1 \right) \\ &+ \mu^3 \left( -r_{z2} \partial_T z_1 + r_{z2} z_1 + r_{z1} z_2 - r_{z1} \partial_T z_2 - \hat{L}^0 z_3 - N_{3,u}[z_1, z_1, \bar{z}_1] \right) \\ &+ \mu^3 \left( -N_{3,c}[z_1, o_1, o_1] \right) \\ &\vdots \end{aligned} \quad (27)$$

and

$$\begin{aligned}
0 &= \mu \hat{L}^0 o_1 \\
&+ \mu^2 \left( -\hat{L}^0 o_2 + r_{o1} o_1 - r_{z1} \partial_T o_1 + \sqrt{\mu r_{o1} + \mu^2 r_{o2} + \dots} \tilde{N}_{2,u}[o_1, o_1] \right) \\
&+ \mu^3 \left( -r_{z2} \partial_T o_1 + r_{o2} o_1 + r_{o1} o_2 - r_{z1} \partial_T o_2 - \hat{L}^0 o_3 - \tilde{N}_{3,u}[o_1, o_1, o_1] \right) \\
&+ \mu^3 \left( -\tilde{N}_{3,c}[o_1, z_1, \bar{z}_1] \right) \\
&\vdots
\end{aligned} \tag{28}$$

We consider amplitude equations up to third order as this is the order where the nonlinearity of the low order inter-map coupling energy enters first. For Eq. (114) and Eq. (115) to be fulfilled each individual order in  $\mu$  has to be zero. At linear order in  $\mu$  we get the two homogeneous equations

$$\hat{L}_z^0 z_1 = 0, \quad \hat{L}_o^0 o_1 = 0. \tag{29}$$

Thus  $z_1$  and  $o_1$  are elements of the kernel of  $\hat{L}_z^0$  and  $\hat{L}_o^0$ . Both kernels contain linear combinations of modes with a wavevector on the corresponding critical circle i.e.

$$\begin{aligned}
z_1(\mathbf{x}, T) &= \sum_j^n \left( A_j(T) e^{i\vec{k}_j \cdot \vec{x}} + A_{j-}(T) e^{-i\vec{k}_j \cdot \vec{x}} \right) \\
o_1(\mathbf{x}, T) &= \sum_j^n \left( B_j(T) e^{i\vec{k}'_j \cdot \vec{x}} + \bar{B}_j(T) e^{-i\vec{k}'_j \cdot \vec{x}} \right),
\end{aligned} \tag{30}$$

with the complex amplitudes  $A_j = \mathcal{A}_j e^{i\phi_j}$ ,  $B_j = \mathcal{B}_j e^{i\psi_j}$  and  $\vec{k}_j = k_{c,z} (\cos(j\pi/n), \sin(j\pi/n))$ ,  $\vec{k}'_j = k_{c,o} (\cos(j\pi/n), \sin(j\pi/n))$ . In view of the hexagonal or stripe layout of the OD pattern shown in Fig. 1,  $n = 3$  is an appropriate choice. Since in cat visual cortex the typical wavelength for OD and OP maps are approximately the same [56, 91] i.e.  $k_{c,o} = k_{c,z} = k_c$  the Fourier components of the emerging pattern are located on a common critical circle. To account for species differences we also analyzed models with detuned OP and OD wavelengths in part (II) of this study.

At second order in  $\mu$  we get

$$\begin{aligned}\hat{L}^0 z_2 + r_{z1} z_1 - r_{z1} \partial_T z_1 &= 0 \\ \hat{L}^0 o_2 + r_{o1} o_1 - r_{z1} \partial_T o_1 &= 0.\end{aligned}\tag{31}$$

As  $z_1$  and  $o_1$  are elements of the kernel  $r_{z1} = r_{o1} = 0$ . At third order, when applying the solvability condition (see Methods), we get

$$\begin{aligned}r_{z2} \partial_T z_1 &= r_{z2} z_1 - \hat{P}_c N_{3,u}[z_1, z_1, \bar{z}_1] - \hat{P}_c N_{3,c}[z_1, o_1, o_1] \\ r_{z2} \partial_T o_1 &= r_{o2} o_1 - \sqrt{r_{o2}} \hat{P}_c \tilde{N}_{2,u}[o_1, o_1] - \hat{P}_c \tilde{N}_{3,u}[o_1, o_1, o_1] - \hat{P}_c \tilde{N}_{3,c}[o_1, z_1, \bar{z}_1].\end{aligned}\tag{32}$$

We insert the leading order fields Eq. (117) and obtain the amplitude equations

$$\begin{aligned}r_{z2} \partial_T A_i &= r_{z2} A_i - \sum_j h_{ij} |B_j|^2 A_i - h B_i^2 A_i - \sum_j g_{ij} |A_j|^2 A_i - \sum_j f_{ij} A_j A_{j-} \bar{A}_{i-} - \dots \\ r_{z2} \partial_T B_i &= r_{o2} B_i - \sum_j h_{ij} |A_j|^2 B_i - 2\sqrt{r_{o2}} \bar{B}_{i+1} \bar{B}_{i+2} - \sum_j \tilde{g}_{ij} |B_j|^2 B_i - \dots\end{aligned}\tag{33}$$

For simplicity we have written only the simplest inter-map coupling terms. Depending on the configuration of active modes additional contributions may enter the amplitude equations. In addition, for the product-type coupling energy, there are coupling terms which contain the constant  $\delta$ , see Methods and Eq. (40). The coupling coefficients are given by

$$\begin{aligned}g_{ij} &= e^{-i\vec{k}_i \cdot \vec{x}} \left( N_{3,u}[e^{i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_j \cdot \vec{x}}, e^{-i\vec{k}_j \cdot \vec{x}}] + N_{3,u}[e^{i\vec{k}_j \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}, e^{-i\vec{k}_j \cdot \vec{x}}] \right) = 2 \\ g_{ii} &= e^{-i\vec{k}_i \cdot \vec{x}} N_{3,u}[e^{i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}, e^{-i\vec{k}_i \cdot \vec{x}}] = 1 \\ g_{ij-} &= e^{-i\vec{k}_i \cdot \vec{x}} \left( N_{3,u}[e^{i\vec{k}_i \cdot \vec{x}}, e^{-i\vec{k}_j \cdot \vec{x}}, e^{i\vec{k}_j \cdot \vec{x}}] + N_{3,u}[e^{-i\vec{k}_j \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_j \cdot \vec{x}}] \right) = 2 \\ f_{ij} &= e^{-i\vec{k}_i \cdot \vec{x}} \left( N_{3,u}[e^{i\vec{k}_j \cdot \vec{x}}, e^{-i\vec{k}_j \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}] + N_{3,u}[e^{-i\vec{k}_j \cdot \vec{x}}, e^{i\vec{k}_j \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}] \right) = 2 \\ f_{ii} &= 0 \\ h_{ij} &= e^{-i\vec{k}_i \cdot \vec{x}} N_{3,c}[e^{i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_j \cdot \vec{x}}, e^{-i\vec{k}_j \cdot \vec{x}}] \\ h_{ii} &= e^{-i\vec{k}_i \cdot \vec{x}} N_{3,c}[e^{i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}, e^{-i\vec{k}_i \cdot \vec{x}}] \\ h &= e^{-i\vec{k}_i \cdot \vec{x}} N_{3,c}[e^{-i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}, e^{i\vec{k}_i \cdot \vec{x}}].\end{aligned}\tag{34}$$



From Eq. (120) we see that inter-map coupling has two effects on the modes of the OP pattern. First, inter-map coupling shifts the bifurcation point from  $r_z$  to  $\left(r_z - \sum_j h_{ij}^{(1)} |B_j|^2\right)$ . This can cause a potential destabilization of pattern solutions for large inter-map coupling strength. Second, inter-map coupling introduces additional resonant interactions that for instance couple the modes  $A_i$  and their opposite modes  $A_{i-}$ . In case of  $A \ll B \ll 1$  the inter-map coupling terms in dynamics of the modes  $B$  are small. In this limit the dynamics of the modes  $B$  decouples from the modes  $A$  and we can use the uncoupled OD dynamics, see Methods. When we scale back to the fast time variable and set  $r_{z2} = r_z$ ,  $r_{o2} = r_o$  we obtain

$$\begin{aligned} \partial_t A_i &= r_z A_i - \sum_j h_{ij} |B_j|^2 A_i - h B_i^2 A_{i-} - \sum_j g_{ij} |A_j|^2 A_i - \sum_j f_{ij} A_j A_{j-} \bar{A}_{i-} \\ r_z \partial_t B_i &= r_o B_i - \sum_j h_{ij} |A_j|^2 B_i - 2\sqrt{r_o} \bar{B}_{i+1} \bar{B}_{i+2} - \sum_j \tilde{g}_{ij} |B_j|^2 B_i. \end{aligned} \quad (35)$$

The amplitude equations are truncated at third order. If pattern formation takes place far from threshold fifth order, seventh order, or even higher order corrections have to be considered. Moreover, at seventh order the nonlinearities of the higher order inter-map coupling terms enter the expansion. A derivation of amplitude equation with higher order inter-map coupling energies is presented in Text S1.

## 1.4 Interpretation of coupling energies

Using symmetry considerations we derived inter-map coupling energies up to eighth order in the fields, see Eq. (19), Eq.(20), and Eq.(21). Which of these various optimization principles could reproduce realistic inter-map relationships such as a uniform coverage of all stimulus features? We identified two types of optimization principles that can be expected to reproduce realistic inter-map relationships and good stimulus coverage. First, product-type coupling energies of the form  $U = o^{2n} |z|^{2n}$ ,  $n = 1, 2, \dots$ . These energies favor configurations in which regions of high gradients avoid each other and thus leading to high coverage. Second, gradient-type coupling energies of the form  $U = |\nabla o \cdot \nabla z|^{2n}$ ,  $n = 1, 2, \dots$ . In experimentally obtained maps, iso-orientation lines show the tendency to intersect the OD borders perpendicularly. Perpendicular intersection angles lead to high coverage as large changes of the field  $z$  in one direction lead to small changes of the field  $o$  in that direction. To see that the gradient-type coupling energy favors perpendicular intersection angles we decompose the complex field  $z(\mathbf{x})$  into the selectivity

$|z|$  and the preferred orientation  $\vartheta$ . We obtain

$$U = |\nabla z \cdot \nabla o|^{2n} = |z|^{2n} (|\nabla o \cdot \nabla \ln |z||^2 + 4|\nabla o \cdot \nabla \vartheta|^2)^n. \quad (36)$$

If the orientation selectivity is locally homogeneous, i.e.  $\nabla \ln |z| \approx 0$ , then the energy is minimized if the direction of the iso-orientation lines ( $\nabla \vartheta$ ) is perpendicular to the OD borders. In our symmetry-based analysis we further identified terms that are expected to lead to the opposite behavior for instance mixture terms such as  $U = o^2 \nabla z \cdot \nabla \bar{z}$ .

Pinwheels are prominent features in OP maps. We therefore also analyze how different optimization principles impact on the pinwheel positions with respect to the co-evolving feature maps. The product-type coupling energies are expected to favor pinwheels at OD extrema. Pinwheels are zeros of  $z$  and are thus expected to reduce this energy term. They will reduce energy the most when  $|o|$  is maximal which should repel pinwheels from OD borders, where  $o(\mathbf{x})$  is zero. Also the gradient-type coupling energy is expected to couple the OD pattern with the position of pinwheels. To see this we decompose the field  $z$  into its real and imaginary part

$$U = (|\nabla o \cdot \nabla \text{Re} z|^2 + |\nabla o \cdot \nabla \text{Im} z|^2). \quad (37)$$

At pinwheel centers the zero contours of  $\text{Re} z$  and  $\text{Im} z$  cross. Since there  $\nabla \text{Re} z$  and  $\nabla \text{Im} z$  are almost constant and not parallel the energy can be minimized only if  $|\nabla o|$  is small at the pinwheel centers, i.e. the extrema or saddle-points of  $o(\mathbf{x})$ .

From the previous considerations we assume all coupling coefficients of the energies to be positive. A negative coupling coefficient can be saturated by higher order inter-map coupling terms. In the following, we discuss the impact of the low order inter-map coupling energies on the resulting optima of the system using the derived amplitude equations. The corresponding analysis for higher order inter-map coupling energies is provided in Text S1.

## 2.1 Optima of particular optimization principles: Low order coupling terms

As indicated by numerical simulations and weakly nonlinear analysis of the uncoupled OD dynamics, see Methods, we discussed the influence of the OD stripe, hexagon, and constant solutions on the OP map

using the coupled amplitude equations derived in the previous section. A potential backreaction onto the dynamics of the OD map can be neglected if the modes  $A_j$  of the OP map are much smaller than the modes  $B_j$  of the OD map. This can be achieved if  $r_z \ll r_o$ . We first give a brief description of the uncoupled OP solutions. Next, we study the impact of the low order coupling energies in Eq. (22) on these solutions. We demonstrate that these energies can lead to a complete suppression of orientation selectivity. In the uncoupled case there are for  $r_z > 0$  two stable stationary solutions to the amplitude equations Eq. (??), namely OP stripes

$$z_{\text{st}} = \mathcal{A} e^{i(\vec{k}_1 \cdot \vec{x} + \phi)}, \quad \mathcal{A} = \sqrt{r_z}, \quad (38)$$

and OP rhombic solutions

$$z_{\text{rh}} = \mathcal{A} \sum_{j=1}^2 \left( e^{i\vec{k}_j \cdot \vec{x} + \phi_j} + e^{-i\vec{k}_j \cdot \vec{x} + \phi_{j-}} \right), \quad (39)$$

with  $\phi_1 + \phi_{1-} = \phi_0$ ,  $\phi_2 + \phi_{2-} = \phi_0 + \pi$ ,  $\phi_0$  an arbitrary phase, and  $\mathcal{A} = \sqrt{r_z/5} \approx 0.447\sqrt{r_z}$ . In the uncoupled case the angle  $\alpha = \arccos \vec{k}_1 \cdot \vec{k}_2 / k_c^2$  between the Fourier modes is arbitrary. The stripe solutions are pinwheel free while the pinwheel density for the rhombic solutions varies as  $\rho = 4 \sin \alpha$  and thus  $0 \leq \rho \leq 4$ . For the rhombic solutions pinwheels are located on a regular lattice. We therefore refer to these and other pinwheel rich solutions which are spatially periodic as pinwheel crystals (PWC). In particular, we refer to pinwheel crystals with as rhombic spatial layout as rPWC solutions and pinwheel crystals with a hexagonal layout as hPWC solutions. Without inter-map coupling, the potential of the two solutions reads  $V_{\text{st}} = -\frac{1}{2}r_z^2 < V_{\text{rh}} = -\frac{2}{5}r_z^2$ , thus the stripe solutions are always energetically preferred compared to rhombic solutions.

In the following we study three scenarios in which inter-map coupling can lead to pinwheel stabilization. First, a deformation of the OP stripe solution can lead to the creation of pinwheels in this solution. Second, inter-map coupling can energetically prefer the (deformed) OP rhombic solutions compared to the stripe solutions. Finally, inter-map coupling can lead to the stabilization of new PWC solutions.

For the low order interaction terms the amplitude equations are given by  $\partial_t A_i = -\delta V / \delta \bar{A}_i$ ,  $\partial_t B_i =$

$-\delta V/\delta \bar{B}_i$  with the potential

$$\begin{aligned}
V = & V_A + V_B + \alpha \delta^2 \sum_j^3 (|A_j|^2 + |A_{j-}|^2) \\
& + 2\alpha \delta (A_1 \bar{A}_2 - B_3 + A_1 \bar{A}_3 - B_2 + A_{1-} \bar{A}_2 \bar{B}_3 + A_{1-} \bar{A}_3 \bar{B}_2) \\
& + \sum_{i,j} g_{ij}^{(1)} |A_i|^2 |B_j|^2 + \sum_{i \neq j} g_{ij}^{(2)} A_i \bar{A}_j \bar{B}_i B_j + \sum_{i \neq j} g_{ij}^{(2)} A_{i-} \bar{A}_{j-} B_i \bar{B}_j \\
& + \sum_{i,j} g_{ij}^{(3)} A_i \bar{A}_{j-} \bar{B}_i \bar{B}_j + \sum_{i,j} g_{ij}^{(3)} \bar{A}_i A_{j-} B_i B_j,
\end{aligned} \tag{40}$$

with the uncoupled contributions

$$\begin{aligned}
V_A = & -r_z \sum_j^3 |A_j|^2 + \frac{1}{2} \sum_{i,j}^3 g_{ij} |A_i|^2 |A_j|^2 + \frac{1}{2} \sum_{i,j}^3 f_{ij} A_i A_{i-} \bar{A}_j \bar{A}_{j-} \\
V_B = & -r_o \sum_j^3 |B_j|^2 + \frac{1}{2} \sum_{i,j}^3 \tilde{g}_{ij} |B_i|^2 |B_j|^2.
\end{aligned} \tag{41}$$

The coupling coefficients read  $g_{ij}^{(1)} = 2\alpha + 2\beta \cos^2(\alpha_{ij})$ ,  $g_{ij}^{(2)} = 2\alpha + \beta (1 + \cos^2(\alpha_{ij}))$ ,  $g_{ij}^{(3)} = 2\alpha + \beta (1 + \cos^2(\alpha_{ij}))$ ,  $g_{ii}^{(3)} = \alpha + \beta$ , where  $\alpha_{ij}$  is the angle between the wavevector  $\vec{k}_i$  and  $\vec{k}_j$ .

## 2.2 Product-type energy $U = \alpha o^2 |z|^2$

We first studied the impact of the low order product-type coupling energy. Here, the constant  $\delta(\gamma)$  enters explicitly in the amplitude equations, see Eq. (40) and Eq. (68).

### 2.2.1 Stationary solutions and their stability

In the case of OD stripes, see Methods, with  $B_1 = B, B_2 = B_3 = 0$  we get the following amplitude equations

$$\begin{aligned}
\partial_t A_1 &= (r_z - \alpha \delta^2 - 2\alpha |B|^2) A_1 - \alpha B^2 A_{1-} + \text{nct.} \\
\partial_t A_2 &= (r_z - \alpha \delta^2 - 2\alpha |B|^2) A_2 - 2\alpha \delta A_{3-} \bar{B} + \text{nct.} \\
\partial_t A_3 &= (r_z - \alpha \delta^2 - 2\alpha |B|^2) A_3 - 2\alpha \delta A_{2-} \bar{B} + \text{nct.}
\end{aligned} \tag{42}$$

where nct. refers to non inter-map coupling terms  $-\sum_j^3 g_{ij}|A_j|^2 A_i - \sum_{j \neq i}^3 f_{ij} A_j A_{j-} \bar{A}_{i-}$ , resulting from the potential  $V_A$ , see Eq. (126). The equations for the modes  $A_{i-}$  are given by interchanging the modes  $A_i$  and  $A_{i-}$  as well as interchanging the modes  $B_i$  and  $\bar{B}_i$ . The OP stripe solution in case of inter-map coupling is given by

$$z = \mathcal{A}_1 e^{i(\vec{k}_1 \cdot \vec{x} + \phi_1)} + \mathcal{A}_{1-} e^{-i(\vec{k}_1 \cdot \vec{x} + \phi_{1-})}, \quad (43)$$

with  $\mathcal{A}_1 = p^{3/2}/(2\sqrt{2}B^2\alpha)$ ,  $\mathcal{A}_{1-} = p/\sqrt{2}$ , and

$p = r_z - 2B^2\alpha - \alpha\delta^2 - \sqrt{(r_z - \alpha\delta^2)(r_z - \alpha(4B^2 + \delta^2))}$  and the phase relation

$\phi_1 - \phi_{1-} = 2\psi_1 + \pi$ . In the uncoupled case ( $\alpha = 0$ ) they reduce to  $\mathcal{A}_{1-} = 0$  and  $\mathcal{A}_1 = \sqrt{r_z}$ . With increasing inter-map coupling the amplitude  $\mathcal{A}_{1-}$  grows and the solutions are transformed, reducing the representation of all but two preferred orientations. The parameter dependence of this solution is shown in Fig. **2A** for different values of the bias  $\gamma$ . Both amplitudes become identical at  $\alpha = r_z/(4B^2 + \delta^2)$  with

$$\mathcal{A}_1 = \mathcal{A}_{1-} = \sqrt{\frac{r_z - \alpha B^2 - \alpha\delta^2}{3}}. \quad (44)$$

This pattern solution finally vanishes at

$$\alpha_c = r_z/(B^2 + \delta^2) = 3r_z/r_o. \quad (45)$$

This existence border is thus independent of the OD bias  $\gamma$ . Above this coupling strength only the trivial solution  $A_j = 0, \forall j$  is stable.

In addition to the OP stripe patterns there exist rhombic OP solutions, see Fig. **2B**. These rhombic solutions are pinwheel rich with a pinwheel density of  $\rho = 4 \sin \pi/3 \approx 3.46$  but are energetically not preferred compared to the stripe solutions, see Fig. **2E**. The rhombic solutions in the uncoupled case  $\mathcal{A}_1 = \mathcal{A}_{1-} = \mathcal{A}_2 = \mathcal{A}_{2-}, \mathcal{A}_3 = \mathcal{A}_{3-} = 0$  are transformed by inter-map coupling. The phase relations are given by

$$\begin{aligned} \phi_1 + \phi_{1-} &= \phi_0, & \phi_1 - \phi_{1-} &= 2\psi_1 + \pi \\ \phi_2 + \phi_{2-} &= \phi_0 + \pi, & \phi_3 + \phi_{3-} &= \phi_0 + \pi \\ \psi_1 + \phi_2 + \phi_3 &= \phi_0, \end{aligned} \quad (46)$$

where  $\phi_0$  is an arbitrary phase. Stationary amplitudes are given by

$$\begin{aligned}\mathcal{A}_1 = \mathcal{A}_{1-} &= \sqrt{\frac{r_z + \alpha(\mathcal{B}^2 - \delta^2)}{5}} \\ \mathcal{A}_2 = \mathcal{A}_{2-} &= \sqrt{\frac{3r_z - 12\mathcal{B}^2\alpha - 3\alpha\delta^2 - 1/3q}{30}} \\ \mathcal{A}_3 = \mathcal{A}_{3-} &= \mathcal{A}_2 \frac{3r_z - 12\mathcal{B}^2\alpha - 3\alpha\delta^2 + 1/3q}{20\mathcal{B}\alpha\delta},\end{aligned}\quad (47)$$

with  $q = \sqrt{-3600\mathcal{B}^2\alpha^2\delta^2 + (-9r_z + 36\mathcal{B}^2\alpha + 9\alpha\delta^2)^2}$ . With increasing inter-map coupling strength  $\alpha$  the amplitudes  $\mathcal{A}_2 = \mathcal{A}_{2-}$  are suppressed, see Fig. (2)**B**. In addition, for nonzero bias  $\gamma$ , there is an increase of the amplitudes  $\mathcal{A}_3 = \mathcal{A}_{3-}$ . The amplitudes  $\mathcal{A}_2$  and  $\mathcal{A}_3$  collapse at  $\alpha/r_z = 3/(12\mathcal{B}^2 + 20\mathcal{B}\delta + 3\delta^2)$ . A further increase of the inter-map coupling strength leads to a suppression of these amplitudes and finally to the OP stripe pattern where  $\mathcal{A}_2 = \mathcal{A}_3 = 0$ .

In the case the OD map is a constant, Eq. (91), the amplitude equations simplify to

$$\partial_t A_i = (r_z - \alpha\delta^2) A_i - \sum_j g_{ij} |A_j|^2 A_i - \sum_j f_{ij} A_j A_{j-} \bar{A}_{i-}. \quad (48)$$

Thus inter-map coupling in this case only renormalizes the bifurcation parameter and the energetic ground state is thus a stripe pattern with an inter-map coupling dependent reduction of the amplitudes

$$\mathcal{A}_1 = \sqrt{r_z - \alpha\delta^2}, \mathcal{A}_2 = \mathcal{A}_3 = 0. \quad (49)$$

Therefore at  $\alpha_c = r_z/\delta^2$  the stripe pattern ceases to exist and the only stable solution is the trivial one i.e.  $A_i = 0$ . In addition, there is the rhombic solution with the stationary amplitudes

$$\mathcal{A}_1 = \mathcal{A}_{1-} = \mathcal{A}_2 = \mathcal{A}_{2-} = \sqrt{\frac{r_z - \alpha\delta^2}{5}}, \mathcal{A}_3 = 0. \quad (50)$$

In the case of OD hexagons  $B_i = \mathcal{B}e^{i\psi_i}$ , Eq. (90), the amplitude equations read

$$\begin{aligned}\partial_t A_i &= (r_z - 6\alpha\mathcal{B}^2 - \alpha\delta^2) A_i - \alpha\mathcal{B}^2 \left( A_{i-} e^{2i\psi_i} + 2A_{(i+1)-} e^{i(\psi_i + \psi_{i+1})} + 2A_{(i+2)-} e^{i(\psi_i + \psi_{i+2})} \right) \\ &\quad - 2\alpha\mathcal{B}^2 \left( A_{i+1} e^{i(\psi_i - \psi_{i+1})} + A_{i+2} e^{i(\psi_i - \psi_{i+2})} \right) \\ &\quad - 2\alpha\delta\mathcal{B} \left( A_{(i+1)-} e^{-i\psi_{i+2}} + A_{(i+2)-} e^{-i\psi_{i+1}} \right) + \text{nct.},\end{aligned}\quad (51)$$

where the indices are cyclic i.e.  $i + 3 = i$ . These amplitude equations have stripe-like solutions as well as solutions with a rhombic layout of the form  $\mathcal{A}_1 = \mathcal{A}_{1-} = \mathcal{A}_2 = \mathcal{A}_{2-}$ ,  $\mathcal{A}_3 = \mathcal{A}_{3-}$ . For both solutions the stationary phases depend on the inter-map coupling strength  $\alpha$ . In this case stationary solutions of Eq. (51) are calculated numerically using a Newton method and initial conditions close to these solutions. In contrast to the case of OD stripes and OD constant solutions the amplitude equations (51) have an additional type of PWC solution which have uniform amplitudes,  $A_j = \mathcal{A}e^{i\phi_i}$ . The dynamics of their phases is given by

$$\begin{aligned}
\partial_t \phi_i = & 2\mathcal{A}^2 \sum_{j \neq i} \sin(\phi_i + \phi_{i-} - \phi_j - \phi_{j-}) \\
& - \mathcal{B}^2 \alpha \sum_{j \neq i} (2 \sin(\phi_i - \phi_j - \psi_i + \psi_j) + 2 \sin(\phi_i - \phi_{j-} - \psi_i - \psi_j)) \\
& - \mathcal{B}^2 \alpha \sin(\phi_i - \phi_{i-} - 2\psi_i) \\
& - 2\delta\alpha\mathcal{B} (\sin(\phi_i - \phi_{(i+1)-} + \psi_{i+2}) + \sin(\phi_i - \phi_{(i+2)-} + \psi_{i+1})) .
\end{aligned} \tag{52}$$

When solving the amplitude equations numerically we observe that the phase relations vary with the inter-map coupling strength for non-uniform solutions. But for the uniform solution the phase relations are independent of the inter-map coupling strength. The phases of the uniform solution are determined up to a free phase  $\varphi$  which results from the orientation shift symmetry  $z \rightarrow z e^{i\varphi}$  of Eq. (9). We therefore choose  $\phi_1 = \psi_1$ . As an ansatz for the uniform solutions we use

$$\begin{aligned}
\mathcal{A}_j &= \mathcal{A}_{j-} = \mathcal{A}, \quad j = 1, 2, 3 \\
\phi_j &= \psi_j + (j-1)2\pi/3 + \Delta \delta_{j,2} \\
\phi_{j-} &= -\psi_j + (j-1)2\pi/3 + \Delta (\delta_{j,1} + \delta_{j,3}),
\end{aligned} \tag{53}$$

where  $\delta_{i,j}$  is the Kronecker delta and  $\Delta$  a constant parameter. Note, that  $z(\mathbf{x})$  cannot become real since  $\phi_j \neq -\phi_{j-}$ . The equation for the uniform amplitudes is then given by

$$\partial_t \mathcal{A} = r_z \mathcal{A} - 9\mathcal{A}^3 - 4\alpha\mathcal{B}^2 \mathcal{A} - \alpha\delta^2 \mathcal{A} + \mathcal{A}\mathcal{B}\alpha(\mathcal{B} - 2\delta) \cos \Delta, \tag{54}$$

while the phase dynamics reads

$$\partial_t \phi_j = -\mathcal{B}\alpha(\mathcal{B} - 2\delta) \sin \Delta. \tag{55}$$

The stationarity condition is fulfilled for an arbitrary  $\delta$  only if  $\Delta = 0$  or  $\Delta = \pi$ . The corresponding amplitudes are given by solving the stationarity condition for the real part and read

$$\mathcal{A}_{\Delta=0} = \sqrt{\frac{r_z - \alpha(3\mathcal{B}^2 + 2\mathcal{B}\delta + \delta^2)}{9}}, \quad \mathcal{A}_{\Delta=\pi} = \sqrt{\frac{r_z - \alpha(5\mathcal{B}^2 - 2\mathcal{B}\delta + \delta^2)}{9}}. \quad (56)$$

We calculate the stability properties of all solutions by linear stability analysis considering perturbations of the amplitudes  $\mathcal{A}_j \rightarrow \mathcal{A} + a_j$ ,  $\mathcal{A}_{j-} \rightarrow \mathcal{A} + a_{j-}$  and of the phases  $\phi_j \rightarrow \phi_j + \varphi_j$ ,  $\phi_{j-} \rightarrow \phi_{j-} + \varphi_{j-}$ . This leads to a perturbation matrix  $M$ . Amplitude and phase perturbations in general do not decouple. We calculated the eigenvalues of the perturbation  $M$  matrix numerically and checked the results by direct numerical simulation of the amplitude equations. In case of the uniform solutions Eq. (134) the perturbation matrix  $M$  is explicitly stated in Text S3.

The stability of the  $\Delta = 0$  and  $\Delta = \pi$  uniform solutions depends on the coupling strength  $\alpha$  and on the sign of  $(\mathcal{B} - 2\delta)$ . As the solution of  $B(\gamma) = 2\delta(\gamma)$  is given by  $\gamma = \gamma^*$  in the stability range of OD hexagons there is only one possible stable uniform solution, the  $\Delta = \pi$  uniform solution. This solution ceases to exist at  $r_z < \alpha(5\mathcal{B}^2 - 2\mathcal{B}\delta + \delta^2)$ . This existence border is in fact independent of the bias  $\gamma$  and given by

$$\alpha_c = 3r_z/r_o. \quad (57)$$

Thus the limit  $r_z \rightarrow 0$  makes the uniform solution unstable for smaller and smaller coupling strengths.

### 2.2.2 Bifurcation diagram

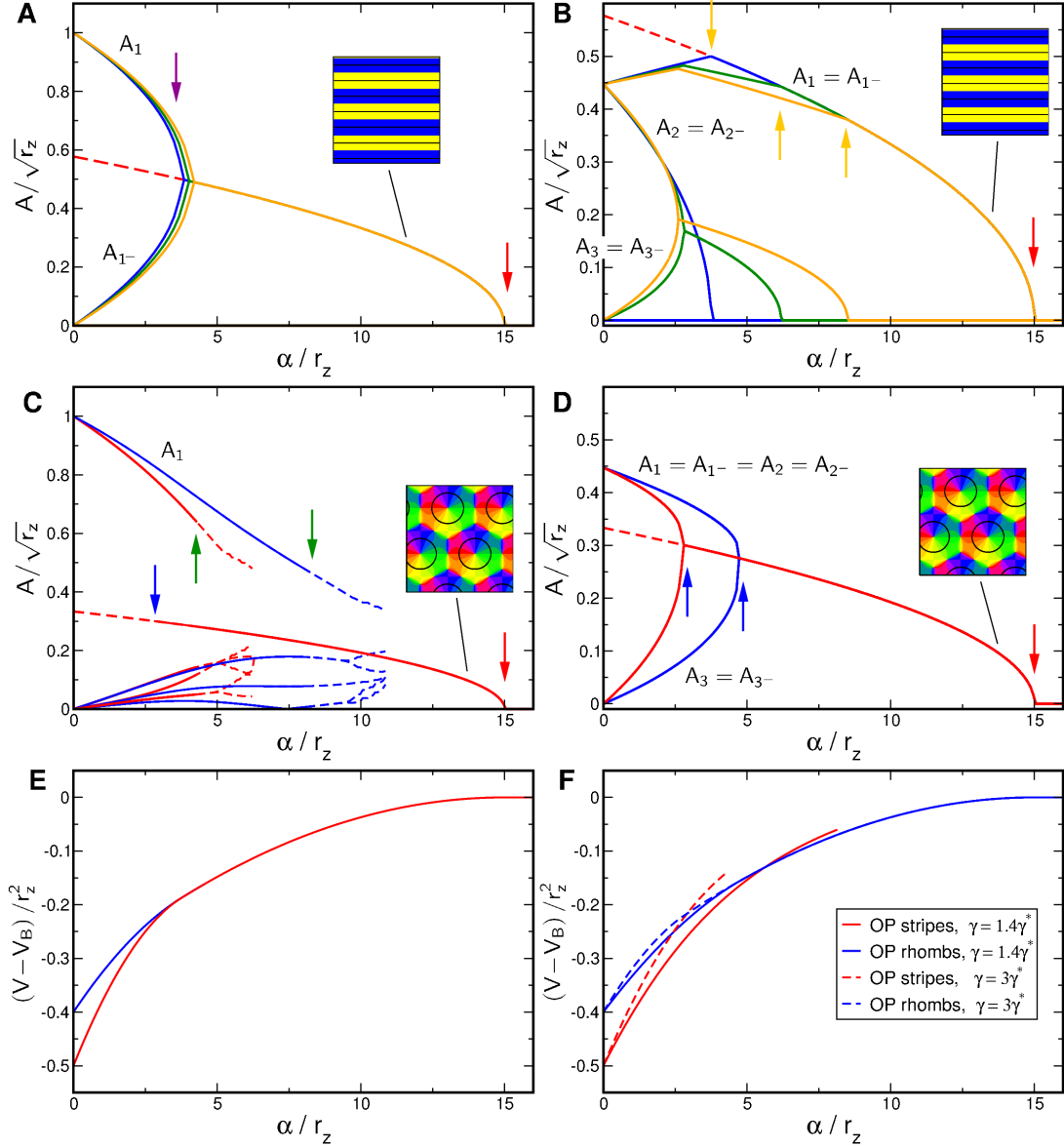
The case of OP solutions when interacting with OD stripes is shown in Fig. 2**A,B**. In case of OP stripes inter-map coupling suppresses the amplitude  $A_1$  of the stripe pattern while increasing the amplitude of the opposite mode  $A_{1-}$ . This transformation reduces the representation of all but two preferred orientations. When both amplitudes collapse the resulting OP map is selective only to two orthogonal orientations namely  $\vartheta = \phi_1$  and  $\vartheta = \phi_1 + \pi/2$ . We refer to these unrealistic solutions as *orientation scotoma solutions*. The phase relations ensure that OD borders that run parallel to the OP stripes are located at the OP maxima and minima i.e. in the center of the orientation scotoma stripes. With increasing inter-map coupling, this orientation scotoma pattern is suppressed until finally all amplitudes are zero and only the homogeneous solution is stable. In case of OP rhombs inter-map coupling makes the rhombic pattern more stripe-like by reducing the amplitude  $A_2 = A_{2-}$ . The mode  $A_3 = A_{3-}$  which is zero in the



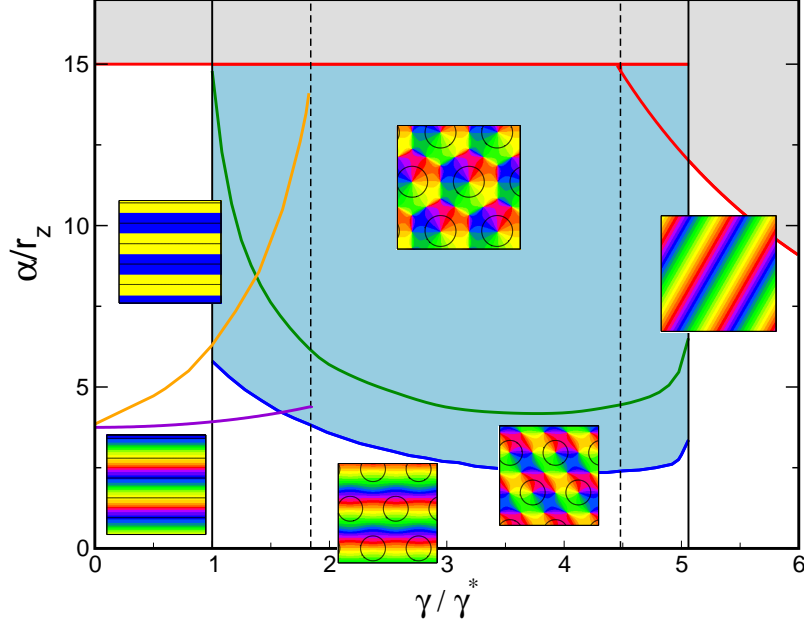
uncoupled case increases and finally collapses with the mode  $A_2$ . Increasing inter-map coupling more suppresses all but the two modes  $A_1 = A_{1-}$ , leading again to the orientation scotoma stripe pattern.

The parameter dependence of OP solutions when interacting with OD hexagons is shown in Fig. **2C,D**. OP stripe solutions became above a critical inter-map coupling strength unstable against PWC solutions. This critical coupling strength strongly depended on the OD bias. OP rhombic solutions also became unstable against PWC but for a lower coupling strength than the OP stripes. Thus there is at intermediate coupling strength a bistability between stripe-like solutions and PWC solutions. The potential of the OP stripe and OP rhombic solutions is shown in Fig. **2E,F**. Stripes are energetically preferred in the uncoupled case as well as for small inter-map coupling strength for which they are stable.

To summarize, stripe solutions were deformed but no pinwheels were created for this solution. The rhombic solutions were energetically not preferred for low inter-map coupling whereas for intermediate inter-map coupling these solutions lose pinwheels and became stripe solutions. Instead, additional pinwheel rich solutions with a crystal layout became stable for intermediate inter-map coupling. For large inter-map coupling orientation selectivity was completely suppressed.



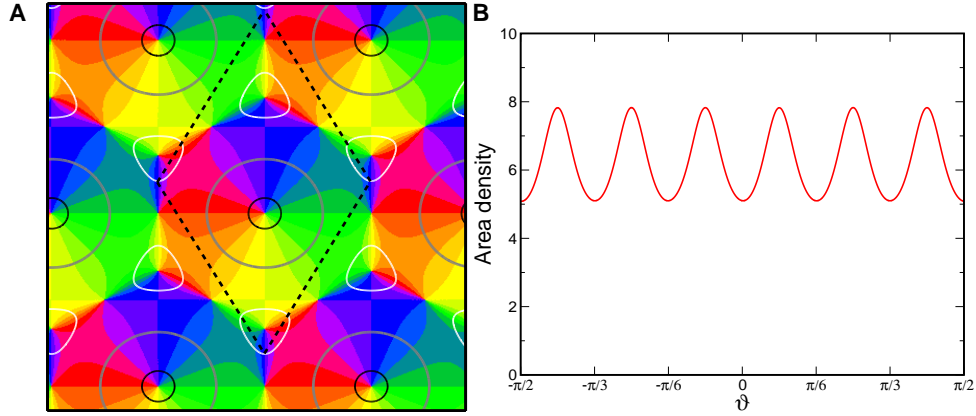
**Figure 2. Stationary amplitudes with coupling energy  $U = \alpha |\mathbf{z}|^2 \mathbf{o}^2$ ,  $r_o = 0.2$ .** Solid (dashed) lines: stable (unstable) solutions to Eq. (42) (OD stripes) and Eq. (51) (OD hexagons). **A,B** OD stripes,  $\gamma = 0$  (blue),  $\gamma = \gamma^*$  (green),  $\gamma = 1.4\gamma^*$  (orange). **C,D** OD hexagons,  $\gamma = 1.4\gamma^*$  (blue),  $\gamma = 3\gamma^*$  (red). **A,C** Transition from OP stripe solutions, **B,D** Transition from OP rhombic solutions. **E** Potential for OP stripes (red) and OP rhombs (blue) interacting with OD stripes,  $\gamma = 0$ . **F** Potential for OP stripes and OP rhombs interacting with OD hexagons. Arrows indicate corresponding lines in the phase diagram, Fig. (3).



**Figure 3. Phase diagram with the coupling energy  $U = \alpha \mathbf{o}^2 |\mathbf{z}|^2$ ,  $r_o = 0.2, r_z \ll r_o$ .** Vertical lines: stability range of OD stripes, hexagons, and constant solution. Magenta (orange) line: transition of stripes (rhombs) to the orientation scotoma solution. Blue line: stability border for the  $\Delta = \pi$  uniform solution (hPWC). Green line: stability line of stripe-like solutions. Red line: pattern solutions ceases to exist, see Eq. (45) and Eq. (57). Blue region: stability region of hPWC, gray region: No pattern solution exists.

### 2.2.3 Phase diagram

The phase diagram as a function of the OD bias  $\gamma$  and the inter-map coupling strength  $\alpha$  for this coupling energy is shown in Fig. 3. When rescaling the inter-map coupling strength as  $\alpha/r_z$  the phase diagram is independent of the bifurcation parameter of the OP map  $r_z$ . Thus for fixed  $r_o \gg r_z$  the phase diagram depends only on two control parameters  $\gamma/\gamma^*$  and  $\alpha/r_z$ . The phase diagram contains the stability borders of the uncoupled OD solutions  $\gamma^*, \gamma_2^*, \gamma_3^*, \gamma_4^*$ . They correspond to vertical lines, as they are independent of the inter-map coupling in the limit  $r_z \ll r_o$ . At  $\gamma = \gamma^*$  hexagons become stable. Stripe solutions become unstable at  $\gamma = \gamma_2^*$ . At  $\gamma = \gamma_3^*$  the homogeneous solution becomes stable while at  $\gamma = \gamma_4^*$  hexagons lose their stability. In the units  $\gamma/\gamma^*$  the borders  $\gamma_2^*, \gamma_3^*, \gamma_4^*$  vary slightly with  $r_o$ , see Fig. 9, and are drawn here for  $r_o = 0.2$ . Colored lines correspond to the stability and existence borders of OP solutions. In the region of stable OD stripes the OP stripes run parallel to the OD stripes. With increasing inter-map coupling strength the orientation preference of all but two orthogonal orientations is suppressed. In the



**Figure 4. Ipsi-center pinwheel crystal.** **A** OP map, superimposed are the OD borders (gray), 90% ipsilateral eye dominance (black), and 90% contralateral eye dominance (white),  $r_o = 0.2$ ,  $\gamma = 3\gamma^*$ . Dashed lines mark the unit cell of the regular pattern. **B** Distribution of preferred orientations.

region of stable OD hexagons stripe-like OP solutions dominate for low inter-map coupling strength. Above a critical bias dependent coupling strength the  $\Delta = \pi$  uniform solution becomes stable (blue line). There is a region of bistability between stripe-like and uniform solutions until the stripe-like solutions lose their stability (orange line). OP rhombic solutions lose their stability when the uniform solution becomes stable. Thus there is no bistability between OP rhombs and OP uniform solutions. As in the case of OD stripes the uniform solution becomes unstable at  $\alpha = r_z/(3\mathcal{B}^2)$ . Also in the case of OD hexagons the inter-map coupling leads to a transition towards the trivial solution where there is no OP pattern at all. In case of the OD constant solution the OP map is a stripe solution. Pinwheel rich solutions thus occur only in the region of stable OD hexagons. In the following we discuss the properties of these solutions.

#### 2.2.4 Interaction induced pinwheel crystals

The uniform solution Eq. (134) with  $\Delta = \pi$  is illustrated in Fig. 4. For all stationary solutions the positions of the pinwheels are fixed by the OD map and there are no translational degrees of freedom. The unit cell (dashed line) contains 6 pinwheels which leads to a pinwheel density of  $\rho = 6 \cos \pi/6 \approx 5.2$ . Two of them are located at OD maxima (contra center) while one is located at an OD minimum (ipsi center). The remaining three pinwheels are located at OD saddle-points. Therefore, all pinwheels are located where the gradient of the OD map is zero. The pinwheel in the center of the OP hexagon is at the ipsilateral OD peak. Because these pinwheels organize most of the map while the others essentially only

match one OP hexagon to its neighbors we refer to this pinwheel crystal as the *Ipsi-center pinwheel crystal*. The iso-orientation lines intersect the OD borders (gray) exactly with a right angle. The intersection angles are, within the stability range of OD hexagons, independent of the bias  $\gamma$ . The remarkable property of perfect intersection angles cannot be deduced directly from the coupling energy term. The solution is symmetric under a combined rotation by  $60^\circ$  and an orientation shift by  $-60^\circ$ . The symmetry of the pattern is reflected by the distribution of preferred orientations, see Fig. 4B. Although the pattern is selective to all orientations the six orientations  $\vartheta + n\frac{\pi}{6}$ ,  $n = 0, \dots, 5$  are slightly overrepresented.

To summarize, the low order product-type inter-map coupling leads in case of OD hexagons to a transition from pinwheel free stripe solutions towards pinwheel crystals. The design of the PWC is an example of an orientation hypercolumn dominated by one pinwheel. With increasing inter-map coupling the PWC solution is suppressed until only the homogeneous solution is stable. In case of OD stripes or the constant solution the OP solutions are pinwheel free stripe pattern.

### 2.3 Gradient-type energy $U = \beta|\nabla z \cdot \nabla o|^2$

When using a gradient-type inter-map coupling energy the interaction terms are independent of the OD shift  $\delta$ . In this case, the coupling strength can be rescaled as  $\beta\mathcal{B}^2$  and is therefore independent of the bias  $\gamma$ . The bias in this case only determines the stability of OD stripes, hexagons or the constant solution.

#### 2.3.1 Stationary solutions and their stability

A coupling to OD stripes is easy to analyze in the case of a gradient-type inter-map coupling. The energetically preferred solutions are OP stripes with the direction perpendicular to the OD stripes for which  $U = 0$ . This configuration corresponds to the Hubel and Wiesel Ice-cube model [2]. In addition there are rPWC solutions with the stationary amplitudes  $\mathcal{A}_1 = \mathcal{A}_{1-} = \sqrt{(r_z + 2\mathcal{B}^2\beta)/5}$ ,  $\mathcal{A}_2 = \mathcal{A}_{2-} = \sqrt{(r_z - \mathcal{B}^2\beta)/5}$ ,  $\mathcal{A}_3 = \mathcal{A}_{3-} = 0$ , and the stationary phases as in Eq. (46). Increasing inter-map coupling strength  $\beta$  leads to an increase of the amplitudes  $\mathcal{A}_1 = \mathcal{A}_{1-}$  while decreasing the amplitudes  $\mathcal{A}_2 = \mathcal{A}_{2-}$  thus making the rhombic solution more stripe-like.

In the case the OD map is a constant, Eq. (91), the gradient-type inter-map coupling leaves the OP dynamics unaffected. The stationary states are therefore OP stripes with an arbitrary direction and rPWC solutions as in the uncoupled case.

In the case of OD hexagons the amplitude equations read

$$\begin{aligned} \partial_t A_i = & (r_z - 3\beta\mathcal{B}^2) A_i + \frac{5}{4}\beta\mathcal{B}^2 \left( A_{i+1}e^{i(\psi_i - \psi_{i+1})} + A_{i+2}e^{i(\psi_i - \psi_{i+2})} \right) \\ & - \beta\mathcal{B}^2 \left( A_{i-}e^{2i\psi_i} + \frac{5}{4}A_{(i+1)-}e^{i(\psi_i + \psi_{i+1})} + \frac{5}{4}A_{(i+2)-}e^{i(\psi_i + \psi_{i+2})} \right) + \text{nct.} \end{aligned} \quad (58)$$

Using  $A_i = \mathcal{A}_i e^{i\phi_i}$  we obtain the phase equations

$$\begin{aligned} \mathcal{A}_i \partial_t \phi_i = & \sum_{j \neq i} \mathcal{A}_j \mathcal{A}_{j-} \mathcal{A}_{i-} \sin(\phi_i + \phi_{i-} - \phi_j - \phi_{j-}) \\ & - \mathcal{B}^2 \beta \sum_{j \neq i} \left( \frac{5}{4} \mathcal{A}_j \sin(\phi_i - \phi_j - \psi_i + \psi_j) + \frac{5}{4} \mathcal{A}_{j-} \sin(\phi_i - \phi_{j-} - \psi_i - \psi_j) \right) \\ & - \mathcal{B}^2 \beta \mathcal{A}_{i-} \sin(\phi_i - \phi_{i-} - 2\psi_i) . \end{aligned} \quad (59)$$

These amplitude equations have stripe-like and rhombic solutions with inter-map coupling dependent phase relations. We therefore calculate their stationary phases and amplitudes numerically using a Newton method and initial conditions close to these solutions. Besides stripe-like and rhombic solutions these amplitude equations have uniform solutions. Again we find that the ansatz Eq. (134) can satisfy the stationarity condition. The phase dynamics in this case reads

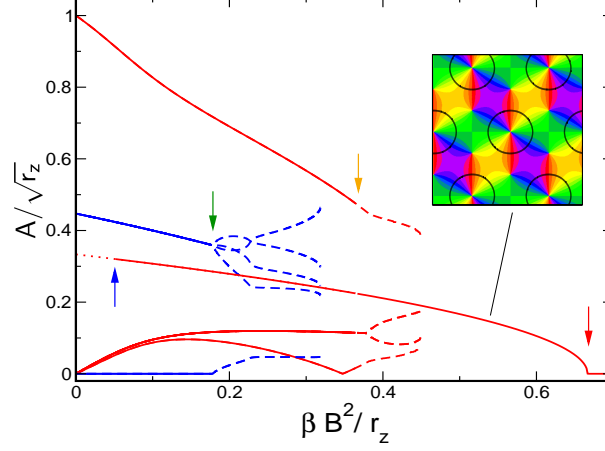
$$\partial_t \phi_i = -\frac{1}{4}\mathcal{B}^2 \beta \sin \Delta . \quad (60)$$

As in the case of the product-type inter-map coupling energy stationary solutions are  $\Delta = 0$  and  $\Delta = \pi$  with the stationary amplitudes

$$\mathcal{A}_{\Delta=0} = \sqrt{\frac{r_z - 3/2\mathcal{B}^2\beta}{9}}, \quad \mathcal{A}_{\Delta=\pi} = \sqrt{\frac{r_z - 2\mathcal{B}^2\beta}{9}} . \quad (61)$$

We studied the stability properties of both stationary solutions by linear stability analysis where amplitude and phase perturbations in general do not decouple. The stability matrix of the uniform solutions is given in Text S3. The eigenvalues are calculated numerically. It turned out that the  $\Delta = \pi$  solution is unstable for  $\beta > 0$  while the  $\Delta = 0$  solution becomes stable for  $\beta \approx 0.05r_z/\mathcal{B}^2$ . The  $\Delta = 0$  solution loses its stability above

$$\beta_c \mathcal{B}^2 = 2r_z/3 . \quad (62)$$



**Figure 5. Stationary amplitudes with  $U = \beta|\nabla\mathbf{z}\cdot\nabla\mathbf{o}|^2$  and OD hexagons.** Solid (dashed) lines: Stable (unstable) solutions to Eq. (58). Transition from OP stripes towards the uniform solution (red), transition from OP rhombs towards the uniform solution (blue). Arrows indicate corresponding lines in the phase diagram, Fig. (6).

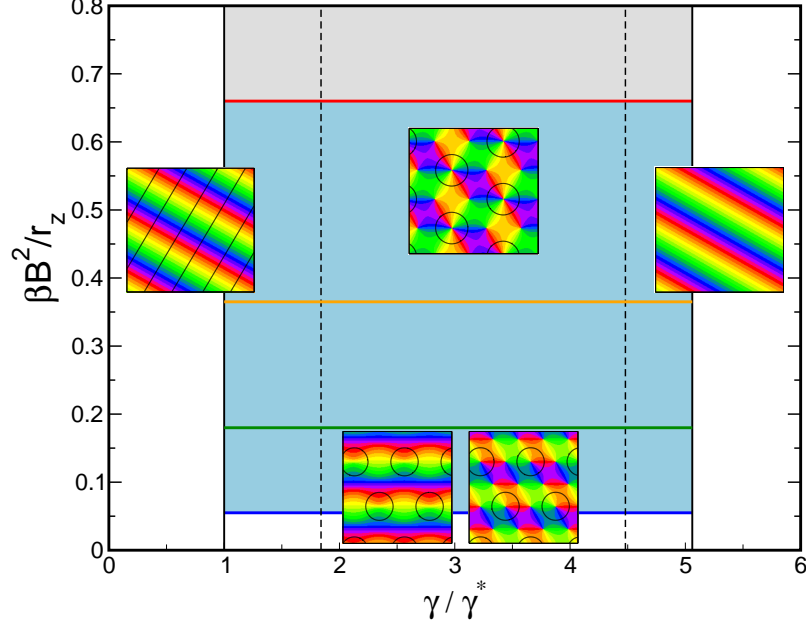
From thereon only the homogeneous solution  $A_j = 0$  is stable.

### 2.3.2 Bifurcation diagram

The course of the stationary amplitudes when interacting with OD hexagons is shown in Fig. 5. The OP rhombic solution is almost unchanged by inter-map coupling but above a critical coupling strength the rhombs decay into a stripe-like solution. The amplitude of the OP stripe solution is suppressed by inter-map coupling and finally becomes unstable against the  $\Delta = 0$  uniform solution. Thus for large inter-map coupling only the uniform solution is stable. A further increase in the inter-map coupling suppresses the amplitude of this uniform solution until finally only the homogeneous solution is stable.

### 2.3.3 Phase diagram

The phase diagram of this coupling energy is shown in Fig. 6. We rescaled the inter-map coupling strength as  $\beta\mathcal{B}^2/r_z$ , where  $\mathcal{B}$  is the stationary amplitude of the OD hexagons. The stability borders are then independent of the OD bias in the OD solutions and further independent of the bifurcation parameter  $r_z$ . This simplifies the analysis since the OP solutions and their stability depend on  $\gamma$  only indirect via the amplitudes  $B$ . In case of OD stripes or OD constant solution there is no pinwheel crystallization. Instead the OP solutions are pinwheel free stripes. In case of OD hexagons hPWCs become stable above



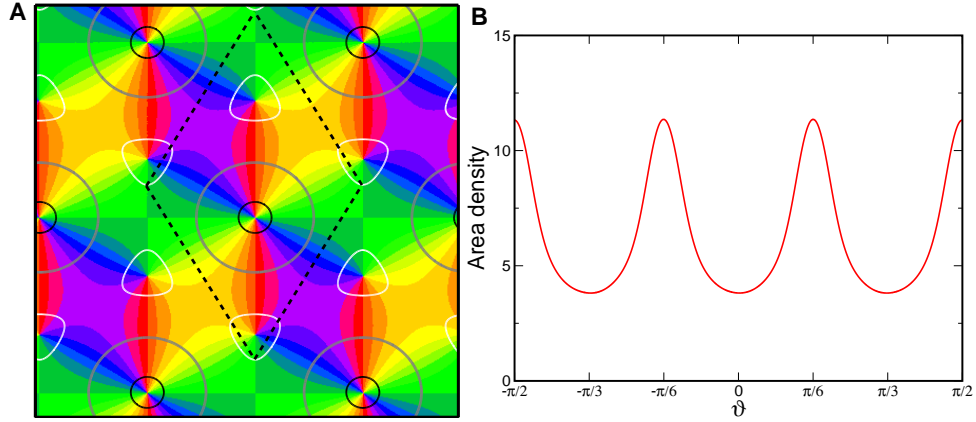
**Figure 6.** Phase diagram with the coupling energy  $\mathbf{U} = \beta|\nabla\mathbf{z}\cdot\nabla\mathbf{o}|^2$ ,  $r_z \ll r_o$ . Vertical black lines: stability range of OD stripes, hexagons, and constant solution. Blue line: stability border for the  $\Delta = 0$  uniform solution. Green line: rhombic solutions become unstable. Orange line: stripe-like solutions become unstable. Red line: pattern solutions cease to exist, see Eq. (61). Gray region: No pattern solution exists.

$\beta \approx 0.05r_z/\mathcal{B}^2$  (blue line). Rhombic OP patterns become unstable at  $\beta\mathcal{B}^4/r_z \approx 0.17$  and decay into a stripe-like solution (green line). At  $\beta\mathcal{B}^4/r_z \approx 0.36$  these stripe-like solutions become unstable (orange line). Thus above  $\beta\mathcal{B}^4/r_z \approx 0.36$  the hPWC is the only stable solution. At  $\beta\mathcal{B}^2/r_z = 2/3$  the pattern solution ceases to exist (red line).

#### 2.3.4 Interaction induced pinwheel crystals

The uniform solution Eq. (134),  $\Delta = 0$  is illustrated in Fig. 7. This PWC contains only three pinwheels per unit cell leading to a pinwheel density of  $\rho = 3 \cos \pi/6 \approx 2.6$ . Two of the three pinwheels are located at maxima of the OD map (contra peak) while the remaining pinwheel is located at the minimum (ipsi peak) of the OD map. A remarkable property of this solution is that the pinwheel located at the OD minimum, carries a topological charge of 1 such that each orientation is represented twice around this pinwheel. Pinwheels of this kind have not yet been observed in experimentally recorded OP maps. This kind of uniform solution corresponds to the structural pinwheel model by Braitenberg [92]. We therefore





**Figure 7. The Braitenberg pinwheel crystal**,  $\Delta = 0$  uniform solution of Eq. (134). **A** OP map, superimposed are the OD borders (gray), 90% ipsilateral eye dominance (black), and 90% contralateral eye dominance (white),  $r_o = 0.2, \gamma = 3\gamma^*$ . Dashed lines mark the unit cell of the regular pattern. **B** Distribution of preferred orientations.

refer to this solution as the *Braitenberg pinwheel crystal*.

The iso-orientation lines are again perfectly perpendicular to OD borders and this is independent of the bias  $\gamma$ . The solution is symmetric under a combined rotation by  $120^\circ$  and an orientation shift by  $-2\pi/3$ . Further it is symmetric under a rotation by  $180^\circ$ . The pattern is selective to all orientations but the distribution of represented orientations is not uniform. The three orientations  $\vartheta + n\frac{\pi}{3}$ ,  $n = 0, \dots, 2$  are overrepresented, see Fig. 7B.

Overall this OP map is dominated by uniform regions around hyperbolic points. In contrast to the ipsi-center PWC all pinwheels in this OP map organize a roughly similar fraction of the cortical surface.

## Discussion

### Summary of results

In this study we presented a symmetry-based analysis of models formalizing that visual cortical architecture is shaped by the coordinated optimization of different functional maps. In particular, we focused on the question of whether and how different optimization principles specifically impact on the spatial layout of functional columns in the primary visual cortex. We identified different representative candidate optimization principles. We developed a dynamical systems approach for analyzing the simultaneous optimization of interacting maps and examined how their layout is influenced by coordinated optimization.

In particular, we found that inter-map coupling can stabilize pinwheel-rich layouts even if pinwheels are intrinsically unstable in the weak coupling limit. We calculated and analyzed the stability properties of solutions forming spatially regular layouts with pinwheels arranged in a crystalline array. We analyzed the structure of these pinwheel crystals in terms of their stability properties, spatial layout, and geometric inter-map relationships. For all models, we calculated phase diagrams showing the stability of the pinwheel crystals depending on the OD bias and the inter-map coupling strength. Although differing in detail and exhibiting distinct pinwheel crystal phases for strong coupling, the phase diagrams exhibited many commonalities in their structure. These include the general fact that the hexagonal PWC phase is preceded by a phase of rhombic PWCs and that the range of OD biases over which pinwheel crystallization occurs is confined to the stability region of OD patch solutions.

### **Comparison to previous work**

Our analytical calculations of attractor and ground states close a fundamental gap in the theory of visual cortical architecture and its development. They rigorously establish that models of interacting OP and OD maps in principle offer a solution to the problem of pinwheel stability [50, 70]. This problem and other aspects of the influence of OD segregation on OP maps have previously been studied in a series of models such as elastic net models [33, 36, 40, 41, 50, 58], self-organizing map models [37, 39, 43, 48, 49], spin-like Hamiltonian models [57, 93], spectral filter models [94], correlation based models [95, 96], and evolving field models [97]. Several of these simulation studies found a higher number of pinwheels per hypercolumn if the OP map is influenced by strong OD segregation compared to the OP layout in isolation or the influence of weak OD segregation [50, 93, 97]. In such models, large gradients of OP and OD avoid each other [39, 48]. As a result, pinwheel centers tend to be located at centers of OD columns as seen in experiments [18, 44, 45, 47, 95]. By this mechanism, pinwheels are spatially trapped and pinwheel annihilation can be reduced [50]. Moreover, many models appear capable of reproducing realistic geometric inter-map relationships such as perpendicular intersection angles between OD borders and iso-orientation lines [58, 94, 95]. Tanaka et al. reported from numerical simulations that the relative positioning of orientation pinwheels and OD columns was dependent on model parameters [95]. Informative as they were, almost all of these previous studies entirely relied on simulation methodologies that do not easily permit to assess the progress and convergence of solutions. Whether the reported patterns were attractors or just snapshots of transient states and whether the solutions would further develop towards pinwheel-free solutions or other states thus remained unclear. Moreover, in almost all previous models, a continuous

variation of the inter-map coupling strength was not possible which makes it hard to disentangle the contribution of inter-map interactions from intrinsic mechanisms. The only prior simulation study of a coordinated optimization model that tracked the number of pinwheels during the optimization process did not provide evidence that pinwheel annihilation could be stopped but only reported a modest reduction in annihilation efficiency [50]. From this perspective, the prior evidence for coordination induced pinwheel stabilization appears relatively limited. Our analytical results leave no room to doubt that map interactions can stabilize an intrinsically unstable pinwheel dynamics. They also reveal that interaction of orientation preference with a stripe pattern of OD is per se not capable of stabilizing pinwheels.

### **The mathematical structure of interaction models**

Independent of its predictions, our study clarifies the general mathematical structure of interaction dominated optimization models. To the best of our knowledge our study for the first time describes an analytical approach for examining the solutions of coordinated optimization models for OP and OD maps. Our symmetry-based phenomenological analysis of conceivable coupling terms provides a general classification and parametrization of biologically plausible coupling terms. To achieve this we mapped the optimization problem to a dynamical systems problem which allows for a perturbation expansion of fixed points, local minima, and optima. Using weakly nonlinear analysis, we derived amplitude equations as an approximate description near the symmetry breaking transition. We identified a limit in which inter-map coupling becomes effectively unidirectional enabling the use of the uncoupled OD patterns. We studied fixed points and calculated their stability properties for different types of inter-map coupling energies. This analysis revealed a fundamental difference between high and low order coupling energies. For the low order versions of these energies, a strong inter-map coupling typically leads to OP map suppression, causing the orientation selectivity of all neurons to vanish. In contrast, the higher order variants of the coupling energies do generally not cause map suppression but only influence pattern selection, see Text S1. We did not consider an interaction with the retinotopic map. Experimental results on geometric relationships between the retinotopic map and the OP map are ambiguous. In case of ferret visual cortex high gradient regions of both maps avoid each other [41]. In case of cat, however, high gradient regions overlap [17]. Such positive correlations cannot be easily treated with dimension reduction models, see [98]. It is noteworthy that our phenomenological analysis identified coupling terms that could induce an attraction of high gradient regions. Such terms contain the gradient of only one field and can thus be considered as a mixture of the gradient and the product-type energy.

### Conditions for pinwheel stabilization

Our results indicate that a patchy layout of a second visual map interacting with the OP map is important for the effectiveness of pinwheel stabilization by inter-map coupling. Such a patchy layout can be easily induced by an asymmetry in the representation of the corresponding stimulus feature such as eye dominance or spatial frequency preference. In spatial frequency maps, for instance, low spatial frequency patches tend to form islands in a sea of high spatial frequency preference [44]. In our model, the patchy layout results from the overall dominance of one eye. In this case, OD domains form a system of hexagonal patches rather than stripes enabling the capture and stabilization of pinwheels by inter-map coupling. The results from all previous models did not support the view that OD stripes are capable of stabilizing pinwheels [50,93,97]. Our analysis shows that OD stripes are indeed not able to stabilize pinwheels, a result that appears to be independent of the specific type of map interaction. In line with this, several other theoretical studies, using numerical simulations [50,93,97], indicated that more banded OD patterns lead to less pinwheel rich OP maps. For instance, in simulations using an elastic net model, the average pinwheel density of OP maps interacting with a patchy OD layout was reported substantially higher (about 2.5 pinwheels per hypercolumn) than for OP maps interacting with a more stripe-like OD layout (about 2 pinwheels per hypercolumn) [50].

### Experimental evidence for pinwheel stabilization by inter-map coupling

Several lines of biological evidence appear to support the picture of interaction induced pinwheel stabilization. Supporting the notion that pinwheels might be stabilized by the interaction with patchy OD columns, visual cortex is indeed dominated by one eye in early postnatal development and has a pronounced patchy layout of OD domains [99–101]. Further support for the potential relevance of this picture comes from experiments in which the OD map was artificially removed resulting apparently in a significantly smoother OP map [43]. In this context it is noteworthy that macaque visual cortex appears to exhibit all three fundamental solutions of our model for OD maps: stripes, hexagons, and a monocular solution, which are stable depending on the OD bias. In the visual cortex of macaque monkeys, all three types of patterns are found near the transition to the monocular segment, see [101] and Fig. (8). Here, OD domains form bands in the binocular region and a system of ipsilateral eye patches at the transition zone to the monocular region where the contralateral eye gradually becomes more dominant. If pinwheel stability depends on a geometric coupling to the system of OD columns one predicts systematic differences in pinwheel density between these three zones of macaque primary visual cortex. Because OD columns

in the binocular region of macaque visual cortex are predominantly arranged in systems of OD stripes our analysis also indicates that pinwheels in these regions are either stabilized by other patchy columnar systems or intrinsically stable.

### **The geometry of interaction induced pinwheel crystals**

One important general observation from our results is that map organization was often not inferable by simple qualitative considerations on the energy functional. The organization of interaction induced hexagonal pinwheel crystals reveals that the relation between coupling energy and resulting map structure is quite complex and often counter intuitive. We analyzed the stationary patterns with respect to intersection angles and pinwheel positions. In all models, intersection angles of iso-orientation lines and OD borders have a tendency towards perpendicular angles whether the energy term mathematically depends on this angle, as for the gradient-type energies, or not, as for the product-type energies. Intersection angle statistics thus are not a very sensitive indicator of the type of interaction optimized. Mathematically, these phenomena result from the complex interplay between the single map energies and the interaction energies. In case of the low order gradient-type inter-map coupling energy all pinwheels are located at OD extrema, as expected from the used coupling energy. For other analyzed coupling energies, however, the remaining pinwheels are located either at OD saddle-points (low order product-type energy) or near OD borders (higher order gradient-type energy), in contrast to the expectation that OD extrema should be energetically preferred. Remarkably, such correlations, which are expected from the gradient-type coupling energies, occur also in the case of the product-type energies. Remarkably, in case of product type energies pinwheels are located at OD saddle-points. which is not expected per se and presumably result from the periodic layout of OP and OD maps. Correlations between pinwheels and OD saddle-points have not yet been studied quantitatively in experiments and may thus provide valuable information on the principles shaping cortical functional architecture.

### **How informative is map structure?**

Our results demonstrate that, although distinct types of coupling energies can leave distinguishing signatures in the structure of maps shaped by interaction (as the OP map in our example), drawing precise conclusions about the coordinated optimization principle from observed map structures is not possible for the analyzed models. In the past numerous studies have attempted to identify signatures of coordinated optimization in the layout of visual cortical maps and to infer the validity of specific optimization models from aspects of their coordinated geometry [33,36,37,39–41,43,48–50,57,58,93]. It was, however,

never clarified theoretically in which respect and to which degree map layout and geometrical factors of inter-map relations are informative with respect to an underlying optimization principle. Because our analysis provides complete information of the detailed relation between map geometry and optimization principle for the different models our results enable to critically assess whether different choices of energy functionals specifically impact on the predicted map structure and conversely what can be learned about the underlying optimization principle from observations of map structures.

We examined the impact of different interaction energies on the structure of local minima and ground states of models for the coordinated optimization of a complex and a real scalar feature map such as OP and OD maps. The models were constructed such that in the absence of interactions, the maps reorganized into simple stripe or blob pattern. In particular, the complex scalar map without interactions would form a periodic stripe pattern without any phase singularity. In all models, increasing the strength of interactions could eventually stabilize qualitatively different more complex and biologically more realistic patterns containing pinwheels that can become the energetic ground states for strong enough inter-map interactions. The way in which this happens provides fundamental insights into the relationships between map structure and energy functionals in optimization models for visual cortical functional architecture. Our results demonstrate that the structure of maps shaped by inter-map interactions is in principle informative about the type of coupling energy. The organization of the complex scalar map that optimizes the joined energy functional was in general different for all different types of coupling terms examined. We identified a class of hPWC solutions which become stable for large inter-map coupling. This class depends on a single parameter which is specific to the used inter-map coupling energy. Furthermore, as shown in Text S1, pinwheel positions in rPWCs, tracked while increasing inter-map coupling strength, were different for different coupling terms examined and thus could in principle serve as a trace of the underlying optimization principle. This demonstrates that, although pinwheel stabilization is not restricted to a particular choice of the interaction term, each analyzed phase diagram is specific to the used coupling energy. In particular, in the strong coupling regime substantial information can be obtained from a detailed inspection of solutions.

In the case of the product-type coupling energies, the resulting phase diagrams are relatively complex as stationary solutions and stability borders depend on the magnitude of the OD bias. Here, even quantitative values of model parameters can in principle be constrained by analysis of the map layout. In contrast, for the gradient-type coupling energies, the bias dependence can be absorbed into the coupling

strength and only selects the stationary OD pattern. This leads to relatively simple phase diagrams. For these models map layout is thus uninformative of quantitative model parameters. We identified several biologically very implausible OP patterns. In the case of the product-type energies, we found orientation scotoma solutions which are selective to only two preferred orientations. In the case of the low order gradient-type energy, we found OP patterns containing pinwheels with a topological charge of 1 which have not yet been observed in experiments. If the relevant terms in the coupling energy could be determined by other means, the parameter regions in which these patterns occur could be used to constrain model parameters by theoretical bounds.

The information provided by map structure overall appears qualitative rather than quantitative. In both low order inter-map coupling energies (and the gradient-type higher order coupling energy, see Text S1), hPWC patterns resulting from strong interactions were fixed, not exhibiting any substantial dependence on the precise choice of interaction coefficient. In principle, the spatial organization of stimulus preferences in a map is an infinite dimensional object that could sensitively depend in distinct ways to a large number of model parameters. It is thus not a trivial property that this structure often gives essentially no information about the value of coupling constants in our models. The situation, however, is reversed when considering the structure of rPWCs. These solutions exist and are stable although energetically not favored in the absence of inter-map interactions. Some of their pinwheel positions continuously depend on the strength of inter-map interactions. These solutions and their parameter dependence nevertheless are also largely uninformative about the nature of the interaction energy. This results from the fact that rPWCs are fundamentally uncoupled system solutions that are only modified by the inter-map interaction. As pointed out before, preferentially orthogonal intersection angles between iso-orientation lines and OD borders appear to be a general feature of coordinated optimization models in the strong coupling regime. Although the detailed form of the intersection angle histogram is solution and thus model specific, our analysis does not corroborate attempts to use this feature to support specific optimization principles, see also [51, 102, 103]. The stabilization of pinwheel crystals for strong inter-map coupling appears to be universal and provides per se no specific information about the underlying optimization principle. In fact, the general structure of the amplitude equations is universal and only the coupling coefficients change when changing the coupling energy. It is thus expected that also for other coupling energies, respecting the proposed set of symmetries, PWC solutions can become stable for large enough inter-map coupling.

## Conclusions

Our analysis conclusively demonstrates that OD segregation can stabilize pinwheels and induce pinwheel-rich optima in models for the coordinated optimization of OP and OD maps when pinwheels are intrinsically unstable in the uncoupled dynamics of the OP map. This allows to systematically assess the possibility that inter-map coupling might be the mechanism of pinwheel stabilization in the visual cortex. The analytical approach developed here is independent of details of specific optimization principles and thus allowed to systematically analyze how different optimization principles impact on map layout. Moreover, our analysis clarifies to which extent the observation of the layout in physiological maps can provide information about optimization principles shaping visual cortical organization.

The common design observed in experimental OP maps [1] is, however, not reproduced by the optima of the analyzed optimization principles. Whether this is a consequence of the applied weakly nonlinear analysis or of the low number of optimized feature maps or should be considered a generic feature of coordinated optimization models will be examined in part (II) of this study [90]. In part (II) we complement our analytical studies by numerical simulations of the full field dynamics. Such simulations allow to study the rearrangement of maps during the optimization process, to study the timescales on which optimization is expected to take place, and to lift many of the mathematical assumptions employed by the above analysis. In particular, we concentrate on the higher order inter-map coupling energies for which the derived amplitude equations involved several simplifying conditions, see Text S1.

## Methods

### Intersection angles

We studied the intersection angles between iso-orientation lines and OD borders. The intersection angle of an OD border with an iso-orientation contour  $\alpha(\mathbf{x})$  is given by

$$\alpha(\mathbf{x}) = \cos^{-1} \left( \frac{\nabla o(\mathbf{x}) \cdot \nabla \vartheta(\mathbf{x})}{|\nabla o(\mathbf{x})| |\nabla \vartheta(\mathbf{x})|} \right), \quad (63)$$

where  $\mathbf{x}$  denotes the position of the OD zero-contour lines. A continuous expression for the OP gradient is given by  $\nabla \vartheta = \text{Im} \nabla z / z$ . We calculated the frequency of intersection angles in the range  $[0, \pi/2]$ . In this way those parts of the maps are emphasized from which the most significant information about the intersection angles can be obtained [18]. These are the regions where the OP gradient is high and thus



every intersection angle receives a statistical weight according to  $|\nabla\vartheta|$ . For an alternative method see [10].

## The transition from OD stripes to OD blobs

We studied how the emerging OD map depends on the overall eye dominance. To this end we mapped the uncoupled OD dynamics to a Swift-Hohenberg equation containing a quadratic interaction term instead of a constant bias. This allowed for the use of weakly nonlinear analysis to derive amplitude equations as an approximate description of the shifted OD dynamics near the bifurcation point. We identified the stationary solutions and studied their stability properties. Finally, we derived expressions for the fraction of contralateral eye dominance for the stable solutions.

### Mapping to a dynamics with a quadratic term

Here we describe how to map the Swift-Hohenberg equation

$$\partial_t o(\mathbf{x}, t) = \hat{L} o(\mathbf{x}, t) - o(\mathbf{x}, t)^3 + \gamma, \quad (64)$$

to one with a quadratic interaction term. To eliminate the constant term we shift the field by a constant amount  $o(\mathbf{x}, t) = \tilde{o}(\mathbf{x}, t) + \delta$ . This changes the linear and nonlinear terms as

$$\begin{aligned} \hat{L} o &\rightarrow \hat{L} \tilde{o} - (k_c^4 - r_o) \delta \\ o^3 &\rightarrow -\tilde{o}^3 + 3\delta\tilde{o}^2 + 3\delta^2\tilde{o} + \delta^3. \end{aligned} \quad (65)$$

We define the new parameters  $\tilde{r}_o = r_o - 3\delta^2$  and  $\tilde{\gamma} = -3\delta$ . This leads to the new dynamics

$$\partial_t \tilde{o} = \tilde{r}_o \tilde{o} - (k_c^2 + \Delta)^2 \tilde{o} + \tilde{\gamma} \tilde{o}^2 - \tilde{o}^3 - \delta^3 - (k_{c,o}^4 - r_o) \delta + \gamma. \quad (66)$$

The condition that the constant part is zero is thus given by

$$-\delta^3 - (k_c^4 - r_o) \delta + \gamma = 0. \quad (67)$$

For  $r_o < 1$  the real solution to Eq. (67) is given by

$$\delta = \frac{2^{1/3} (k_c - r_o)}{\beta} - \frac{\beta}{3 \cdot 2^{1/3}}, \quad (68)$$

with  $\beta = \left( -27\gamma + \sqrt{108 (r_o - k_c)^3 + 729\gamma^2} \right)^{1/3}$ . For small  $\gamma$  this formula is approximated as

$$\delta \approx \gamma \frac{1}{k_c^4 - r_o} - \gamma^3 \frac{1}{(k_c^4 - r_o)^4} + 3\gamma^5 \frac{1}{(k_c^4 - r_o)^7} + \dots \quad (69)$$

The uncoupled OD dynamics we consider in the following is therefore given by

$$\partial_t \tilde{o} = \tilde{r}_o \tilde{o} - (k_c^2 + \Delta)^2 \tilde{o} + \tilde{\gamma} \tilde{o}^2 - \tilde{o}^3. \quad (70)$$

This equation has been extensively studied in pattern formation literature [76].

### Amplitude equations for OD patterns

We studied Eq. (70) using weakly nonlinear analysis. This method leads to amplitude equation as an approximate description of the full field dynamics Eq. (70) near the bifurcation point  $\tilde{r}_o = 0$ . We summarize the derivation of the amplitude equations for the OD dynamics which is of the form

$$\partial_t o(\mathbf{x}, t) = \hat{L} o(\mathbf{x}, t) + N_2[o, o] - N_3[o, o, o], \quad (71)$$

with the linear operator  $\hat{L} = r_o - (k_{c,o}^2 + \Delta)^2$ . In this section we use for simplicity the variables  $(o, r_o, \gamma)$  instead of  $(\tilde{o}, \tilde{r}_o, \tilde{\gamma})$ . The derivation is performed for general quadratic and cubic nonlinearities but are specified later according to Eq. (9) as  $N_3[o, o, o] = o^3$  and  $N_2[o, o] = \gamma o^2$ . For the calculations in the following, it is useful to separate  $r_o$  from the linear operator

$$\hat{L} = r_o + \hat{L}^0, \quad (72)$$

therefore the largest eigenvalue of  $\hat{L}^0$  is zero. The amplitude of the field  $o(\mathbf{x}, t)$  is assumed to be small near the onset  $r_o = 0$  and thus the nonlinearities are small. We therefore expand both the field  $o(\mathbf{x}, t)$

and the control parameter  $r_o$  in powers of a small expansion parameter  $\mu$  as

$$o(\mathbf{x}, t) = \mu o_1(\mathbf{x}, t) + \mu^2 o_2(\mathbf{x}, t) + \mu^3 o_3(\mathbf{x}, t) + \dots, \quad (73)$$

and

$$r_o = \mu r_1 + \mu^2 r_2 + \mu^3 r_3 + \dots \quad (74)$$

The dynamics at the critical point  $r_o = 0$  becomes arbitrarily slow since the intrinsic timescale  $\tau = r_o^{-1}$  diverges at the critical point. To compensate we introduce a rescaled time scale  $T$  as

$$T = r_o t, \quad \partial_t = r_o \partial_T. \quad (75)$$

In order for all terms in Eq. (71) to be of the same order the quadratic interaction term  $N_2$  must be small. We therefore rescale  $N_2$  as  $\sqrt{r_o} N_2$ . This preserves the nature of the bifurcation compared to the case  $N_2 = 0$ .

We insert the expansion Eq. (73) and Eq. (74) in the dynamics Eq. (71) and get

$$\begin{aligned} 0 &= \mu \hat{L}^0 o_1 \\ &+ \mu^2 \left( -\hat{L}^0 o_2 - r_1 \partial_T o_1 + r_1 o_1 + \sqrt{\mu r_1 + \mu^2 r_2 + \dots} N_2[o_1, o_1] \right) \\ &+ \mu^3 \left( -\hat{L}^0 o_3 + r_1 (o_2 - \partial_T o_2) + r_2 (o_1 - \partial_T o_1) - N_3[o_1, o_1, o_1] \right) \\ &\vdots \end{aligned} \quad (76)$$

We sort and collect all terms in order of their power in  $\mu$ . The equation can be fulfilled for  $\mu > 0$  only if each of these terms is zero. We therefore solve the equation order by order. In the leading order we get the homogeneous equation

$$\hat{L}^0 o_1 = 0. \quad (77)$$

Thus  $o_1$  is an element of the kernel of  $\hat{L}^0$ . The kernel contains linear combinations of modes with wavevector  $\vec{k}_j$  on the critical circle  $|\vec{k}_j| = k_{c,o}$ . At this level any of such wavevectors is possible. We choose

$$o_1 = \sum_j^n B_j(T) e^{i\vec{k}_j \cdot \vec{x}} + \sum_j^n \bar{B}_j(T) e^{-i\vec{k}_j \cdot \vec{x}}, \quad (78)$$

where the wavevectors are chosen to be equally spaced  $\vec{k}_j = k_{c,o} (\cos(j\pi/n), \sin(j\pi/n))$  and the complex amplitudes  $B_j = \mathcal{B}_j e^{i\psi_j}$ . The homogeneous equation leaves the amplitudes  $B_j$  undetermined. These amplitudes are fixed by the higher order equations. Besides the leading order homogeneous equation we get inhomogeneous equations of the form

$$\hat{L}^0 o_m = F_m \quad (79)$$

To solve this inhomogeneous equation we first apply a solvability condition. We thus apply the *Fredholm Alternative theorem* to Eq. (79). Since the operator  $\hat{L}^0$  is self-adjoint  $\hat{L}^0 = \hat{L}^{0\dagger}$ , the equation is solvable if and only if  $F_m$  is orthogonal to the kernel of  $\hat{L}^0$  i.e.

$$\langle F_m, \tilde{o} \rangle = 0, \quad \forall \hat{L}^0 \tilde{o} = 0 \quad (80)$$

The orthogonality to the kernel can be expressed by a projection operator  $\hat{P}_c$  onto the kernel and the condition  $\langle F, \tilde{o} \rangle = 0$  can be rewritten as  $\hat{P}_c F = 0$ .

At second order we get

$$\hat{L}^0 o_2 = r_1 (o_1 - \partial_T o_1) . \quad (81)$$

Applying the solvability condition Eq. (80) we see that this equation can be fulfilled only for  $r_1 = 0$ . At third order we get

$$\hat{L}^0 o_3 = r_2 (o_1 - \partial_T o_1) + N_2[o_1, o_1] - N_3[o_1, o_1, o_1] . \quad (82)$$

The parameter  $r_2$  sets the scale in which  $o_1$  is measured and we can set  $r_2 = 1$ . We apply the solvability condition and get

$$\partial_T o_1 = o_1 + \hat{P}_c N_2[o_1, o_1] - \hat{P}_c N_3[o_1, o_1, o_1] . \quad (83)$$

We insert our ansatz Eq. (78) which leads to the amplitude equations at third order

$$\partial_T B_i = B_i + \hat{P}_i \sum_{j,k} B_j B_k e^{-i\vec{k}_i \vec{x}} N_2[e^{i\vec{k}_j \vec{x}}, e^{i\vec{k}_k \vec{x}}] - \hat{P}_i \sum_{j,k} B_j B_k B_l e^{-i\vec{k}_i \vec{x}} N_3[e^{i\vec{k}_j \vec{x}}, e^{i\vec{k}_k \vec{x}}, e^{i\vec{k}_l \vec{x}}] , \quad (84)$$

where  $\hat{P}_i$  is the projection operator onto the subspace  $\{e^{i\vec{k}_i \vec{x}}\}$  of the kernel.  $\hat{P}_i$  picks out all combinations of the modes which have their wavevector equal to  $\vec{k}_i$ . In our case the three active modes form a so called triad resonance  $\vec{k}_1 + \vec{k}_2 + \vec{k}_3 = 0$ . The quadratic coupling terms which are resonant to the mode  $B_1$  are

therefore given by

$$\overline{B}_2 \overline{B}_3 e^{-i\vec{k}_1 \vec{x}} \left( N_2 [e^{-i\vec{k}_2 \vec{x}}, e^{-i\vec{k}_3 \vec{x}}] + N_2 [e^{-i\vec{k}_3 \vec{x}}, e^{-i\vec{k}_2 \vec{x}}] \right). \quad (85)$$

Resonant contributions from the cubic nonlinearity result from terms of the form  $|B_j|^2 B_i$ . Their coupling coefficients are given by

$$\begin{aligned} \tilde{g}_{ij} = & N_3 [e^{i\vec{k}_i \vec{x}}, e^{i\vec{k}_j \vec{x}}, e^{-i\vec{k}_j \vec{x}}] + N_3 [e^{i\vec{k}_i \vec{x}}, e^{-i\vec{k}_j \vec{x}}, e^{i\vec{k}_j \vec{x}}] + N_3 [e^{i\vec{k}_j \vec{x}}, e^{i\vec{k}_i \vec{x}}, e^{-i\vec{k}_j \vec{x}}] + \\ & N_3 [e^{-i\vec{k}_j \vec{x}}, e^{i\vec{k}_i \vec{x}}, e^{i\vec{k}_j \vec{x}}] + N_3 [e^{i\vec{k}_j \vec{x}}, e^{-i\vec{k}_j \vec{x}}, e^{i\vec{k}_i \vec{x}}] + N_3 [e^{-i\vec{k}_j \vec{x}}, e^{i\vec{k}_j \vec{x}}, e^{i\vec{k}_i \vec{x}}], \end{aligned} \quad (86)$$

and

$$\tilde{g}_{ii} = N_3 [e^{i\vec{k}_i \vec{x}}, e^{i\vec{k}_i \vec{x}}, e^{-i\vec{k}_i \vec{x}}] + N_3 [e^{i\vec{k}_i \vec{x}}, e^{-i\vec{k}_i \vec{x}}, e^{i\vec{k}_i \vec{x}}] + N_3 [e^{-i\vec{k}_i \vec{x}}, e^{i\vec{k}_i \vec{x}}, e^{i\vec{k}_i \vec{x}}]. \quad (87)$$

When specifying the nonlinearities Eq. (9) the coupling coefficients are given by  $\tilde{g}_{ij} = 6, \tilde{g}_{ii} = 3$ . Finally, the amplitude equations (here in the shifted variables  $(\tilde{r}_o, \tilde{\gamma})$ ) are given by

$$\partial_t B_1 = \tilde{r}_o B_1 - 3|B_1|^2 B_1 - 6(|B_2|^2 + |B_3|^2) B_1 + 2\tilde{\gamma} \overline{B}_2 \overline{B}_3, \quad (88)$$

where we scaled back to the original time variable  $t$ . Equations for  $B_2$  and  $B_3$  are given by cyclic permutation of the indices.

### Stationary solutions

The amplitude equations (88) have three types of stationary solutions, namely OD stripes

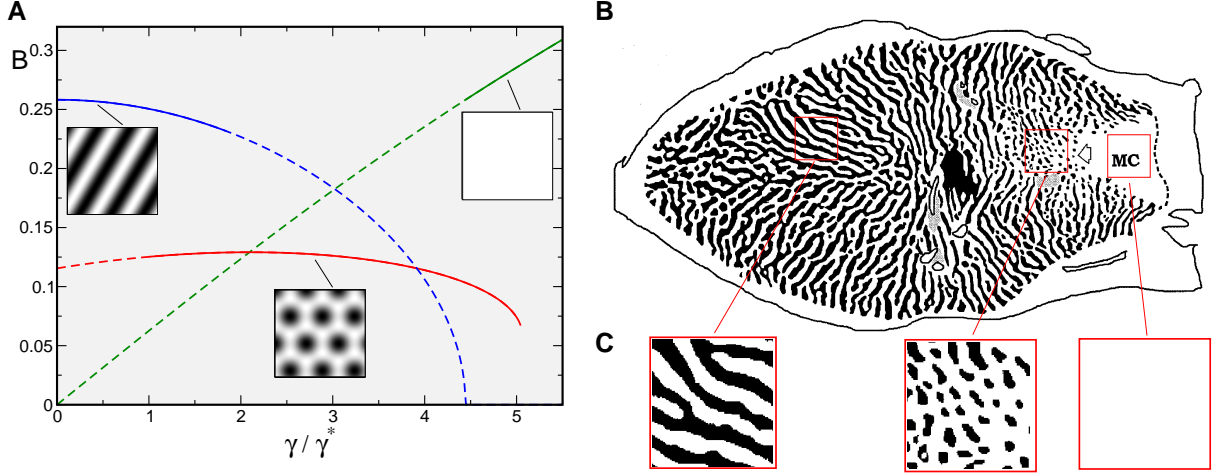
$$o_{st}(\mathbf{x}) = 2\mathcal{B}_{st} \cos(x + \psi) + \delta, \quad (89)$$

with  $\mathcal{B}_{st} = \sqrt{\tilde{r}/3}$ , hexagons

$$o_{hex}(\mathbf{x}) = \mathcal{B}_{hex} \sum_{j=1}^3 e^{i\psi_j} e^{i\vec{k}_j \cdot \vec{x}} + c.c. + \delta, \quad (90)$$

with the resonance condition  $\sum_j^3 \vec{k}_j = 0$  and  $\mathcal{B}_{hex} = -\tilde{\gamma}/15 + \sqrt{(\tilde{\gamma}/15)^2 + \tilde{r}/15}$ . Finally, there is a homogeneous solution with spatially constant eye dominance

$$o_c(\mathbf{x}) = \delta. \quad (91)$$



**Figure 8. OD patterns.** **A** Stationary amplitudes of the OD dynamics. The course of  $\mathcal{B}_{st}(\gamma)$  Eq. (89) (blue),  $\mathcal{B}_{hex}(\gamma)$  Eq. (90) (red), and of  $\delta(\gamma)$  Eq. (68) (green) for  $r_o = 0.2$ . The solutions are plotted in solid lines within their stability ranges. **B** OD map of macaque monkey. Adapted from [101]. **C** Details of **B** with stripe-like, patchy, and homogeneous layout.

The spatial average of all solutions is  $\langle o(\mathbf{x}) \rangle = \delta$ . The course of  $\mathcal{B}_{st}$ ,  $\mathcal{B}_{hex}$ , and of  $\delta(\gamma)$  is shown in Fig. 8.

### Linear stability analysis for OD patterns

We decomposed the amplitude equations (88) into the real and imaginary parts. From the imaginary part we get the phase equation

$$\partial_t \psi_1 = -2\tilde{\gamma} \sin(\psi_1 + \psi_2 + \psi_3), \quad (92)$$

and equations for  $\psi_2, \psi_3$  by cyclic permutation of the indices. The stationary phases are given by  $\psi_1 + \psi_2 + \psi_3 = \{0, \pi\}$ . The phase equation can be derived from the potential  $V[\psi] = -2\tilde{\gamma} \cos(\psi_1 + \psi_2 + \psi_3)$ . We see that the solution  $\psi_1 + \psi_2 + \psi_3 = 0$  is stable for  $\tilde{\gamma} > 0$  ( $\gamma < 0$ ) and the solution  $\psi_1 + \psi_2 + \psi_3 = \pi$  is stable for  $\tilde{\gamma} < 0$  ( $\gamma > 0$ ).

We calculate the stability borders of the OD stripe, hexagon, and constant solution in the uncoupled case. This treatment follows [76]. In case of stripes the three modes of the amplitude equations are perturbed as

$$B_1 \rightarrow B_{st} + b_1, \quad B_2 \rightarrow b_2, \quad B_3 \rightarrow b_3, \quad (93)$$

assuming small perturbations  $b_1, b_2$ , and  $b_3$ . This leads to the linear equations  $\partial_t \vec{b} = M \vec{b}$  with the stability matrix

$$M = \begin{pmatrix} \tilde{r} - 9B_{st}^2 & 0 & 0 \\ 0 & \tilde{r} - 6B_{st}^2 & 2\tilde{\gamma}B_{st} \\ 0 & 2\tilde{\gamma}B_{st} & \tilde{r} - 6B_{st}^2 \end{pmatrix}. \quad (94)$$

The corresponding eigenvalues are given by

$$\lambda = \left( -2\tilde{r}, -\tilde{r} - 2\sqrt{\tilde{r}/3}\tilde{\gamma}, -\tilde{r} + 2\sqrt{\tilde{r}/3}\tilde{\gamma} \right). \quad (95)$$

This leads to the two borders for the stripe stability

$$\tilde{r} = 0, \quad \tilde{r} = \frac{4}{3}\tilde{\gamma}^2. \quad (96)$$

In terms of the original variables  $r_o, \gamma$  the borders are given by ( $0 < r_o < 1$ )

$$\gamma_3^* = \frac{(3 - 2r_o)\sqrt{r_o}}{3^{3/2}}, \quad \gamma_2^* = \frac{(15 - 14r_o)\sqrt{r_o}}{15^{3/2}}. \quad (97)$$

To derive the stability borders for the hexagon solution  $o_{hex}(\mathbf{x})$  we perturb the amplitudes as

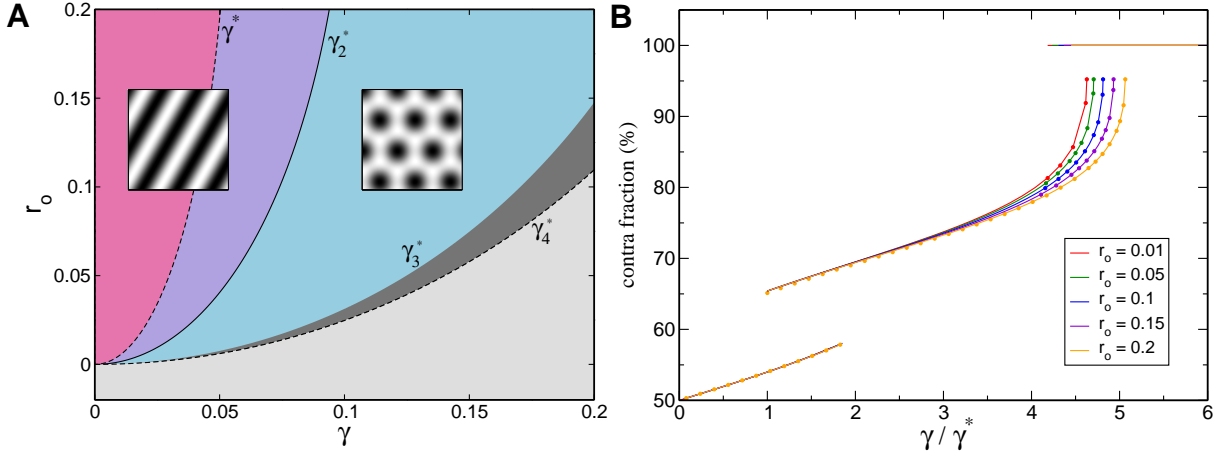
$$B_1 \rightarrow B_{hex} + b_1, \quad B_2 \rightarrow B_{hex} + b_2, \quad B_3 \rightarrow B_{hex} + b_3. \quad (98)$$

The stability matrix is then given by

$$M = \begin{pmatrix} -21B_{hex} + \tilde{r} & -12B_{hex}^2 - 2B_{hex}\tilde{\gamma} & -12B_{hex}^2 - 2B_{hex}\tilde{\gamma} \\ -12B_{hex}^2 - 2B_{hex}\tilde{\gamma} & -21B_{hex} + \tilde{r} & -12B_{hex}^2 - 2B_{hex}\tilde{\gamma} \\ -12B_{hex}^2 - 2B_{hex}\tilde{\gamma} & -12B_{hex}^2 - 2B_{hex}\tilde{\gamma} & -21B_{hex} + \tilde{r} \end{pmatrix}, \quad (99)$$

and the corresponding eigenvalues are given by

$$\lambda = \left( -45B_h^2 + \tilde{r} - 4B_h\tilde{\gamma}, -9B_h^2 + \tilde{r} + 2B_h\tilde{\gamma}, -9B_h^2 + \tilde{r} + 2B_h\tilde{\gamma} \right). \quad (100)$$



**Figure 9. The uncoupled OD dynamics.** **A** Phase diagram of the OD model Eq. (64). Dashed lines: stability border of hexagon solutions, solid line: stability border of stripe solution, gray regions: stability region of constant solution **B** Percentage of neurons dominated by the contralateral eye plotted for the three stationary solutions. Circles: numerically obtained values, solid lines:  $C_{st}$  and  $C_{hex}$ .

The stability borders for the hexagon solution are given by

$$\tilde{r} = -\frac{1}{15}\tilde{\gamma}^2, \quad \tilde{r} = \frac{16}{3}\tilde{\gamma}^2. \quad (101)$$

In terms of the original variables we finally get

$$\gamma_4^* = \frac{(12 - 7r_o)\sqrt{r_o}\sqrt{5}}{24\sqrt{3}}, \quad \gamma^* = \frac{(51 - 50r_o)\sqrt{r_o}}{51^{3/2}}. \quad (102)$$

The phase diagram of this model is depicted in Fig. 9A. It shows the stability borders  $\gamma^*$ ,  $\gamma_2^*$ ,  $\gamma_3^*$ , and  $\gamma_4^*$  for the three solutions obtained by linear stability analysis. Without a bias term the OD map is either constant, for  $r_o < 0$ , or has a stripe layout, for  $r_o > 0$ . For positive  $r_o$  and increasing bias term there are two transition regions, first a transition region from stripes to hexagons and second a transition region from hexagons to the constant solution.

The spatial layout of the OD hexagons consists of hexagonal arrays of ipsilateral eye dominance blobs in a sea of contralateral eye dominance, see Fig. 9A.



### Contralateral eye fraction

To compare the obtained solutions with physiological OD maps we quantified the fraction of neurons selective to the contralateral eye inputs. For stripe and hexagon solutions we thus calculated the fraction of contralateral eye dominated territory  $C_{st}$  and  $C_{hex}$ . In case of stripes this is a purely one-dimensional problem. The zeros of the field are given by

$$o_{st}(x) = 2\mathcal{B}_{st} \cos(x + \psi) + \delta = 0, \quad (103)$$

with the solution

$$x = \arccos\left(\frac{-\delta}{2\mathcal{B}_{st}}\right). \quad (104)$$

As the field has a periodicity of  $\pi$  the area fraction is given by

$$C_{st} = \arccos\left(\frac{-\delta}{2\mathcal{B}_{st}}\right) / \pi. \quad (105)$$

In case of hexagons we observe that the territory of negative  $o(\mathbf{x})$  values is approximately a circular area. We obtain the fraction of negative  $o(\mathbf{x})$  values by relating this area to the area of the whole hexagonal lattice. In case of hexagons the field is given by

$$o_{hex}(\mathbf{x}) = 2\mathcal{B}_{hex} \sum_j \cos(\vec{k}_j \vec{x} + \psi_j) + \delta. \quad (106)$$

As an approximation we project the field onto the  $x$ -axis and choose for simplicity  $\psi_j = 0, \forall j$ . The field has its maximum at the origin  $o_{hex}(0, 0) = 6 + \delta$ . The projection leads to

$$f(x) = 2\mathcal{B}_{hex} (\cos x + 2 \cos(1/2)x) + \delta. \quad (107)$$

The zeros  $f(x_1) = 0$  are located at

$$x_1 = 2 \arccos\left(\frac{1}{2} \left(-1 + \sqrt{3 + \frac{\delta}{\mathcal{B}_{hex}}}\right)\right). \quad (108)$$

The circular area of positive  $o_{hex}(\mathbf{x})$  values is now given by  $A_c = \pi x_1^2$ . The periodicity of the hexagonal pattern is given by  $f(x_2)_{\delta=0} = \min(f)_{\delta=0} = -3$ . This leads to  $x_2 = 4\pi/3$ . The area of the hexagon is

therefore given by  $A_{hex} = 3x_2^2\sqrt{3}/2$ . The contra fraction is finally given by

$$1 - C_{hex} \approx \frac{A_c}{A_{hex}} = \frac{\sqrt{3}}{2\pi} \arccos \left( \frac{1}{2} \left( -1 + \sqrt{3 + \frac{\delta}{\mathcal{B}_{hex}}} \right) \right)^2. \quad (109)$$

The course of the fractions  $C_{st}$  and  $C_{hex}$  is shown in Fig. 9B. At the border  $\gamma = \gamma^*$ , where hexagons become stable  $C_{hex} \approx 65.4\%$ . At the border  $\gamma = \gamma_4^*$ , where hexagons loose stability  $C_{hex} \approx 95.2\%$ . Both quantities are independent of  $r_o$ . We confirmed our results by direct numerical calculation of the fraction of positive  $o_{hex}(\mathbf{x})$  pixel values. Deviations from the result Eq. (109) are small. For  $\gamma/\gamma^* \approx 1$  the zeros of Eq. (107) are not that well approximated with a circular shape and the projection described above leads to the small deviations which decrease with increasing bias  $\gamma$ .

## Text S1: Supporting Information for

### Coordinated optimization of visual cortical maps

#### (I) Symmetry-based analysis

### 3 Introduction

In case of the low order inter-map coupling energies strong inter-map coupling leads to a suppression of OP selectivity. This suppressive effect can be avoided by restricting coupling strengths. One aim of this article is to test different optimization principles and potentially rule out some optimization principles. When comparing our results from different optimization principles to biological data such parameter tuning reduces the practicability. In this supporting information we complement our study using the high order inter-map coupling energies. We show that in this case a suppression of OP selectivity cannot occur. We derive coupled amplitude equations which, however, involve several mathematical assumptions. A systematic treatment as it is shown in the main article would imply that low order and higher order inter-map coupling energies are in general non-zero. Low order energy terms would enter at third order in the expansion and higher order corrections could potentially alter the stability properties. In addition, higher order inter-map coupling energies can affect the stability of patterns. In the following, we assume all low order inter-map coupling energies to be zero and that contributions entering the amplitude equations at higher orders can be neglected. The obtained results are confirmed numerically in part (II) of this study.

### 4 Coupled amplitude equations: Higher order terms

We studied the coupled Swift-Hohenberg equations

$$\begin{aligned}\partial_t z(\mathbf{x}, t) &= r_z z(\mathbf{x}, t) - \hat{L}_z^0 z(\mathbf{x}, t) - N_{3,u}[z, z, \bar{z}] - N_{7,c}[z, z, \bar{z}, o, o, o, o] \\ \partial_t o(\mathbf{x}, t) &= r_o o(\mathbf{x}, t) - \hat{L}_o^0 o(\mathbf{x}, t) + N_{2,u}[o, o] - N_{3,u}[o, o, o] - \tilde{N}_{7,c}[o, o, o, z, z, \bar{z}, \bar{z}],\end{aligned}\quad (110)$$

with the higher order inter-map coupling energies

$$U = \tau o^4 |z|^4 + \epsilon |\nabla z \cdot \nabla o|^4, \quad (111)$$

using weakly nonlinear analysis. We study Eq. (110) close to the pattern forming bifurcation where  $r_z$  and  $r_o$  are small. We therefore expand both control parameters in powers of the small expansion parameter  $\mu$

$$\begin{aligned} r_z &= \mu r_{z1} + \mu^2 r_{z2} + \mu^3 r_{z3} + \dots \\ r_o &= \mu r_{o1} + \mu^2 r_{o2} + \mu^3 r_{o3} + \dots \end{aligned} \quad (112)$$

Close to the bifurcation the fields are small and thus nonlinearities are weak. We therefore expand both fields as

$$\begin{aligned} o(\mathbf{x}, t) &= \mu o_1(\mathbf{x}, t) + \mu^2 o_2(\mathbf{x}, t) + \mu^3 o_3(\mathbf{x}, t) + \dots \\ z(\mathbf{x}, t) &= \mu z_1(\mathbf{x}, t) + \mu^2 z_2(\mathbf{x}, t) + \mu^3 z_3(\mathbf{x}, t) + \dots \end{aligned} \quad (113)$$

We further introduced a common slow timescale  $T = r_z t$  and insert the expansions in Eq. (110) and get

$$\begin{aligned} 0 &= \mu \hat{L}^0 z_1 \\ &+ \mu^2 \left( -\hat{L}^0 z_2 + r_{z1} z_1 - r_{z1} \partial_T z_1 \right) \\ &+ \mu^3 \left( -r_{z2} \partial_T z_1 + r_{z2} z_1 + r_{z1} z_2 - r_{z1} \partial_T z_2 - \hat{L}^0 z_3 - N_{3,u}[z_1, z_1, \bar{z}_1] \right) \\ &\vdots \\ &+ \mu^7 \left( -\hat{L}^0 z_7 + r_{z2} z_5 + r_{z4} z_3 + r_{z6} z_1 + \dots + N_{3,u}[z_5, z_1, \bar{z}_1] \right) \\ &+ \mu^7 \left( -N_{7,c}[z_1, z_1, \bar{z}_1, o_1, o_1, o_1, o_1] \right) \\ &\vdots \end{aligned} \quad (114)$$

and

$$\begin{aligned}
0 &= \mu \hat{L}^0 o_1 \\
&+ \mu^2 \left( -\hat{L}^0 o_2 + r_{o1} o_1 - r_{z1} \partial_T o_1 + \sqrt{\mu r_{o1} + \mu^2 r_{o2} + \dots} \tilde{N}_{2,u}[o_1, o_1] \right) \\
&+ \mu^3 \left( -r_{z2} \partial_T o_1 + r_{o2} o_1 + r_{o1} o_2 - r_{z1} \partial_T o_2 - \hat{L}^0 o_3 - \tilde{N}_{3,u}[o_1, o_1, o_1] \right) \\
&\vdots \\
&+ \mu^7 \left( -\hat{L}^0 o_7 + r_{o2} o_5 + r_{o4} o_3 + r_{o6} o_1 + \dots - \tilde{N}_{3,u}[o_5, o_1, o_1] - \tilde{N}_{2,u}[o_1, o_5] - \dots \right) \\
&+ \mu^7 \left( -\tilde{N}_{7,c}[o_1, o_1, o_1, z_1, z_1, \bar{z}_1, \bar{z}_1] \right) \\
&\vdots
\end{aligned} \tag{115}$$

We consider amplitude equations up to seventh order as this is the order where the nonlinearity of the higher order coupling energy enters first. For Eq. (114) and Eq. (115) to be fulfilled each individual order in  $\mu$  has to be zero. At linear order in  $\mu$  we get the two homogeneous equations

$$\hat{L}_z^0 z_1 = 0, \quad \hat{L}_o^0 o_1 = 0. \tag{116}$$

Thus  $z_1$  and  $o_1$  are elements of the kernel of  $\hat{L}_z^0$  and  $\hat{L}_o^0$ . Both kernels contain linear combinations of modes with a wavevector on the critical circle i.e.

$$\begin{aligned}
z_1(\mathbf{x}, T) &= \sum_j^n \left( A_j^{(1)}(T) e^{i\vec{k}_j \cdot \vec{x}} + A_j^{(1)}(T) e^{-i\vec{k}_j \cdot \vec{x}} \right) \\
o_1(\mathbf{x}, T) &= \sum_j^n \left( B_j^{(1)}(T) e^{i\vec{k}'_j \cdot \vec{x}} + \overline{B}_j^{(1)}(T) e^{-i\vec{k}'_j \cdot \vec{x}} \right),
\end{aligned} \tag{117}$$

with the complex amplitudes  $A_j^{(1)} = \mathcal{A}_j e^{i\phi_j}$ ,  $B_j^{(1)} = \mathcal{B}_j e^{i\psi_j}$  and  $\vec{k}_j = k_{c,z} (\cos(j\pi/n), \sin(j\pi/n))$ ,  $\vec{k}'_j = k_{c,o} (\cos(j\pi/n), \sin(j\pi/n))$ . In view of the hexagonal or stripe layout of the OD pattern shown in Fig. 1,  $n = 3$  is an appropriate choice. Since in cat visual cortex the typical wavelength for OD and OP maps are approximately the same [56, 91] i.e.  $k_{c,o} = k_{c,z} = k_c$  the Fourier components of the emerging pattern are located on a common critical circle. To account for species differences we also analyzed models with detuned OP and OD wavelengths in part (II) of this study.

At second order in  $\mu$  we get

$$\begin{aligned}\hat{L}^0 z_2 + r_{z1} z_1 - r_{z1} \partial_T z_1 &= 0 \\ \hat{L}^0 o_2 + r_{o1} o_1 - r_{z1} \partial_T o_1 &= 0.\end{aligned}\tag{118}$$

As  $z_1$  and  $o_1$  are elements of the kernel  $r_{z1} = r_{o1} = 0$ . At third order, when applying the solvability condition (see Methods), we get

$$\begin{aligned}r_{z2} \partial_T z_1 &= r_{z2} z_1 - \hat{P}_c N_{3,u}[z_1, z_1, \bar{z}_1] \\ r_{z2} \partial_T o_1 &= r_{o2} o_1 - \sqrt{r_{o2}} \hat{P}_c \tilde{N}_{2,u}[o_1, o_1] - \hat{P}_c \tilde{N}_{3,u}[o_1, o_1, o_1].\end{aligned}\tag{119}$$

We insert the leading order fields Eq. (117) and obtain the amplitude equations

$$\begin{aligned}r_{z2} \partial_T A_i^{(1)} &= r_{z2} A_i^{(1)} - \sum_j g_{ij} |A_j^{(1)}|^2 A_i^{(1)} - \sum_j f_{ij} A_j^{(1)} A_{j-}^{(1)} \bar{A}_{i-}^{(1)} \\ r_{z2} \partial_T B_i^{(1)} &= r_{o2} B_i^{(1)} - 2\sqrt{r_{o2}} \bar{B}_{i+1}^{(1)} \bar{B}_{i+2}^{(1)} - \sum_j \tilde{g}_{ij} |B_j^{(1)}|^2 B_i^{(1)}.\end{aligned}\tag{120}$$

These uncoupled amplitude equations obtain corrections at higher order. There are fifth order, seventh order and even higher order corrections to the uncoupled amplitude equations. In addition, at seventh order enters the nonlinearity of the higher order inter-map coupling energies. The amplitude equations up to seventh order are thus derived from

$$\begin{aligned}r_{z2} \partial_T z_1 &= r_{z2} z_1 - \hat{P}_c N_{3,u}[z_1, z_1, \bar{z}_1] \\ r_{z2} \partial_T z_3 &= r_{z2} z_3 - \cdots - \hat{P}_c N_{3,u}[z_1, z_1, \bar{z}_3] \\ r_{z2} \partial_T z_5 &= r_{z2} z_5 - \cdots - \hat{P}_c N_{3,u}[z_3, z_1, \bar{z}_3] - \hat{P}_c N_{7,c}[z_1, z_1, \bar{z}_1, o_1, o_1, o_1, o_1],\end{aligned}\tag{121}$$

and corresponding equations for the fields  $o_1$ ,  $o_3$ , and  $o_5$ . The field  $z_1$  is given in Eq. (117) and its amplitudes  $A^{(1)}$  and  $B^{(1)}$  are determined at third order. The field  $z_3$  contains contributions from modes off the critical circle  $z_{3,off}$ ,  $|\vec{k}_{off}| \neq k_c$  and on the critical circle i.e.  $z_3 = z_{3,off} + \sum_j^n \left( A_j^{(3)}(T) e^{i\vec{k}_j \cdot \vec{x}} + A_{j-}^{(3)}(T) e^{-i\vec{k}_j \cdot \vec{x}} \right)$ . Its amplitude  $A^{(3)}$  are determined at fifth order. The field  $z_5$  also contains contributions from modes off the critical circle  $z_{5,off}$  and on the critical circle i.e.  $z_5 = z_{5,off} + \sum_j^n \left( A_j^{(5)}(T) e^{i\vec{k}_j \cdot \vec{x}} + A_{j-}^{(5)}(T) e^{-i\vec{k}_j \cdot \vec{x}} \right)$ .

Its amplitude  $A^{(5)}$  are determined at seventh order. This leads to a series of amplitude equations

$$\begin{aligned}
r_{z2}\partial_T A_i^{(1)} &= r_{z2}A_i^{(1)} - \sum_j g_{ij}|A_j^{(1)}|^2 A_i^{(1)} - \sum_j f_{ij}A_j^{(1)}A_{j-}^{(1)}\bar{A}_{i-}^{(1)} \\
r_{z2}\partial_T A_i^{(3)} &= r_{z2}A_i^{(3)} - \dots - \sum_j g_{ij}|A_j^{(1)}|^2 \bar{A}_i^{(3)} \\
r_{z2}\partial_T A_i^{(5)} &= r_{z2}A_i^{(5)} - \dots - \sum_j g_{ij}|A_j^{(3)}|^2 A_i^{(1)} - \sum_{jlk} h_{ijlk}|A_j^{(1)}|^2 |B_l^{(1)}|^2 |B_k^{(1)}|^2 A_i^{(1)},
\end{aligned} \tag{122}$$

which are solved order by order. We set  $r_{z2} = r_z$  and  $r_{o2} = r_o$  and rescale to the fast time. This leads to

$$\begin{aligned}
\partial_t A_i^{(1)} &= r_z A_i^{(1)} - \sum_j g_{ij}|A_j^{(1)}|^2 A_i^{(1)} - \sum_j f_{ij}A_j^{(1)}A_{j-}^{(1)}\bar{A}_{i-}^{(1)} \\
\partial_t A_i^{(3)} &= r_z A_i^{(3)} - \dots - \sum_j g_{ij}|A_j^{(1)}|^2 \bar{A}_i^{(3)} \\
\partial_t A_i^{(5)} &= r_z A_i^{(5)} - \dots - \sum_j g_{ij}|A_j^{(3)}|^2 A_i^{(1)} - \sum_{jlk} h_{ijlk}|A_j^{(1)}|^2 |B_l^{(1)}|^2 |B_k^{(1)}|^2 A_i^{(1)}.
\end{aligned} \tag{123}$$

We can combine the amplitude equations up to seventh order by introducing the amplitudes  $A_j = A_j^{(1)} + A_j^{(3)} + A_j^{(5)}$  and  $B_j = B_j^{(1)} + B_j^{(3)} + B_j^{(5)}$ . This leads to the amplitude equations

$$\begin{aligned}
\partial_t A_i &= r_z A_i - \sum_j g_{ij}|A_j|^2 A_i - \sum_j f_{ij}A_j A_{j-} \bar{A}_{i-} \\
&\quad - \sum_{jlk} h_{ijlk}|A_j|^2 |B_l|^2 |B_k|^2 A_i - \dots \\
\partial_t B_i &= r_o B_i - 2\bar{B}_{i+1}\bar{B}_{i+2} - \sum_j \tilde{g}_{ij}|B_j|^2 A B_i \\
&\quad - \sum_{jlk} h_{ijlk}|B_j|^2 |A_l|^2 |A_k|^2 B_i - \dots
\end{aligned} \tag{124}$$

For simplicity we have written only the simplest inter-map coupling terms. Depending on the configuration of active modes additional contributions may enter the amplitude equations. In addition, for the product-type coupling energy, there are coupling terms which contain the constant  $\delta$ , see Methods. In case of  $A \ll B \ll 1$  the inter-map coupling terms in dynamics of the modes  $B$  are small. In this limit the dynamics of the modes  $B$  decouples from the modes  $A$  and we can use the uncoupled OD dynamics, see Methods. In the following, we use the effective inter-map coupling strength  $\epsilon B^4$  (and  $\tau B^4$ ).

## 5 Higher order inter-map coupling energies

### 5.1 Optima of particular optimization principles: Higher order coupling terms

In this article we demonstrated that the low order coupling terms can lead to a complete suppression of OP selectivity i.e. vanishing magnitude of the order parameter  $|z|$ . As the coupling terms are effectively linear they not only influence pattern selection but also whether there is a pattern at all. This is in general not the case for higher order coupling energies using the amplitude equations Eq. (124). In this case the coupling is an effective cubic interaction term and complete selectivity suppression is impossible. Moreover, as in the low-order energy case, we could identify the limit  $r_z \ll r_o$  in which the backreaction onto the OD map formally becomes negligible. The potential is of the form

$$\begin{aligned}
V = & V_A + V_B + \\
& + \sum_{j,l,k} \sum_{u,v,w,p} h_{uvwp}^{ijkl} A_j A_l \bar{A}_k \bar{A}_i B_u B_v B_w B_p \delta_{\vec{k}_j + \vec{k}_l - \vec{k}_k - \vec{k}_i + \vec{k}_u + \vec{k}_v + \vec{k}_w + \vec{k}_p, 0} \\
& + \delta \sum_{j,l,k} \sum_{u,v,w} h_{uvp}^{ijkl} A_j A_l \bar{A}_k \bar{A}_i B_u B_v B_w \delta_{\vec{k}_j + \vec{k}_l - \vec{k}_k - \vec{k}_i + \vec{k}_u + \vec{k}_v + \vec{k}_w, 0} \\
& + \delta^2 \sum_{j,l,k} \sum_{u,v} h_{uvp}^{ijkl} A_j A_l \bar{A}_k \bar{A}_i B_u B_v \delta_{\vec{k}_j + \vec{k}_l - \vec{k}_k - \vec{k}_i + \vec{k}_u + \vec{k}_v, 0} \\
& + \delta^3 \sum_{j,l,k} \sum_u h_{uvp}^{ijkl} A_j A_l \bar{A}_k \bar{A}_i B_u \delta_{\vec{k}_j + \vec{k}_l - \vec{k}_k - \vec{k}_i + \vec{k}_u, 0} \\
& + \delta^4 \sum_{j,l,k} h^{ijkl} A_j A_l \bar{A}_k \bar{A}_i \delta_{\vec{k}_j + \vec{k}_l - \vec{k}_k - \vec{k}_i, 0}, \tag{125}
\end{aligned}$$

where  $\delta_{i,j}$  denotes the Kronecker delta and the uncoupled contributions

$$\begin{aligned}
V_A = & -r_z \sum_j^3 |A_j|^2 + \frac{1}{2} \sum_{i,j}^3 g_{ij} |A_i|^2 |A_j|^2 + \frac{1}{2} \sum_{i,j}^3 f_{ij} A_i A_{i-} \bar{A}_j \bar{A}_{j-} \\
V_B = & -r_o \sum_j^3 |B_j|^2 + \frac{1}{2} \sum_{i,j}^3 \tilde{g}_{ij} |B_i|^2 |B_j|^2. \tag{126}
\end{aligned}$$

Amplitude equations can be derived from the potential by  $\partial_t A_i = -\delta V / \delta \bar{A}_i$ . We have not written terms involving the modes  $A_{j-}$  or  $\bar{B}_j$ . The complete amplitude equations involving all modes and the corresponding coupling coefficients are given in Text S2. As for the low order coupling energies terms



involving the constant  $\delta$  depend only on the coupling coefficient of the product-type energy  $\tau$ . In the following we specify the amplitude equations for negligible backreaction where  $\mathcal{B} = \mathcal{B}_{hex}$ ,  $\mathcal{B} = \mathcal{B}_{st}$ , or  $\mathcal{B} = 0$ .

## 5.2 Product-type energy $U = \tau o^4 |z|^4$

First, we studied the higher order product-type inter-map coupling energy  $U = \tau o^4 |z|^4$ . As for the lower order version of this coupling energy the shift  $\delta(\gamma)$  explicitly enters the amplitude equations resulting in a rather complex parameter dependence, see Eq. (68) in the Methods section.

### 5.2.1 Stationary solutions and their stability

In the case of OD stripes the amplitude equations of OP modes read

$$\begin{aligned}
\partial_t A_1 &= r_z A_1 - \sum_j \left( g_{1j}^{(1)} |A_j|^2 A_1 + g_{1j}^{(2)} |A_j|^2 A_{1-} + g_{1j}^{(3)} A_j A_{j-} \bar{A}_{1-} + g_{1j}^{(4)} A_j A_{j-} \bar{A}_1 \right) \\
&\quad - B^4 A_{1-}^2 \bar{A}_1 - \sum_{u \neq v \neq w} A_u A_v \bar{A}_w \left( (8\delta^3 B + 24\delta B^2 \bar{B}) \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, 0} \right. \\
&\quad \left. + (8\delta^3 \bar{B} + 24\delta B \bar{B}^2) \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, 2\vec{k}_1} + 8\delta B^3 \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, -2\vec{k}_1} \right) \\
\partial_t A_2 &= r_z A_2 - \sum_j \left( g_{2j}^{(1)} |A_j|^2 A_2 + g_{2j}^{(3)} A_j A_{j-} \bar{A}_{2-} \right) \\
&\quad - g_{ii}^{(2)} A_2 A_{1-} \bar{A}_1 - g^{(5)} A_2 A_1 \bar{A}_{1-} - 1/2 g_{ii}^{(2)} A_{1-}^2 \bar{A}_{2-} - 1/2 g^{(5)} A_1^2 \bar{A}_{2-} \\
&\quad - \sum_{u,v,w} A_u A_v \bar{A}_w \left( g_{uv}^{(6)} \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, \vec{k}_2} + g_{ij}^{(7)} \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, \vec{k}_1 + \vec{k}_2} \right. \\
&\quad \left. + g_{ij}^{(8)} \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, -\vec{k}_1 + \vec{k}_2} + g_{ij}^{(9)} \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, 2\vec{k}_1 + \vec{k}_2} + g_{ij}^{(10)} \delta_{\vec{k}_u + \vec{k}_v - \vec{k}_w, -2\vec{k}_1 + \vec{k}_2} \right),
\end{aligned} \tag{127}$$

where  $\delta_{i,j}$  denotes the Kronecker delta and

$$\begin{aligned}
g_{ii}^{(1)} &= 1 + \delta^4 + 12\delta^2|B|^2 + 6|B|^4, & g_{ij \neq i}^{(1)} &= 2g_{ii}^{(1)}, \\
g_{ii}^{(2)} &= g_{ij \neq i}^{(2)} = 12\delta^2 B^2 + 8B^3 \overline{B}, \\
g_{ii}^{(3)} &= 0, & g_{ij \neq i}^{(3)} &= 2 + 12|B|^4 + 24\delta^2|B|^2 + 2\delta^4, \\
g_{ii}^{(4)} &= 0, & g_{ij \neq i}^{(4)} &= 12\delta^2 B^2 + 8B^3 \overline{B}, \\
g^{(5)} &= 12\delta^2 \overline{B}^2 + 8B \overline{B}^3, & g_{uu}^{(6)} &= 6|B|^4 + 6\delta|B|^2, \quad g_{uv \neq u}^{(6)} = 2g_{uu}^{(6)}, \\
g_{uu}^{(7)} &= 4\overline{B}\delta^3 + 1B\overline{B}^2\delta, & g_{uv \neq u}^{(7)} &= 2g_{uu}^{(7)}, \\
g_{uu}^{(8)} &= 4B\delta^3 + 1B^2\overline{B}\delta, & g_{uv \neq u}^{(8)} &= 2g_{uu}^{(8)}, \\
g_{uu}^{(9)} &= 6\overline{B}^2\delta^2, & g_{uv \neq u}^{(9)} &= 2g_{uu}^{(9)}, \\
g_{uu}^{(10)} &= 6B^2\delta^2, & g_{uv \neq u}^{(10)} &= 2g_{uu}^{(10)}.
\end{aligned}$$

The equation for the mode  $A_3$  is given by interchanging the modes  $A_2$  and  $A_3$  in Eq. (127). The equations for the modes  $A_{i-}$  are given by interchanging the modes  $A_i$  and  $A_{i-}$  and interchanging the modes  $B_i$  and  $\overline{B}_i$ .

In this case, at low inter-map coupling the OP stripes given by

$$z = \mathcal{A}_1 e^{i(\vec{k}_1 \cdot \vec{x} + \phi_1)} - \mathcal{A}_{1-} e^{-i(\vec{k}_1 \cdot \vec{x} + \phi_{1-})}, \quad (128)$$

with  $\phi_1 - \phi_{1-} = 2\psi_1 + \pi$  run parallel to the OD stripes. Their stationary amplitudes are given by

$$\begin{aligned}
A_1^2 &= \left( u - v - \sqrt{u^2 - 2uv + v^2 - 16w^2} \right)^2 x / 32w \\
A_{1-} &= x/2,
\end{aligned} \quad (129)$$

with  $x = r_z (u - v + \sqrt{u^2 - 2uv + v^2 - 16w^2}) / (uv - v^2 - 8w^2)$ ,  $u = 2 + 13\mathcal{B}^4\tau + 24\mathcal{B}^2\delta^2\tau + 2\delta^4\tau$ ,  $v = (6\mathcal{B}^4 + 12\mathcal{B}^2\delta^2 + \delta^4)\tau$ ,  $w = (2\mathcal{B}^2 + 3\delta^2)\tau\mathcal{B}^2$ . The parameter dependence of these stripe solutions is shown in Fig. 10A.

At large inter-map coupling the attractor states of the OP map consist of a stripe pattern containing only two preferred orientations, namely  $\vartheta = \phi_1$  and  $\vartheta = \phi_1 + \pi/2$ . The zero contour lines of the OD map are along the maximum amplitude of orientation preference minimizing the energy term.

In addition there are rhombic solutions

$$z = \mathcal{A}_1 e^{i(\vec{k}_1 \cdot \vec{x} + \psi_1)} + \mathcal{A}_{1-} e^{-i(\vec{k}_1 \cdot \vec{x} - \psi_1 + \pi)} + \mathcal{A}_2 e^{i(\vec{k}_2 \cdot \vec{x} + \psi_1)} + \mathcal{A}_{2-} e^{-i(\vec{k}_2 \cdot \vec{x} - \psi_1)} , \quad (130)$$

which exist also in the uncoupled case, see Fig. 10B. However, these rhombic solutions are energetically not favored compared to stripe solutions, see Fig. 10C. The inclusion of the inter-map coupling makes these rhombic solution even more stripe-like.

In case of a OD constant solution the amplitude equations read

$$\partial_t A_i = r_z A_i - \sum_j g_{ij} |A_j|^2 A_i - \sum_j f_{ij} A_j A_{j-} \bar{A}_{i-} , \quad (131)$$

with  $g_{ii} = 1 + \delta^4 \tau$ ,  $g_{ij} = 2 + 2\delta^4 \tau$  and  $f_{ij} = 2 + 2\delta^4 \tau$ . Inter-map coupling thus leads to a renormalization of the uncoupled interaction terms. Stationary solutions are stripes with the amplitude

$$\mathcal{A} = \sqrt{\frac{r_z}{1 + \delta^4 \tau}} , \quad (132)$$

and rhombic solutions with the stationary phases  $\phi_1 + \phi_{1-} - \phi_2 - \phi_{2-} = \pi$  and the stationary amplitudes

$$\mathcal{A}_1 = \mathcal{A}_{1-} = \mathcal{A}_2 = \mathcal{A}_{2-} = \sqrt{r_z / (5 + 5\delta^4 \tau)} . \quad (133)$$

In the case of OD hexagons we identify, in addition to stripe-like and rhombic solutions, uniform solutions  $\mathcal{A}_i = \mathcal{A}$ . When solving the amplitude equations numerically we have seen that the phase relations vary with the inter-map coupling strength  $\tau$  for non-uniform solutions. But for the uniform solution the phase relations are independent of the inter-map coupling strength. We use the ansatz for uniform solutions

$$\begin{aligned} \mathcal{A}_j &= \mathcal{A}_{j-} = \mathcal{A}, \quad j = 1, 2, 3 \\ \phi_j &= \psi_j + (j-1)2\pi/3 + \Delta \delta_{j,2} \\ \phi_{j-} &= -\psi_j + (j-1)2\pi/3 + \Delta (\delta_{j,1} + \delta_{j,3}) , \end{aligned} \quad (134)$$

where  $\delta_{i,j}$  is the Kronecker delta and  $\Delta$  a constant parameter. This leads to the stationarity condition

$$6\mathcal{A}^2\mathcal{B} [4(-4B^3 + 7B^2\delta - B\delta^2 + \delta^3) + \mathcal{B} \cos \Delta (13B^2 - 8B\delta + 6\delta^2)] \sin \Delta = 0. \quad (135)$$

Four types of stationary solutions exist namely the  $\Delta = 0, \Delta = \pi$ , which we already observed in case of the low order energies, and the solutions

$$\Delta = \Delta(\gamma) = \pm \arccos \left( \frac{4(4B^3 - 7B^2\delta + B\delta^2 - \delta^3)}{\mathcal{B}(13B^2 - 8B\delta + 6\delta^2)} \right), \quad (136)$$

which depends on  $\mathcal{B}$  and  $\delta$  and thus on the bias  $\gamma$ . The course of Eq. (136) as a function of  $\gamma$  is shown in Fig. 11B. Stationary amplitudes for these solutions are given by

$$\begin{aligned} \mathcal{A}_{\Delta=0}^2 &= \frac{r_z}{3\tau(3/\tau + 33\mathcal{B}^4 + 56\mathcal{B}^3\delta + 50\mathcal{B}^2\delta^2 + 16\mathcal{B}\delta^3 + 3\delta^4)} \\ \mathcal{A}_{\Delta=\pi}^2 &= \frac{r_z}{\tau(9/\tau + 483\mathcal{B}^4 - 504\mathcal{B}^3\delta + 246\mathcal{B}^2\delta^2 - 48\mathcal{B}\delta^3 + 9\delta^4)} \\ \mathcal{A}_{\Delta(\gamma)}^2 &= \frac{r_z(13\mathcal{B}^2 - 8\mathcal{B}\delta + 6\delta^2)}{3\tau(411\mathcal{B}^6\tau + 704\mathcal{B}^5\delta\tau - 376\mathcal{B}^4\delta^2\tau + 32\mathcal{B}^3\delta^3\tau + 2\delta^2(9 - 7\delta^4\tau) - 39\mathcal{B}^2(3\delta^4\tau - 1) + 8\mathcal{B}\delta(5\delta^4\tau - 3))} \end{aligned} \quad (137)$$

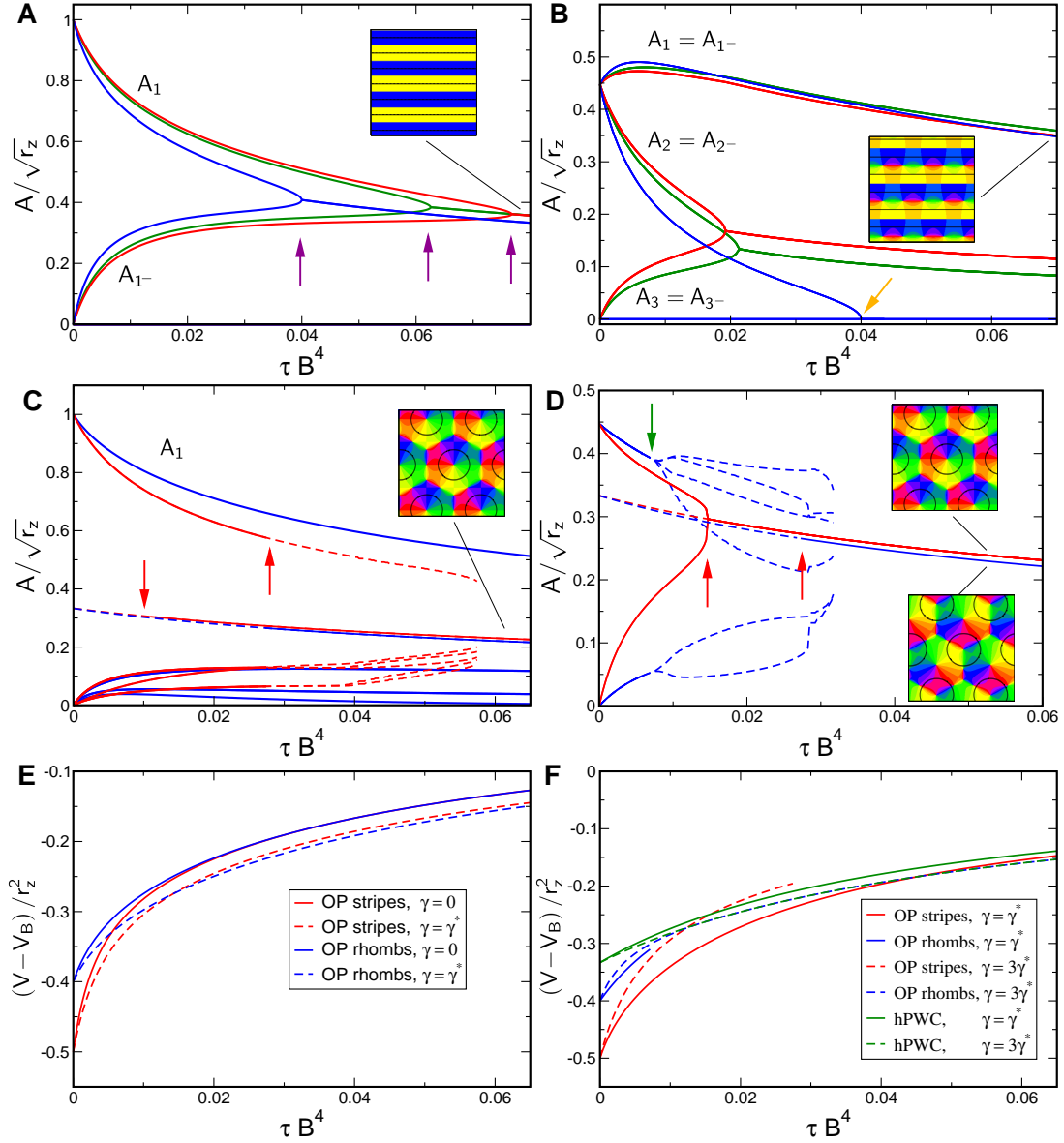
We study the stability properties of OP stripe-like, rhombic and uniform solutions using linear stability analysis. The eigenvalues of the stability matrix, see Text S2, are calculated numerically. Linear stability analysis shows that for  $\tau \geq 0$  the  $\Delta = 0$  solution is unstable for all bias values. The stability region of the  $\Delta = \pi$  solution and the solution Eq. (136) is bias dependent. The bias dependent solution Eq. (136) is stable for  $\gamma > \gamma^*$  and  $\gamma < \gamma_c$  for which  $\Delta = \pi$ , see Fig. 11B. For larger bias  $\gamma > \gamma_c$  only the  $d = \pi$  uniform solution is stable.

## 5.2.2 Bifurcation diagram

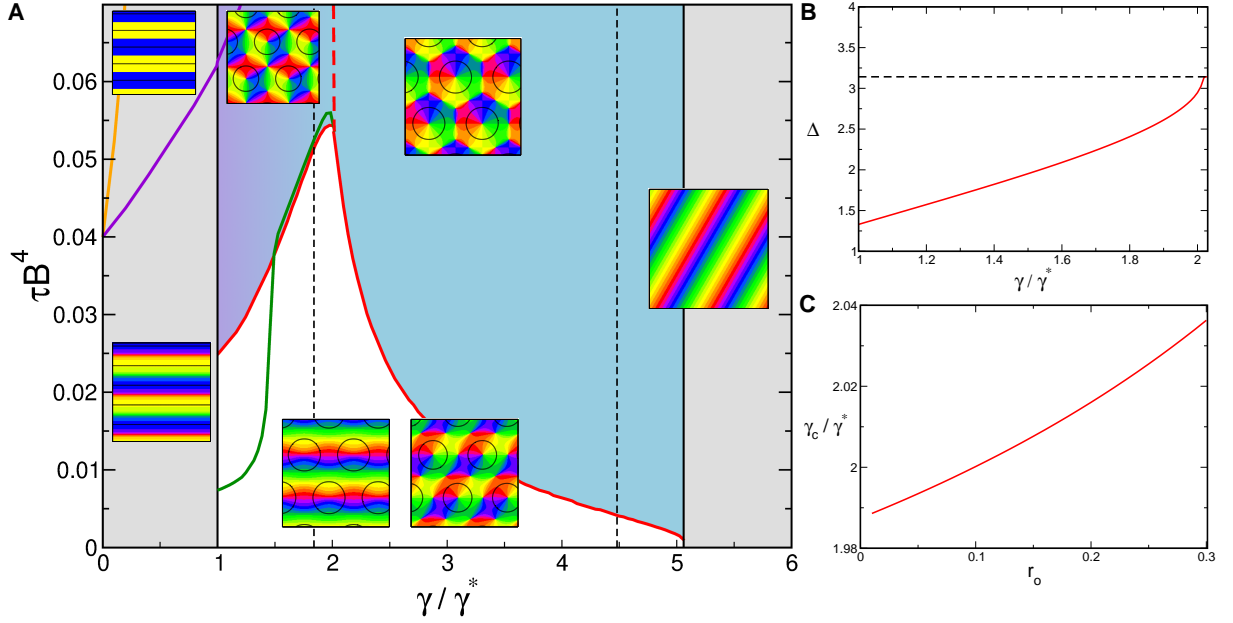
The parameter dependence of OP solutions when interacting with OD stripes is shown in Fig. 10A,B. Similar to the low order variant of this coupling energy the amplitude of the stripes pattern  $A_1$  is suppressed while the amplitude of the opposite mode  $A_{1-}$  grows. Finally both amplitudes collapse, leading to an orientation scotoma solution. In contrast to the low order variant this stripe pattern is stable for arbitrary large inter-map coupling. In case of OP rhombic solutions inter-map coupling transforms this solution by reducing the amplitudes  $A_2 = A_{2-}$  while increasing the amplitudes  $A_3 = A_{3-}$ . Without

OD bias this solution is then transformed into the orientation scotoma stripe pattern, similar to the low order variant of this energy. In contrast to the low order energy, for non-zero bias the amplitudes  $A_2$  and  $A_3$  stay small but non-zero.

The parameter dependence of OP solutions when interacting with OD hexagons is shown in Fig. 10**C,D**. For a small OD bias ( $\gamma = \gamma^*$ ) OP rhombic solutions decay into OP stripe-like patterns. These stripe-like patterns stay stable also for large-inter map coupling. In case of a larger OD bias ( $\gamma = 3\gamma^*$ ), both the OP stripe and the OP rhombic solutions decay into the uniform PWC solution. Thus for small bias there is a bistability between stripe-like and uniform PWC solutions while for larger OD bias the uniform PWC solution is the only stable solution. The potential of OP stripe and OP rhombic solutions is shown in Fig. 10**E,F**. In the uncoupled case as well as for small inter-map coupling strength OP stripe solutions are for all bias values the energetic ground state. For large inter-map coupling and a small bias ( $\gamma \approx \gamma^*$ ) rhombic solutions are unstable and the stripe-like solutions are energetically preferred compared to PWC solutions. For larger bias, however, PWC solutions are the only stable solutions for large inter-map coupling.



**Figure 10. Stationary amplitudes with coupling energy  $U = \tau|z|^4\mathbf{o}^4$ .** Solid (dashed) lines: stable (unstable) solutions. **A,B** OD stripes,  $\gamma = 0$  (blue),  $\gamma = \gamma^*$  (green),  $\gamma = 1.4\gamma^*$  (red). **C,D** OD hexagons,  $\gamma = \gamma^*$  (blue),  $\gamma = 3\gamma^*$  (red). **A,C** Transition from OP stripe solutions, **B,D** Transition from OP rhombic solutions. **E** Potential, Eq. (125), of OP stripes and OP rhombs interacting with OD stripes. **F** Potential, Eq. (125), of OP stripes, OP rhombs, and hPWC interacting with OD hexagons. Arrows indicate corresponding lines in the phase diagram, Fig. (11).



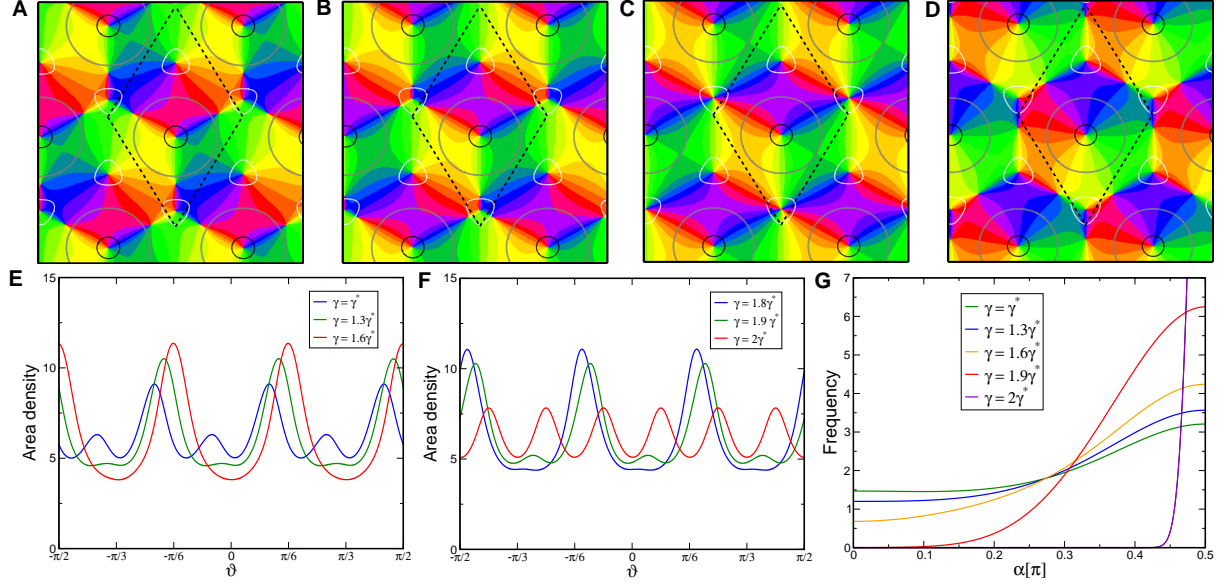
**Figure 11. A** Phase diagram with coupling energy  $U = \tau\mathbf{o}^4|\mathbf{z}|^4$ ,  $r_o = 0.2, r_z \ll r_o$ . Vertical black lines: stability range of OD stripes, hexagons, and constant solutions. Magenta (orange) line: Stability border of orientation scotoma stripes. Green solid line: Stability border of rhombic solutions. Red solid line: Stability border of PWC solutions, red dashed line:  $\gamma_c$ , **B** Course of Eq. (136), dashed line:  $\Delta = \pi$ . **C** Stability border between Eq. (136) solution and the  $\Delta = \pi$  solution as a function of  $r_o$  (vertical red line in **A**).

### 5.2.3 Phase diagram

The stability properties of all stationary solutions are summarized in the phase diagram Fig. 11. Compared to the gradient-type interaction energy we cannot scale out the dependence on  $r_o$ . The phase diagram is thus plotted for  $r_o = 0.2$ . We rescale the inter-map coupling strength as  $\tau\mathcal{B}^4$  where  $\mathcal{B}$  is the stationary amplitude of the OD hexagons. In the regime of stable OD stripes there is a transition from OP stripes towards the orientation scotoma stripe solution. In the regime of stable OD hexagons there is a transition from OP stripes towards PWC solutions (red line). The stability border of PWC solutions is strongly OD bias dependent and has a peak at  $\gamma \approx 2\gamma^*$ . For small OD bias  $\gamma$  the uniform solution Eq. (136) is stable. With increasing bias there is a smooth transition of this solution until at  $\gamma = \gamma_c$  the  $d = \pi$  uniform solution becomes stable. In Fig. 11C the stability border  $\gamma_c$  between the two types of uniform solutions is plotted as a function of  $r_o$ . We observe that there is only a weak dependence on the control parameter and  $\gamma_c \approx 2\gamma^*$ .

### 5.2.4 Interaction induced pinwheel crystals

Figure 12 illustrates the uniform solutions Eq. (136) for different values of the OD bias  $\gamma$ . For small



**Figure 12. Bias dependent pinwheel crystals**, Eq. (136) **A**  $\gamma = \gamma^*$ , **B**  $\gamma = 1.3\gamma^*$ , **C**  $\gamma = 1.6\gamma^*$ , **D**  $\gamma = 2\gamma^*$ . OP map, superimposed are the OD borders (gray), 90% ipsilateral eye dominance (black), and 90% contralateral eye dominance (white),  $r_o = 0.2$ . Dashed lines mark the unit cell of the regular pattern. **E,F** Distribution of orientation preference. **G** Intersection angles between iso-orientation lines and OD borders.

bias, the OP pattern has six pinwheels per unit cell. Two of them are located at OD maxima while one is located at an OD minimum. The remaining three pinwheels are located near the OD border. With increasing bias, these three pinwheels are pushed further away from the OD border, being attracted to the OD maxima. With further increasing bias three shifted pinwheels merge with the one at the OD maximum building a single charge 1 pinwheel centered on a contralateral peak. The remaining two pinwheels are located at an ipsi and contra peak, respectively. Note, compared to the Braitenberg PWC of the  $\Delta = 0$  uniform solution the charge 1 pinwheel here is located at the contralateral OD peak. Finally, the charge 1 pinwheels split up again into four pinwheels. With increasing bias the solution more and more resembles the Ipsi-center PWC ( $\Delta = \pi$  solution) which is stable also in the lower order version of the coupling energy. Finally, at  $\gamma/\gamma^* \approx 2$  the Ipsi-center PWC becomes stable and fixed for  $\gamma > 2\gamma^*$ . The distribution of preferred orientations for different values of the bias  $\gamma$  is shown in Fig. 12**E,F**, reflecting the symmetry of each pattern. The distribution of intersection angles is shown in Fig. 12**G**. Remarkably, all



solutions show a tendency towards perpendicular intersection angles. This tendency is more pronounced with increasing OD bias. At about  $\gamma/\gamma^* \approx 1.9$  parallel intersection angles are completely absent and at  $\gamma/\gamma^* \approx 2$  there are exclusively perpendicular intersection angles.

### 5.3 Gradient-type energy $U = \epsilon |\nabla o \cdot \nabla z|^4$

Finally, we examine the higher order version of the gradient-type inter-map coupling. The interaction terms are independent of the OD shift  $\delta$ . In this case the coupling strength can be rescaled as  $\beta \mathcal{B}^4$  and is therefore independent of the bias  $\gamma$ . The bias in this case only determines the stability of OD stripes, hexagons or the constant solution.

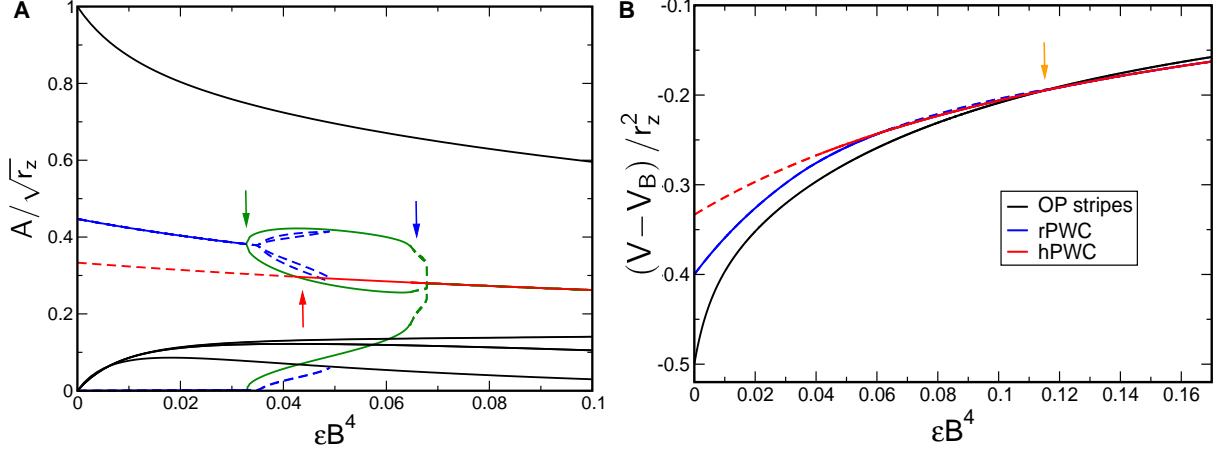
#### 5.3.1 Stationary solutions and their stability

As for its lower order pendant a coupling to OD stripes is relatively easy to analyze. The energetic ground state corresponds to OP stripes with the direction perpendicular to the OD stripes for which  $U = 0$ . In addition, there are rhombic solutions with the stationary amplitudes  $\mathcal{A}_1 = \mathcal{A}_{1-} = \mathcal{A}_2 = \mathcal{A}_{2-} = \sqrt{r_z/(5 + 80\epsilon \mathcal{B}^4)}$ . In case the OD map is a constant,  $o(\mathbf{x}) = \delta$ , the gradient-type inter-map coupling leaves the OP unaffected. As for its lower order pendant the stationary states are therefore OP stripes running in an arbitrary direction and the uncoupled rhombic solutions.

In case of OD hexagons we identified three types of non-uniform solutions. Besides stripe-like solutions of  $z(\mathbf{x})$  with one dominant mode we find rPWCs  $\mathcal{A}_j = \mathcal{A}_{j-} = (\mathcal{A}, a, \mathcal{A})$  with  $a \ll \mathcal{A}$  and distorted rPWCs  $\mathcal{A}_j = (\mathcal{A}_1, \mathcal{A}_2, \mathcal{A}_3), \mathcal{A}_{j-} = (\mathcal{A}_3, \mathcal{A}_2, \mathcal{A}_1)$  with  $\mathcal{A}_1 \neq \mathcal{A}_2 \neq \mathcal{A}_3$ . Note, that distorted rPWCs are not stable in case of the product-type coupling energy or the analyzed low-order coupling energies. For these non-uniform solutions the stationary phases are inter-map coupling strength dependent. We therefore calculate the stationary phases and amplitudes numerically using a Newton method and initial conditions close to these solutions.

In case of OD hexagons there are further uniform solutions  $A_j = A_{j-} = \mathcal{A}, B_j = \mathcal{B}$  and  $\psi_1 = \psi_3 = 0, \psi_2 = \pi$ . The imaginary part of the amplitude equations, see Text S1, leads to equations for the phases  $\phi_j$ . The ansatz Eq. (134) leads to the stationarity condition

$$(13 \cos \Delta - 5) \sin \Delta = 0. \quad (138)$$



**Figure 13. Stationary amplitudes with coupling energy  $U = \epsilon |\nabla \mathbf{z} \cdot \nabla \mathbf{o}|^4$ , **A**** Solid (dashed) lines: Stable (unstable) solutions. Blue: rPWC, green: distorted rPWC, red: hPWC. Black lines: stripe-like solutions. **B** Potential, Eq. (125), of OP stripes (black), OP rhombs (blue), and hPWC solutions (red). Arrows indicate corresponding lines in the phase diagram, Fig. (S14).

The solutions are  $\Delta = 0$ ,  $\Delta = \pi$ , and  $\Delta = \pm \arccos(\frac{5}{13}) \approx \pm 1.176$  where the stationary amplitude are given by

$$\mathcal{A} = \sqrt{r_z / (9 + \epsilon B^4 (61.875 - 7.5 \cos \Delta + 4.875 \cos(2\Delta)))}. \quad (139)$$

We calculated the stability properties of all stationary solutions by linear stability analysis considering perturbations of the amplitudes  $\mathcal{A}_j \rightarrow \mathcal{A} + a_j$ ,  $\mathcal{A}_{j-} \rightarrow \mathcal{A} + a_{j-}$  and of the phases  $\phi_j \rightarrow \phi_j + \varphi_j$ ,  $\phi_{j-} \rightarrow \phi_{j-} + \varphi_{j-}$ . This leads to a perturbation matrix  $M$ . In general amplitude and phase perturbations do not decouple. We therefore calculate the eigenvalues of the perturbation  $M$  matrix numerically. It turns out that for this type of coupling energy only the uniform solutions with  $\Delta = \pm \arccos(\frac{5}{13})$  are stable while the  $\Delta = 0$  and  $\Delta = \pi$  solutions are unstable in general.

### 5.3.2 Bifurcation diagram

For increasing inter-map coupling strength the amplitudes of the OP stripe and OP rhombic solutions are shown in Fig. 13A. In case of stable OD hexagons there is a transition from rPWC (blue) towards distorted rPWC (green). The distorted rPWCs then decay into the hPWC (red). In case of OP stripes (black dashed lines) inter-map coupling leads to a slight suppression of the dominant mode and a growth of the remaining modes. This growth saturates at small amplitudes and thus the solution stays stripe-like. This stripe-like solution remains stable for arbitrary large inter-map coupling. Therefore there is a

bistability between hPWC solutions and stripe-like solutions for large inter-map coupling.

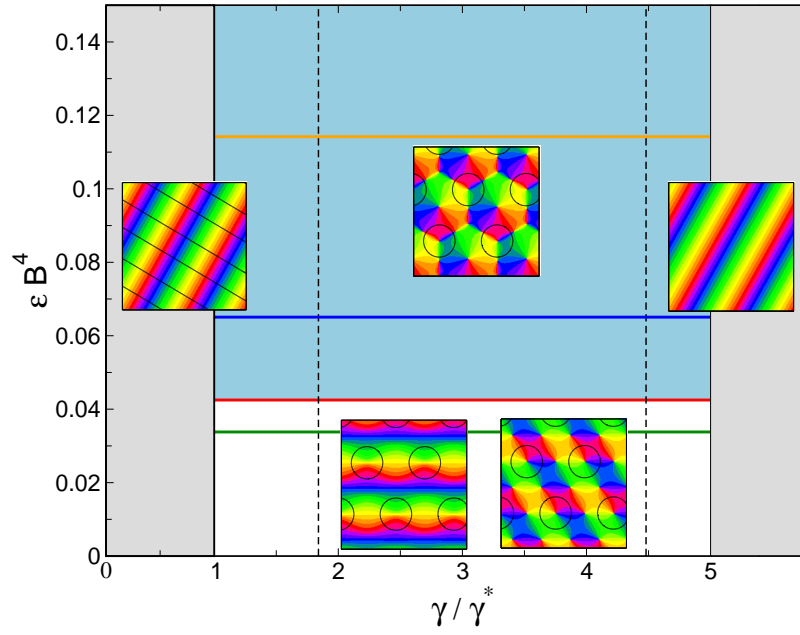
The stability borders for the rPWC and distorted rPWC solutions were obtained by calculating their bifurcation diagram numerically from the amplitude equations, see Text S1. With increasing map coupling we observe a transition from a rPWC towards a distorted rPWC at  $\epsilon\mathcal{B}^4 \approx 0.033$  (blue dashed line in Fig. 14A), see also Fig. 17A. The distorted rPWC loses its stability at  $\epsilon\mathcal{B}^4 \approx 0.065$  (blue solid line in Fig. 14A) and from thereon all amplitudes are equal corresponding to the hPWC. There is a bistability between hPWC, rPWC, and stripe-like solutions. To calculate the inter-map coupling needed for the hexagonal solution to become the energetic ground state we calculated the potential Eq. (125) for the three solutions. In case of the uniform solution Eq. (134) the potential is given by

$$V = -6\mathcal{A}^2 r_z - 3\mathcal{B}^2 r_o + 27\mathcal{A}^4 + \frac{45}{2}\mathcal{B}^4 + \frac{1}{16}\mathcal{A}^4\mathcal{B}^4\epsilon(3210 - 456\cos\Delta + 90\cos(2\Delta)) . \quad (140)$$

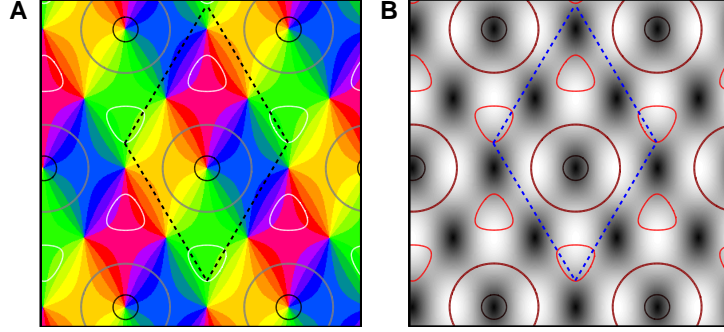
The potential in case of the rhombic and stripe-like solutions was obtained by numerically solving the amplitude equations using Newtons method and initial conditions close to these solutions. Above  $\epsilon\mathcal{B}^4 \approx 0.12$  the hPWC is energetically preferred compared to stripe-like solutions (red dashed line in in Fig. 14) and thus corresponds to the energetic ground state for large inter-map coupling, see Fig. (13)B.

### 5.3.3 Phase diagram

We calculated the phase diagram of the coupled system in the limit  $r_z \ll r_o$ , shown in Fig. 14. The phase diagram contains the stability borders of the uncoupled OD solutions  $\gamma^*, \gamma_2^*, \gamma_3^*, \gamma_4^*$ . They correspond to vertical lines, as they are independent of the inter-map coupling in the limit  $r_z \ll r_o$ . At  $\gamma = \gamma^*$  hexagons become stable. Stripe solutions become unstable at  $\gamma = \gamma_2^*$ . At  $\gamma = \gamma_3^*$  the homogeneous solution becomes stable while at  $\gamma = \gamma_4^*$  hexagons loose their stability. In units  $\gamma/\gamma^*$  the borders  $\gamma_2^*, \gamma_3^*, \gamma_4^*$  vary slightly with  $r_o$ , see Fig. 9, and are drawn here for  $r_o = 0.2$ . We rescale the inter-map coupling strength as  $\epsilon\mathcal{B}^4$  where  $\mathcal{B}$  is the stationary amplitude of the OD hexagons. The stability borders of OP solutions are then horizontal lines. For  $\gamma < \gamma^*$  or for  $\gamma > \gamma_4^*$  pinwheel free orientation stripes are dynamically selected. For  $\gamma^* < \gamma < \gamma_4^*$  and above a critical effective coupling strength  $\epsilon\mathcal{B}^4 \approx 0.042$  hPWC solutions are stable and become the energetic ground state of Eq. (125) above  $\epsilon\mathcal{B}^4 \approx 0.117$ . Below  $\epsilon\mathcal{B}^4 \approx 0.065$ , rPWC solutions are stable leading to a bistability region between rPWC and hPWC solutions. We find in this region



**Figure 14. Phase diagram with coupling energy  $U = \epsilon |\nabla \mathbf{z} \cdot \nabla \mathbf{o}|^4$ , for  $r_z \ll r_o$ .** Vertical lines: stability range of OD hexagons, green line: transition from rPWC to distorted rPWC, red line: stability border of hPWC, blue line: stability border of distorted rPWC. Above orange line: hPWC corresponds to ground state of energy.



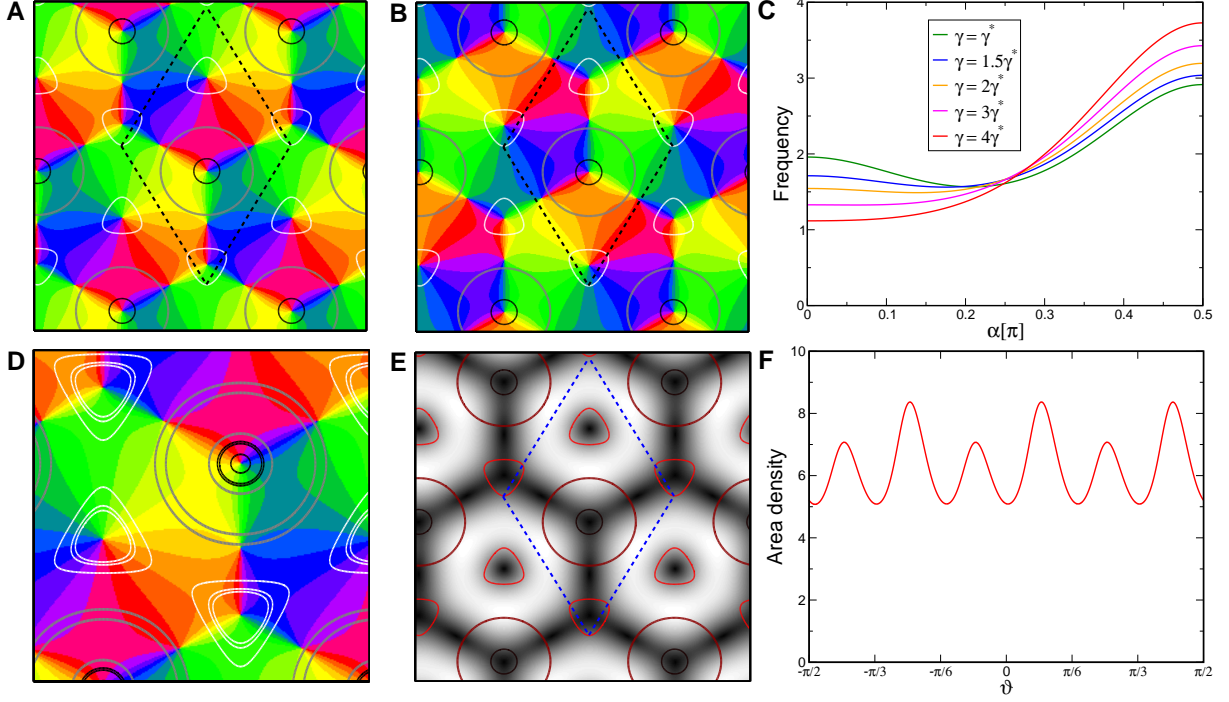
**Figure 15. Rhombic pinwheel crystals.** **A** OP map with superimposed OD borders (gray), 90% ipsilateral eye dominance (black), and 90% contralateral eye dominance (white),  $\gamma = 3\gamma^*$ ,  $r_o = 0.2$ . **B** Selectivity  $|z(\mathbf{x})|$ , white: high selectivity, black: low selectivity.

that rhombic solutions transform into distorted rhombic solutions above an effective coupling strength of  $\epsilon\mathcal{B}^4 \approx 0.033$ .

#### 5.3.4 Interaction induced pinwheel crystals

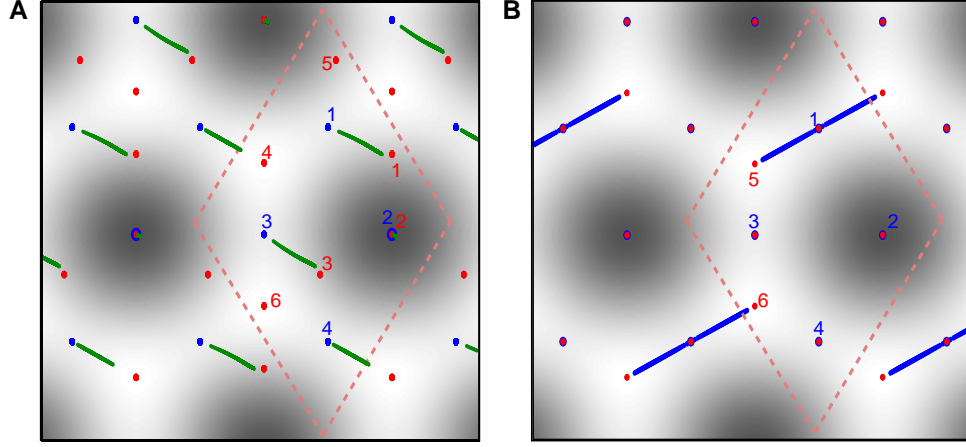
First, we studied the spatial layout of the rhombic solutions which is illustrated in Fig. 15. The rPWC solutions are symmetric under rotation by 180 degree. The rhombic solution has 4 pinwheels per unit cell and its pinwheel density is thus  $\rho = 4 \cos(\pi/6) \approx 3.5$ . One may expect that the energy term Eq. (111) favors pinwheels to co-localize with OD extrema. In case of the rhombic layout there is only one pinwheel at an OD extremum while the other three pinwheels are located at OD saddle-points which are also energetically favorable positions with respect to  $U$ . The orientation selectivity  $|z(\mathbf{x})|$  for the rPWC is shown in Fig. 15B. The pattern of selectivity is arranged in small patches of highly selective regions.

The hexagonal layout of the two stable uniform solutions is shown in Fig. 16. The  $\Delta = \pm \arccos(5/13)$  solutions have six pinwheels per unit cell. Their pinwheel density is therefore  $\rho = 6 \cos \pi/6 \approx 5.2$ . Three pinwheels of the same topological charge are located at the extrema of the OD map. Two of these are located at the OD maximum while one is located at the OD minimum. The remaining three pinwheels are not at an OD extremum but near the OD border. The distance to the OD border depends on the OD bias, see Fig. 16D. For a small bias ( $\gamma \approx \gamma^*$ ) these three pinwheels are close to the OD borders and with increasing bias the OD border moves away from the pinwheels. The pinwheel in the center of the OP hexagon is at the contralateral OD peak. Because these pinwheels organize most of the map while the others essentially only match one OP hexagon to its neighbors we refer to this pinwheel



**Figure 16. Contra-center pinwheel crystals.** **A,B** OP map, superimposed are the OD borders (gray), 90% ipsilateral eye dominance (black), and 90% contralateral eye dominance (white),  $r_o = 0.2, \gamma = 3\gamma^*$ . **A**  $\Delta = \arccos(5/13)$ , **B**  $\Delta = -\arccos(5/13)$ . **C** Distribution of orientation preference. **D** OP map with superimposed OD map for three different values ( $\gamma = \gamma^*, \gamma = (\gamma_4^* - \gamma^*)/2 + \gamma^*, \gamma = \gamma_4^*$ ) of the OD bias. **E** Selectivity  $|z(\mathbf{x})|$ , white: high selectivity, black: low selectivity. **F** Distribution of intersection angles.

crystal as the *Contra-center pinwheel crystal*. Note, that some pinwheels are located at the vertices of the hexagonal pattern. Pinwheels located between these vertices (on the edge) are not in the middle of this edge. Solutions with  $\Delta = \pm \arccos(5/13)$  are therefore not symmetric under a rotation by 60 degree but symmetric under a rotation by 120 degree. Therefore the solution  $\Delta = + \arccos(5/13)$  cannot be transformed into the solution  $\Delta = - \arccos(5/13)$  by a rotation of the OD and OP pattern by 180 degrees. This symmetry is also reflected by the distribution of preferred orientations, see Fig. 16F. Six orientations are slightly overrepresented. Compared to the Ipsi-center PWC, which have a  $60^\circ$  symmetry, this distribution illustrates the  $120^\circ$  symmetry of the pattern. The distribution of intersection angles is continuous, see Fig. 16C. Although there is a fixed uniform solution with varying OD bias the distribution of intersection angles changes. The reason for this is the bias dependent change in the OD borders, see Fig. 16D. For all bias values there is a tendency towards perpendicular intersection angles, although for



**Figure 17. Inter-map coupling strength dependent pinwheel positions.** OD map, superimposed pinwheel positions (points) for different inter-map coupling strengths,  $\gamma/\gamma^* = 3$ . Numbers label pinwheels within the unit cell (dashed lines). Blue (green, red) points: pinwheel positions for rPWC (distorted rPWC, hPWC) solutions. **A**  $\mathbf{U} = \epsilon |\nabla \mathbf{z} \cdot \nabla \mathbf{o}|^4$ , using stationary amplitudes from Fig. (13)(a). Positions of distorted rPWCs move continuously (pinwheel 1,3,4). **B**  $\mathbf{U} = \tau |\mathbf{z}|^4 \mathbf{o}^4$ , using stationary amplitudes from Fig. (10)D. Positions of rPWCs move continuously (pinwheel 5,6).

low OD bias there is an additional small peak at parallel intersection angles. The orientation selectivity  $|z(\mathbf{x})|$  for the hPWC is shown in Fig. 16E. The pattern shows hexagonal bands of high selectivity.

Finally, we study changes in pinwheel positions during the transition from a rPWC towards a hPWC i.e. with increasing inter-map coupling strength. In case of the higher order gradient-type coupling energy there is a transition towards a contra-center PWC, see Fig. 17A. In the regime where the distorted rPWC is stable, three of the four pinwheels of the rPWC are moving either from an OD saddle-point to a position near an OD border (pinwheel 1 and 3) or from an OD saddle-point to an OD extremum (pinwheel 4). One pinwheel (pinwheel 2) is fixed in space. At the transition to the hPWC two additional pinwheels are created, one near an OD border (pinwheel 5) and one at an OD extremum (pinwheel 6). We compare the inter-map coupling strength dependent pinwheel positions of the gradient-type coupling energy with those of the product type coupling energy, see Fig. (17)B. In this case three (pinwheel 2,3,4) of the four rPWC pinwheels have a inter-map coupling strength independent position. The remaining pinwheel (pinwheel 1) with increasing inter-map coupling strength splits up into three pinwheels. While one of these three pinwheels (pinwheel 1) is fixed in space the remaining two pinwheels (pinwheel 5,6) move towards the extrema of OD. Thus for large inter-map coupling, where hPWC solutions are stable, all six pinwheels are located at OD extrema.

## 6 Summary

We derived amplitude equations and analyzed ground states of the higher order inter-map coupling energies. We calculated local and global optima and derived corresponding phase diagrams. A main difference between phase diagrams for low order and high order coupling energies consists in the collapse of orientation selectivity above a critical coupling strength that occurs only in the low order models. In contrast, for the high order versions, orientation selectivity is preserved for arbitrarily strong inter-map coupling. In order to neglect the backreaction on the dynamics of the modes  $B$  we assumed  $A \ll B \ll 1$ . Our results, however, show that for the stability of pinwheel crystals a finite amplitude  $B$  is necessary. A decrease in  $B$  cannot be compensated by another parameter (as it would be  $r_z$  in case of the low order inter-map coupling energies). For a finite  $B$  even higher order corrections to the amplitude equations than those presented here can thus become significant. Such terms are we neglected in the present treatment. In part (II) of this study we numerically confirm our main results for the higher order inter-map coupling energies.

From a practical point of view, the analyzed phase diagrams and pattern properties indicate that the higher order gradient-type coupling energy is the simplest and most convenient choice for constructing models that reflect the correlations of map layouts in the visual cortex. For this coupling, intersection angle statistics are reproduced well, pinwheels can be stabilized, and pattern collapse cannot occur.



## Text S2: Supporting Information for

### Coordinated optimization of visual cortical maps

#### (I) Symmetry-based analysis

## 7 Amplitude equations for higher order coupling energies

Here, we list the amplitude equations for the OP dynamics in case of the high order inter-map coupling energies  $U = \epsilon |\nabla z \cdot \nabla o|^4$  and  $U = \tau |z|^4 o^4$ .

$$\begin{aligned}
\partial_t A_i = & r_z A_i - \sum_j |A_j|^2 A_i \left( g_{ij} + \delta^4 g'_{ij} + \delta^2 \sum_u g_{iju} |B_u|^2 \right. \\
& \left. + \delta g''_{ij} (B_1 B_2 B_3 + \bar{B}_1 \bar{B}_2 \bar{B}_3) + \sum_{u,v} g_{ijuv} |B_u|^2 |B_v|^2 \right) \\
& - \sum_j |A_{j-}|^2 A_i \left( g_{ij-} + \delta^4 g'_{ij-} + \delta^2 \sum_u g_{ij-u} |B_u|^2 \right. \\
& \left. + \delta g''_{ij-} (B_1 B_2 B_3 + \bar{B}_1 \bar{B}_2 \bar{B}_3) + \sum_{u,v} g_{ij-uv} |B_u|^2 |B_v|^2 \right) \\
& - \sum_j A_j A_{j-} \bar{A}_{i-} \left( f_{ij} + \delta^4 f'_{ij} + \delta^2 \sum_u f_{iju} |B_u|^2 \right. \\
& \left. + \delta f''_{ij} (B_1 B_2 B_3 + \bar{B}_1 \bar{B}_2 \bar{B}_3) + \sum_{u,v} f_{ijuv} |B_u|^2 |B_v|^2 \right) \\
& - \sum_{j \neq l} A_i A_j \bar{A}_l \left( \sum_u h_{ijlu}^{(1)} \bar{B}_j B_l |B_u|^2 + \delta^2 h_{ijl}^{(1)} \bar{B}_j B_l \right) \\
& - \sum_{j,l} A_i A_{j-} \bar{A}_l \left( \sum_u h_{ij-lu}^{(1)} B_j B_l |B_u|^2 + \delta^2 h_{ij-l}^{(1)} B_j B_l \right) \\
& - \sum_{j,l} A_i A_j \bar{A}_{l-} \left( \sum_u h_{ijl-u}^{(1)} \bar{B}_j \bar{B}_l |B_u|^2 + \delta^2 h_{ijl-}^{(1)} \bar{B}_j \bar{B}_l \right) \\
& - \sum_{j \neq l} A_i A_{j-} \bar{A}_{l-} \left( \sum_u h_{ij-l-u}^{(1)} B_j \bar{B}_l |B_u|^2 + \delta^2 h_{ij-l-}^{(1)} B_j \bar{B}_l \right) \\
& - \sum_{l,j \neq k} A_j A_l \bar{A}_k h_{ijlk}^{(2)} \bar{B}_j \bar{B}_l B_k B_i - \sum_{l,j,k} A_{j-} A_l \bar{A}_k h_{ij-lk}^{(2)} B_j \bar{B}_l B_k B_i \\
& - \sum_{l,j \neq k} A_j A_l \bar{A}_{k-} h_{ijlk-}^{(2)} \bar{B}_j \bar{B}_l \bar{B}_k B_i - \sum_{l,j \neq k} A_{j-} A_{l-} \bar{A}_k h_{ij-l-k}^{(2)} B_j B_l B_k B_i
\end{aligned}$$

$$\begin{aligned}
& - \sum_{l,j \neq k} A_j - A_l \bar{A}_k - h_{ij-lk}^{(2)} B_j \bar{B}_l \bar{B}_k B_i - \sum_{l,j \neq k} A_j - A_l - \bar{A}_k - h_{ij-l-k}^{(2)} B_j B_l \bar{B}_k B_i \\
& - \sum_{j,l} |A_j|^2 A_l \left( \sum_u h_{ijlu}^{(3)} |B_u|^2 \bar{B}_l B_i + \delta^2 h_{ijl}^{(3)} \bar{B}_l B_i \right) \\
& - \sum_{j,l} |A_j -|^2 A_l \left( \sum_u h_{ij-lu}^{(3)} |B_u|^2 \bar{B}_l B_i + \delta^2 h_{ij-l}^{(3)} \bar{B}_l B_i \right) \\
& - \sum_{j,l} |A_j|^2 A_l - \left( \sum_u h_{ijl-u}^{(3)} |B_u|^2 B_l B_i + \delta^2 h_{ijl}^{(3)} B_l B_i \right) \\
& - \sum_{j,l} |A_j -|^2 A_l - \left( \sum_u h_{ij-l-u}^{(3)} |B_u|^2 B_l B_i + \delta^2 h_{ij-l}^{(3)} B_l B_i \right) \\
& - \sum_{j,u} \delta h_{iju}^{(4)} A_i \bar{A}_j A_u B_{u+1} B_{u+2} B_j - \sum_{j,u} \delta h_{iuj}^{(4)} A_i A_j \bar{A}_u \bar{B}_{u+1} \bar{B}_{u+2} \bar{B}_j \\
& - \sum_{j,u} \delta h_{ij-u}^{(4)} A_i \bar{A}_j - A_u B_{u+1} B_{u+2} \bar{B}_j - \sum_{j,u} \delta h_{ij-u}^{(4)} A_i A_j - \bar{A}_u \bar{B}_{u+1} \bar{B}_{u+2} \bar{B}_j \\
& - \sum_{j,u} \delta h_{iju}^{(4)} A_i \bar{A}_j A_u - \bar{B}_{u+1} \bar{B}_{u+2} B_j - \sum_{j,u} \delta h_{iju}^{(4)} A_i A_j \bar{A}_u - B_{u+1} B_{u+2} B_j \\
& - \sum_{j,u} \delta h_{ij-u}^{(4)} A_i \bar{A}_j - A_u - \bar{B}_{u+1} \bar{B}_{u+2} \bar{B}_j - \sum_{j,u} \delta h_{ij-u}^{(4)} A_i A_j - \bar{A}_u - B_{u+1} B_{u+2} \bar{B}_j \\
& - \sum_u h_{iu}^{(5)} A_i A_u \bar{A}_{(u+1)-} B_{u+2} B_1 B_2 B_3 - \sum_u h_{iu-}^{(5)} A_i A_u - \bar{A}_{(u+1)} \bar{B}_{u+2} B_1 B_2 B_3 \\
& - \sum_u \tilde{h}_{iu}^{(5)} A_i A_u \bar{A}_{(u+1)-} B_{u+2} \bar{B}_1 \bar{B}_2 \bar{B}_3 - \sum_u \tilde{h}_{iu-}^{(5)} A_i A_u - \bar{A}_{(u+1)} \bar{B}_{u+2} \bar{B}_1 \bar{B}_2 \bar{B}_3 \\
& - \sum_u \delta^3 h^{(5)} A_i A_u \bar{A}_{(u+1)-} B_{u+2} - \sum_u \delta^3 h^{(5)} A_i A_u - \bar{A}_{(u+1)} \bar{B}_{u+2} \\
& - \sum_{j,u} \delta h_{iju}^{(6)} \bar{A}_j A_u A_{u+1} B_{u+2} B_j B_i - \sum_{j,u} \delta h_{ij-u}^{(6)} \bar{A}_j - A_u A_{u+1} B_{u+2} \bar{B}_j B_i \\
& - \sum_{j,u} \delta h_{iju}^{(6)} \bar{A}_j A_u - A_{(u+1)-} \bar{B}_{u+2} B_j B_i - \sum_{j,u} \delta h_{ij-u}^{(6)} \bar{A}_j - A_u - A_{(u+1)-} \bar{B}_{u+2} \bar{B}_j B_i \\
& - \sum_{j,u} \delta h_{iju}^{(7)} |A_j|^2 A_u B_{u+1} B_{u+2} B_i - \sum_{j,u} \delta h_{ij-u}^{(7)} |A_j -|^2 A_u B_{u+1} B_{u+2} B_i \\
& - \sum_{j,u} \delta h_{iju}^{(7)} |A_j|^2 A_u - \bar{B}_{u+1} \bar{B}_{u+2} B_i - \sum_{j,u} \delta h_{ij-u}^{(7)} |A_j -|^2 A_u - \bar{B}_{u+1} \bar{B}_{u+2} B_i \\
& - \sum_{ij} \delta h_{ij}^{(8)} A_j^2 \bar{A}_{i+2} \bar{B}_j^2 \bar{B}_{i+1} - \sum_{ij} \delta h_{ij-}^{(8)} A_j^2 - \bar{A}_{i+2} B_j^2 \bar{B}_{i+1} \\
& - \sum_{ij} \delta^3 h_{ij}^{(9)} |A_j|^2 A_{(i+2)-} \bar{B}_{i+1} - \sum_{ij} \delta^3 h_{ij-}^{(9)} |A_j -|^2 A_{(i+2)-} \bar{B}_{i+1}
\end{aligned}$$

where the indices are considered to be cyclic i.e.  $j+3 = j$ . All sums are considered to run from 1 to 3. In the article, these amplitude equations are specified in case of OD stripes, Eq. (109), OD hexagons, Eq. (110), or a constant OD solution, Eq (111).



## 8 Coupling coefficients

In the following, we list the non-zero elements of the coupling coefficients.

$g_{ii} = 1$	$g_{ij} = 2$	$g'_{ii} = \tau$	$g'_{ij} = 2\tau$
$g_{iji} = g_{ijj} = g_{iju} = 24\tau$	$g_{iii} = g_{iij} = 12\tau$		
$g''_{ij} = 48\tau$	$g''_{ii} = 24\tau$		
$g_{ijii} = 6\epsilon + 12\tau$	$g_{ijij} = 33\epsilon + 48\tau$	$g_{ijjj} = 6\epsilon + 12\tau$	$g_{ijiu} = 3\epsilon + 48\tau$
$g_{ijju} = -3\epsilon + 48\tau$	$g_{ijuu} = 1.5\epsilon + 12\tau$		
$f_{ij} = 2$	$f'_{ij} = 2\tau$		
$f_{iju} = f_{ijj} = f_{iji} = 24\tau$	$f''_{ij} = 48\tau$		
$f_{ijii} = 12\tau$	$f_{ijij} = 48\tau + 33\epsilon$	$f_{ijjj} = 12\tau + 6\epsilon$	$f_{ijiu} = 48\tau + 3\epsilon$
$f_{ijju} = 48\tau - 3\epsilon$	$f_{ijuu} = 12\tau + 1.5\epsilon$		
$h_{ijli}^{(1)} = 15\epsilon + 48\tau$	$h_{ijlj}^{(1)} = 0.75\epsilon + 24\tau$	$h_{ijll}^{(1)} = 0.75\epsilon + 24\tau$	
$h_{ijii}^{(1)} = 21\epsilon + 24\tau$	$h_{ijij}^{(1)} = 9.75\epsilon + 24\tau$	$h_{ijil}^{(1)} = 1.5\epsilon + 48\tau$	
$h_{iiji}^{(1)} = 10.5\epsilon + 12\tau$	$h_{iijj}^{(1)} = 4.875\epsilon + 12\tau$	$h_{iiju}^{(1)} = 0.75\epsilon + 24\tau$	
$h_{ij-li}^{(1)} = 15\epsilon + 48\tau$	$h_{ij-lj}^{(1)} = h_{ij-ll}^{(1)} = 0.75\epsilon + 24\tau$		
$h_{ijl-i}^{(1)} = 15\epsilon + 48\tau$	$h_{ijl-j}^{(1)} = h_{ijl-l}^{(1)} = 0.75\epsilon + 24\tau$		
$h_{ij-l-i}^{(1)} = 15\epsilon + 48\tau$	$h_{ij-l-j}^{(1)} = h_{ij-l-l}^{(1)} = 0.75\epsilon + 24\tau$		
$h_{ijl}^{(1)} = 24\tau$	$h_{iij}^{(1)} = 12\tau$	$h_{ij-l}^{(1)} = h_{ii-j}^{(1)} = 24\tau$	$h_{ij-j}^{(1)} = 12\tau$
$h_{ijl-}^{(1)} = 24\tau$	$h_{iij-}^{(1)} = 12\tau$	$h_{iii-}^{(1)} = 6\tau$	$h_{iji-}^{(1)} = 24\tau$
$h_{ij-l-}^{(1)} = 24\tau$	$h_{ii-j-}^{(1)} = 24\tau$	$h_{ij-i-}^{(1)} = 24\tau$	
$h_{ijli}^{(2)} = 7.5\epsilon + 24\tau$	$h_{iij}^{(2)} = 10.5\epsilon + 12\tau$	$h_{ij-li}^{(2)} = 7.5\epsilon + 24\tau$	$h_{ii-j}^{(2)} = 21\epsilon + 24\tau$
$h_{ijl-}^{(2)} = 15\epsilon + 48\tau$	$h_{iij-}^{(2)} = 8.25\epsilon + 12\tau$	$h_{ijjl-}^{(2)} = 3.75\epsilon + 12\tau$	
$h_{ij-l-i}^{(2)} = 7.5\epsilon + 24\tau$	$h_{ij-l-j}^{(2)} = 7.5\epsilon + 24\tau$	$h_{ij-l-l}^{(2)} = 7.5\epsilon + 24\tau$	
$h_{ij-ll-}^{(2)} = 7.5\epsilon + 24\tau$	$h_{ij-li-}^{(2)} = 15\epsilon + 48\tau$		
$h_{ij-l-i-}^{(2)} = 15\epsilon + 48\tau$	$h_{ij-j-i-}^{(2)} = 8.25\epsilon + 12\tau$	$h_{ij-j-l-}^{(2)} = 3.75\epsilon + 12\tau$	
$h_{ijli}^{(3)} = 0.75\epsilon + 24\tau$	$h_{ijlj}^{(3)} = 15\epsilon + 48\tau$	$h_{ijll}^{(3)} = 0.75\epsilon + 24\tau$	$h_{ijji}^{(3)} = 4.875\epsilon + 12\tau$
$h_{ijjj}^{(3)} = 10.5\epsilon + 12\tau$	$h_{ijjl}^{(3)} = 0.75\epsilon + 24\tau$	$h_{ijl}^{(3)} = 24\tau$	$h_{ijj}^{(3)} = 12\tau$
$h_{iiji}^{(3)} = 12\epsilon + 24\tau$	$h_{iijj}^{(3)} = 9.75\epsilon + 24\tau$	$h_{iijl}^{(3)} = 1.5\epsilon + 48\tau$	$h_{iij}^{(3)} = 24\tau$
$h_{ii-j-i}^{(3)} = 21\epsilon + 24\tau$	$h_{ii-jj}^{(3)} = 9.75\epsilon + 24\tau$	$h_{ii-jl}^{(3)} = 1.5\epsilon + 48\tau$	
$h_{ij-j-i}^{(3)} = 9.75\epsilon + 24\tau$	$h_{ij-jj}^{(3)} = 21\epsilon + 24\tau$	$h_{ij-jl}^{(3)} = 15\epsilon + 48\tau$	
$h_{ij-li}^{(3)} = 0.75\epsilon + 24\tau$	$h_{ij-lj}^{(3)} = 0.75\epsilon + 24\tau$	$h_{ij-ll}^{(3)} = 15\epsilon + 48\tau$	

$$\begin{array}{llll}
h_{ii-j}^{(3)} = 24\tau & h_{ij-j}^{(3)} = 24\tau & h_{ij-l}^{(3)} = 24\tau & \\
h_{iii-i}^{(3)} = 16\epsilon + 8\tau & h_{iii-j}^{(3)} = 12\epsilon + 24\tau & h_{iji-i}^{(3)} = 4\epsilon + 8\tau & h_{iji-j}^{(3)} = 16.5\epsilon + 24\tau \\
h_{iji-l}^{(3)} = 1.5\epsilon + 24\tau & h_{iij-i}^{(3)} = 21\epsilon + 24\tau & h_{iij-j}^{(3)} = 9.75\epsilon + 24\tau & h_{iij-l}^{(3)} = 1.5\epsilon + 48\tau \\
h_{ijj-i}^{(3)} = 9.75\epsilon + 24\tau & h_{ijj-j}^{(3)} = 21\epsilon + 24\tau & h_{ijj-l}^{(3)} = 1.5\epsilon + 48\tau & h_{ijl-i}^{(3)} = 0.75\epsilon + 24\tau \\
h_{ijl-j}^{(3)} = 15\epsilon + 48\tau & h_{ijl-l}^{(3)} = 0.75\epsilon + 24\tau & h_{iii-}^{(3)} = 12\tau & h_{iji-}^{(3)} = 12\tau \\
h_{iij-}^{(3)} = 24\tau & h_{iij-}^{(3)} = 24\tau & h_{ijl-}^{(3)} = 24\tau & \\
h_{ii-i-i}^{(3)} = 8\epsilon + 4\tau & h_{ii-i-j}^{(3)} = 6\epsilon + 12\tau & h_{ii-j-i}^{(3)} = 21\epsilon + 24\tau & h_{ii-j-j}^{(3)} = 9.75\epsilon + 24\tau \\
h_{ii-j-l}^{(3)} = 1.5\epsilon + 48\tau & h_{ij-i-i}^{(3)} = 4\epsilon + 8\tau & h_{ij-i-j}^{(3)} = 16.5\epsilon + 24\tau & h_{ij-i-l}^{(3)} = 1.5\epsilon + 24\tau \\
h_{ij-j-i}^{(3)} = 4.875\epsilon + 24\tau & h_{ij-j-j}^{(3)} = 10.5\epsilon + 12\tau & h_{ij-j-l}^{(3)} = 0.75\epsilon + 24\tau & h_{ij-l-i}^{(3)} = 0.75\epsilon + 24\tau \\
h_{ij-l-j}^{(3)} = 15\epsilon + 48\tau & h_{ij-l-l}^{(3)} = 0.75\epsilon + 24\tau & h_{ii-i-}^{(3)} = 6\tau & h_{ij-j-}^{(3)} = 12\tau \\
h_{ii-j-}^{(3)} = 24\tau & h_{ij-l-}^{(3)} = 24\tau & h_{ii-i-}^{(3)} = 12\tau & \\
h_{iji}^{(4)} = 12\tau & h_{ijl}^{(4)} = 24\tau & h_{ii-i}^{(4)} = h_{ij-i}^{(4)} = 24\tau & h_{ii-j}^{(4)} = 48\tau \\
h_{ijj-j}^{(4)} = h_{ij-l}^{(4)} = 48\tau & h_{iji-}^{(4)} = h_{ijj-}^{(4)} = h_{ijl-}^{(4)} = 48\tau & h_{ij-i-}^{(4)} = h_{ij-l-}^{(4)} = 24\tau & \\
h_{ii}^{(5)} = 0.375\epsilon + 12\tau & \tilde{h}_{ii}^{(5)} = 2h_{ii}^{(5)} & h_{ii+1}^{(5)} = 7.5\epsilon + 48\tau & \tilde{h}_{ii+1}^{(5)} = 2h_{ii+1}^{(5)} \\
h_{ii+2}^{(5)} = 0.75\epsilon + 24\tau & \tilde{h}_{ii+2}^{(5)} = 2h_{ii+2}^{(5)} & h_{ii-}^{(5)} = 1.5\epsilon + 48\tau & \tilde{h}_{ii-}^{(5)} = 1/2h_{ii-}^{(5)} \\
h_{i(i+1)-}^{(5)} = 15\epsilon + 48\tau & \tilde{h}_{i(i+1)-}^{(5)} = 1/2h_{i(i+1)-}^{(5)} & & \\
h^{(5)} = 8\tau & & & \\
h_{ijj}^{(6)} = h_{iju}^{(6)} = 24\tau & h_{ii}^{(6)} = 8\tau & h_{ii-i}^{(6)} = h_{ij-i}^{(6)} = 48\tau & h_{ii-j}^{(6)} = h_{ij-j}^{(6)} = 24\tau \\
h_{iii-}^{(6)} = h_{iij-}^{(6)} = 24\tau & h_{iji-}^{(6)} = h_{ijj-}^{(6)} = h_{iju-}^{(6)} = 48\tau & & \\
h_{ij-j-}^{(6)} = h_{ii-i-}^{(6)} = 48\tau & h_{ij-u-}^{(6)} = h_{ii-j-}^{(6)} = 24\tau & h_{ij-i-}^{(6)} = 48\tau & \\
h_{ijj}^{(7)} = 12\tau & h_{ii}^{(7)} = h_{ijl}^{(7)} = 24\tau & h_{ii-j}^{(7)} = h_{ij-j}^{(7)} = h_{ij-l}^{(7)} = 24\tau & \\
h_{iii-}^{(7)} = h_{iij-}^{(7)} = h_{ijl-}^{(7)} = 48\tau & h_{ijj-}^{(7)} = h_{ijl-}^{(7)} = 48\tau & & \\
h_{ii-j-}^{(7)} = h_{ij-i-}^{(7)} = 48\tau & h_{ii-i-}^{(7)} = h_{ij-j-}^{(7)} = 24\tau & h_{ij-l-}^{(7)} = 48\tau & \\
h_{ii}^{(8)} = h_{ij}^{(8)} = 12\tau & h_{ii-}^{(8)} = h_{ij-}^{(8)} = 12\tau & & \\
h_{ij}^{(9)} = h_{ii}^{(9)} = 8\tau & & & 
\end{array}$$

Note, that coupling coefficients involving the constant shift  $\delta$  only occur in case of the product-type inter-map coupling energy.

## Text S3: Supporting Information for

### Coordinated optimization of visual cortical maps

#### (I) Symmetry-based analysis

#### Stability matrix

Here, we state the stability matrices  $M$  used in the linear stability analysis of the coupled amplitude equations. The stability matrix is defined by

$$\partial_t \begin{pmatrix} \text{Re}A_i \\ \text{Re}A_{i-} \\ \text{Im}A_i \\ \text{Im}A_{i-} \end{pmatrix} = M \begin{pmatrix} \text{Re}A_i \\ \text{Re}A_{i-} \\ \text{Im}A_i \\ \text{Im}A_{i-} \end{pmatrix} = \begin{pmatrix} M1 & M2 \\ M3 & M4 \end{pmatrix} \begin{pmatrix} \text{Re}A_i \\ \text{Re}A_{i-} \\ \text{Im}A_i \\ \text{Im}A_{i-} \end{pmatrix}$$

for the uniform solutions Eq. (60). We separate the uncoupled contributions from the inter-map coupling contributions i.e.  $M1 = M1^{(u)} + M1^{(\alpha)}$ . The uncoupled contributions are given by

$$M1^{(u)} = r_z \mathbf{I} + \mathcal{A}^2 \begin{pmatrix} -13 & -3 & 3 & -2c & -3c - \sqrt{3}s & 3c - \sqrt{3}s \\ -3 & -23/2 & 0 & -3c - \sqrt{3}s & -2c & 0 \\ 3 & 0 & -23/2 & 3c - \sqrt{3}s & 0 & -2c \\ -2c & -3c - \sqrt{3}s & 3c - \sqrt{3}s & -12 - \cos 2\Delta & -2 - 2u & 2 + 2v \\ -3d + \sqrt{3}s & -2d & 0 & -2 - 2u & -12 - \cos(2\Delta + 10\pi/3) & -4d^2 \\ 3c - \sqrt{3}s & 0 & -2c & -2 - 2v & -4s^2 & -12 + u \end{pmatrix}$$

$$M2^{(u)} = \mathcal{A}^2 \begin{pmatrix} 0 & \sqrt{3} & \sqrt{3} & 2s & 2\cos(\Delta - \pi/6) & 2\cos(\Delta + \pi/6) \\ \sqrt{3} & \sqrt{3}/2 & 0 & 2\cos(\Delta - \pi/6) & 2s & 4s \\ \sqrt{3} & 0 & -\sqrt{3}/2 & 2\cos(\Delta + \pi/6) & 4s & 2s \\ -2s & \sqrt{3}d - 3s & \sqrt{3}d + 3s & -\sin 2\Delta & 2x & 2y \\ \sqrt{3}d - 2s & -2d & 0 & 2x & y & 2\sin 2\Delta \\ \sqrt{3}d + 3s & 0 & -2s & 2y & 2\sin 2\Delta & -x \end{pmatrix}$$

$$M3^{(u)} = \mathcal{A}^2 \begin{pmatrix} 0 & \sqrt{3} & \sqrt{3} & 2s & 2\cos(\Delta - \pi/6) & 2\cos(\Delta + \pi/6) \\ \sqrt{3} & \sqrt{3}/2 & 0 & 2\cos(\Delta - \pi/6) & 2s & 4s \\ \sqrt{3} & 0 & -\sqrt{3}/2 & 2\cos(\Delta + \pi/6) & 4s & 2s \\ -2s & \sqrt{3}c - 3s & \sqrt{3}c + 3s & -\sin 2\Delta & 2x & 2y \\ \sqrt{3}d - 3s & -2s & 0 & 2x & y & 2\sin 2\Delta \\ \sqrt{3}c + 3s & 0 & -2s & 2y & 2\sin 2\Delta & -x \end{pmatrix}$$

$$M4^{(u)} = r_z \mathbf{I} + \mathcal{A}^2 \begin{pmatrix} -11 & -1 & 1 & -2c & 2w & 2z \\ -1 & -25/2 & -4 & 2w & -2c & -4c \\ 1 & -4 & -25/2 & 2z & -4c & -2c \\ -2c & 2w & 2z & -12 + \cos 2\Delta & 2(u-1) & 2(1+v) \\ 2w & -2c & -4c & 2(u-1) & -12 + \cos(2\Delta + 10\pi/3) & -4c^2 \\ 2z & -4c & -2c & 2(v+1) & -4c^2 & -12 + \cos(2\Delta + 8\pi/3) \end{pmatrix}$$

where  $\mathbf{I}$  denotes the  $6 \times 6$  identity matrix and  $s = \sin \Delta$ ,  $c = \cos \Delta$ ,  $u = \sin(2\Delta + \pi/6)$ ,  $v = \sin(2\Delta - \pi/6)$ ,  $x = \cos(2\Delta + \pi/6)$ ,  $y = \cos(2\Delta - \pi/6)$ ,  $w = \sin(\Delta - \pi/6)$ ,  $z = \sin(\Delta + \pi/6)$ .

The coupling part in case of the low order product-type inter-map coupling energy is given by

$$M1^{(\alpha)} = \alpha \begin{pmatrix} -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 & -2\mathcal{B}^2 & -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & -2\mathcal{B}(\mathcal{B} - \delta) \\ 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) \\ -2\mathcal{B}^2 & 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}(-\mathcal{B} + \delta) & 2\mathcal{B}(\mathcal{B} - \delta) & -\mathcal{B}^2 \\ -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & -2\mathcal{B}(\mathcal{B} - \delta) & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 & -2\mathcal{B}^2 \\ 2\mathcal{B}^2(\mathcal{B} - \delta) & -\mathcal{B}^2 & 2\mathcal{B}(\mathcal{B} - \delta) & 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) & 2\mathcal{B}^2 \\ 2\mathcal{B}(-\mathcal{B} + \delta) & 2\mathcal{B}(\mathcal{B} - \delta) & -\mathcal{B}^2 & -2\mathcal{B}^2 & 2\mathcal{B}^2 & -(6\mathcal{B}^2 + \delta^2) \end{pmatrix}$$

$$M4^{(\alpha)} = M1^{(\alpha)}, M2^{(\alpha)} = M3^{(\alpha)} = 0.$$

The coupling part in case of the low order gradient-type inter-map coupling energy is given by

$$M1^{(\beta)} = \beta \mathcal{B}^2 \begin{pmatrix} 3 & -5/4 & 5/4 & 1 & -5/4 & 5/4 \\ -5/4 & 3 & -5/4 & -5/4 & 1 & -5/4 \\ 5/4 & -5/4 & 3 & 5/4 & -5/4 & 1 \\ 1 & -5/4 & 5/4 & 3 & -5/4 & 5/4 \\ -5/4 & 1 & -5/4 & -5/4 & 3 & -5/4 \\ 5/4 & -5/4 & 1 & 5/4 & -5/4 & 3 \end{pmatrix}$$

$$M4^{(\beta)} = M1^{(\beta)}, M2^{(\beta)} = M3^{(\beta)} = 0.$$

The stationary amplitudes  $\mathcal{A}$  are given in Eq. (63), Eq. (68), Eq. (81), and Eq. (83). The stationary amplitudes  $\mathcal{B}$  and the constant  $\delta$  are given by Eq. (94) and Eq. (116), respectively.

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- 16 **Contra-center pinwheel crystals. **A,B**** OP map, superimposed are the OD borders (gray), 90% ipsilateral eye dominance (black), and 90% contralateral eye dominance (white),  $r_o = 0.2, \gamma = 3\gamma^*$ . **A**  $\Delta = \arccos(5/13)$ , **B**  $\Delta = -\arccos(5/13)$ . **C** Distribution of orientation preference. **D** OP map with superimposed OD map for three different values ( $\gamma = \gamma^*, \gamma = (\gamma_4^* - \gamma^*)/2 + \gamma^*, \gamma = \gamma_4^*$ ) of the OD bias. **E** Selectivity  $|z(\mathbf{x})|$ , white: high selectivity, black: low selectivity. **F** Distribution of intersection angles. . . . . 70
- 17 **Inter-map coupling strength dependent pinwheel positions.** OD map, superimposed pinwheel positions (points) for different inter-map coupling strengths,  $\gamma/\gamma^* = 3$ . Numbers label pinwheels within the unit cell (dashed lines). Blue (green, red) points: pinwheel positions for rPWC (distorted rPWC, hPWC) solutions. **A**  $U = \epsilon |\nabla \mathbf{z} \cdot \nabla \mathbf{o}|^4$ , using stationary amplitudes from Fig. (13)(a). Positions of distorted rPWCs move continuously (pinwheel 1,3,4). **B**  $U = \tau |\mathbf{z}|^4 |\mathbf{o}|^4$ , using stationary amplitudes from Fig. (10)**D**. Positions of rPWCs move continuously (pinwheel 5,6). . . . . 71